

Differentiable Programming for High Energy Physics

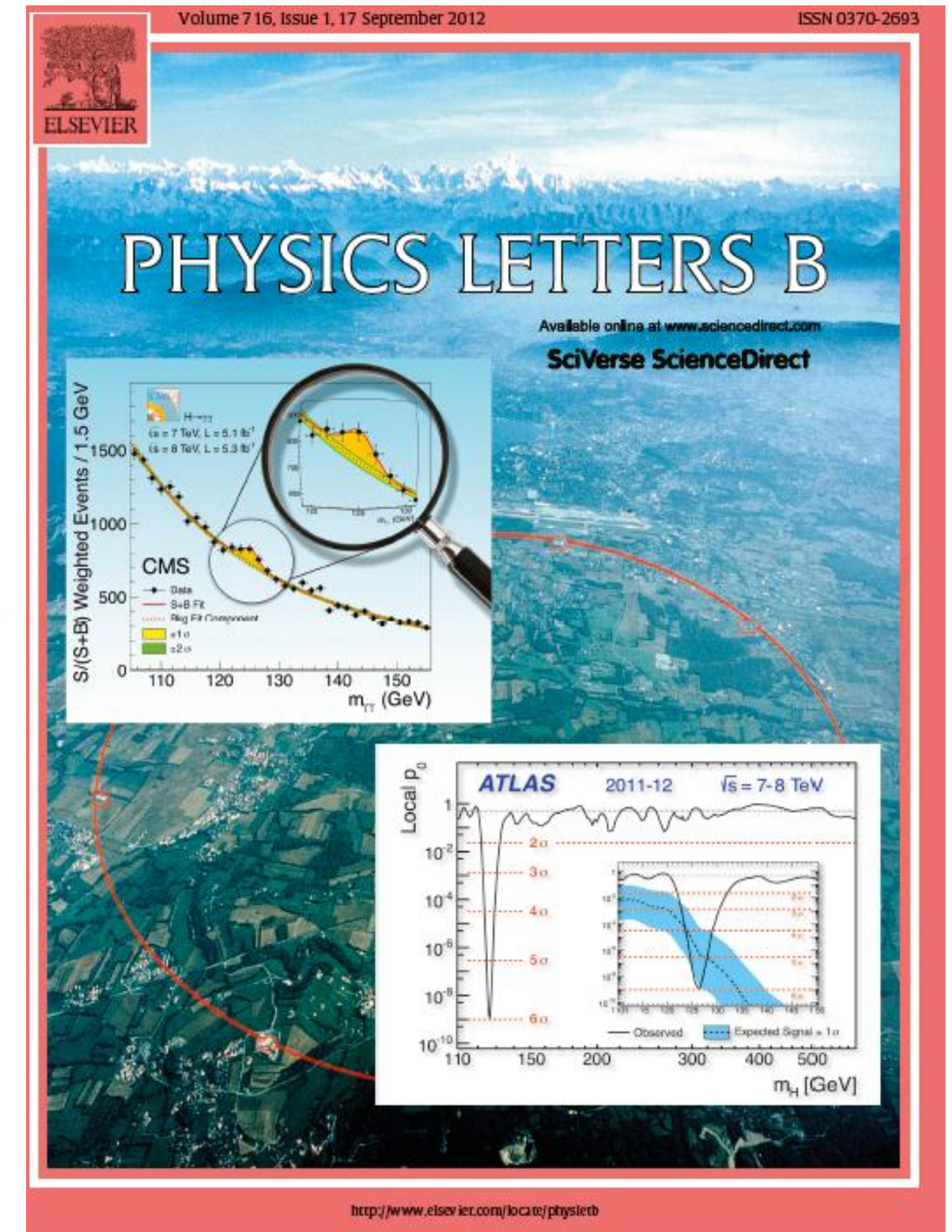
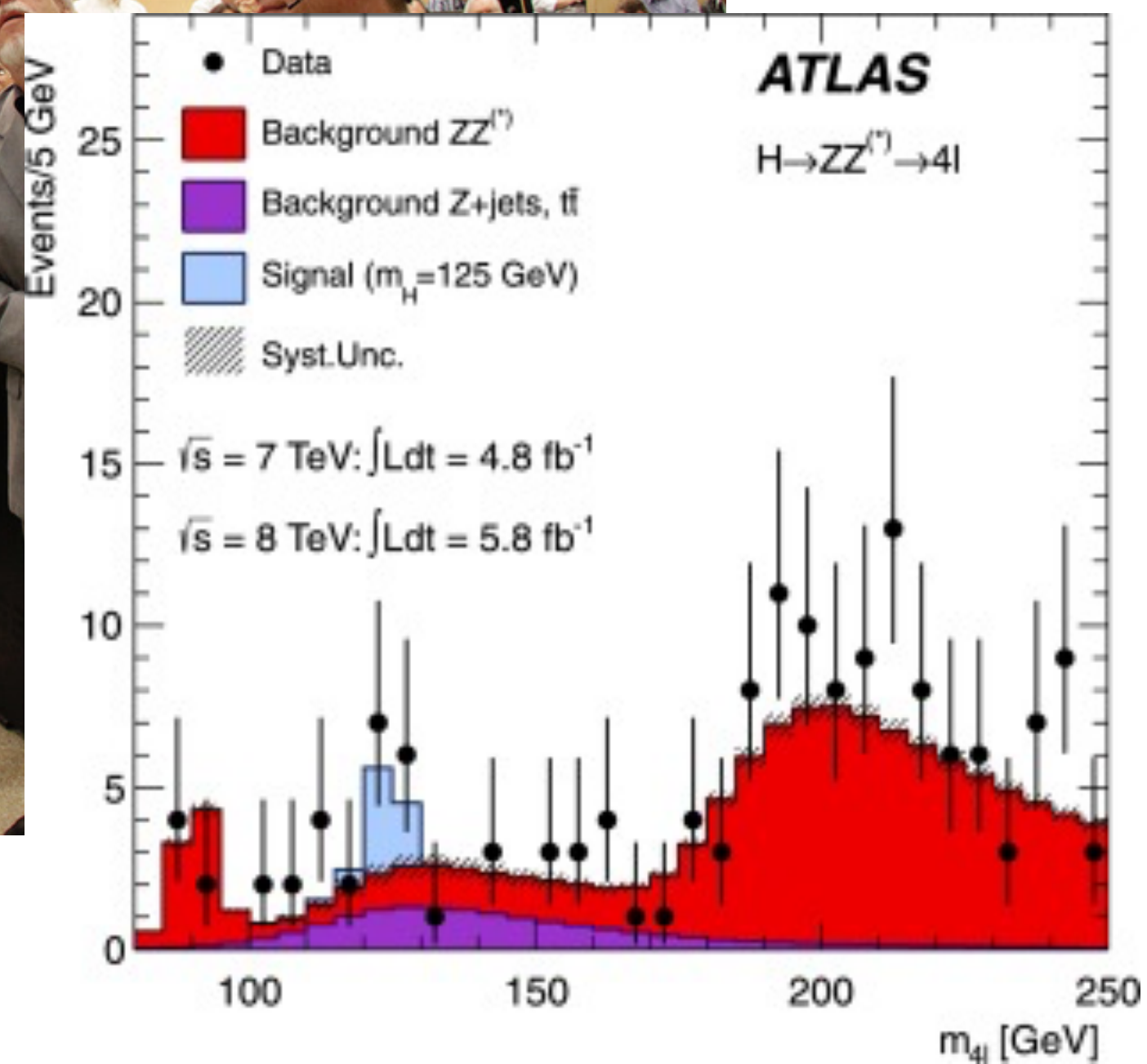
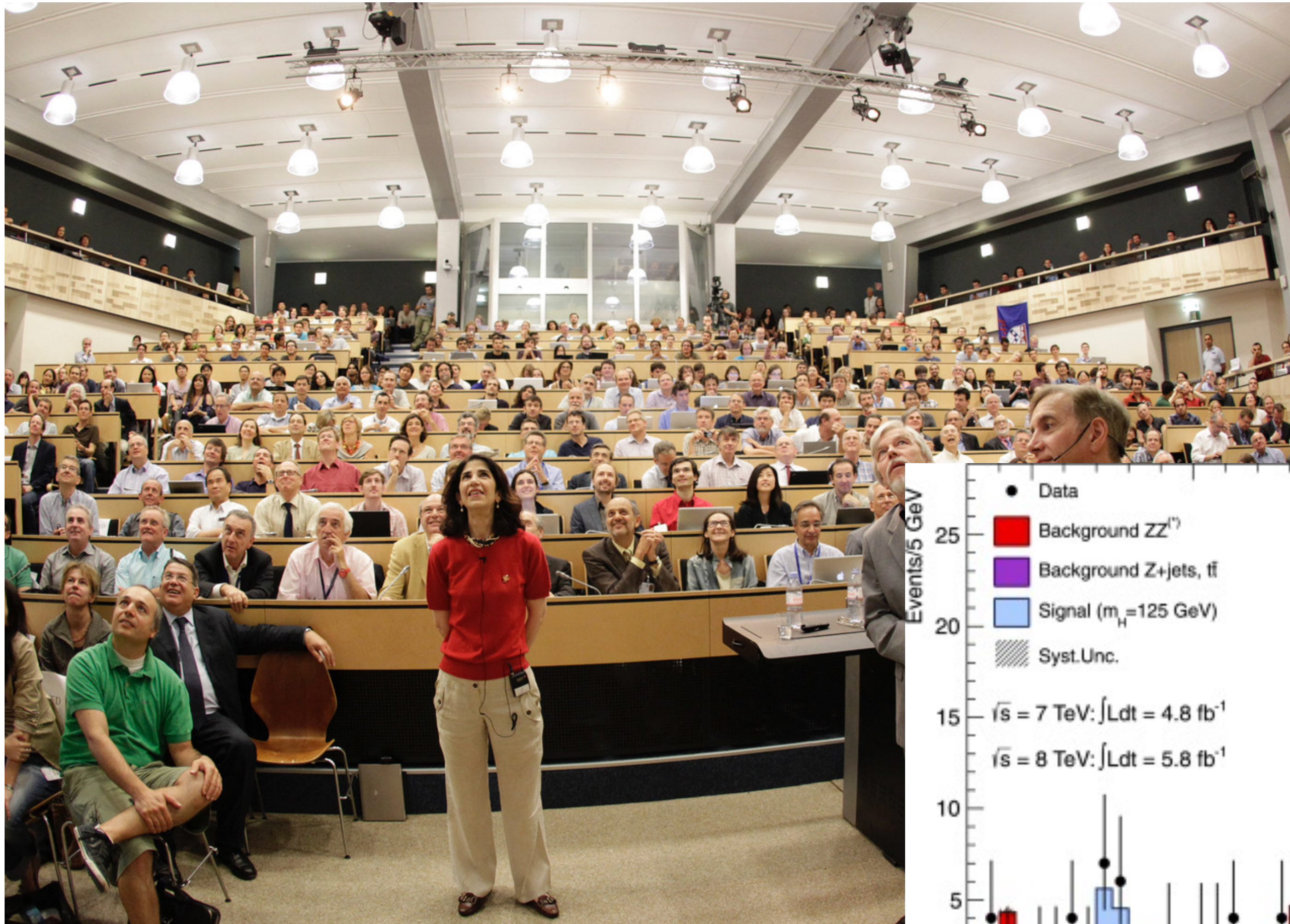
QCHS Stavanger

Lukas Heinrich

Technische
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July 2012 in Physics



Inference in HNEP is fundamentally challenging

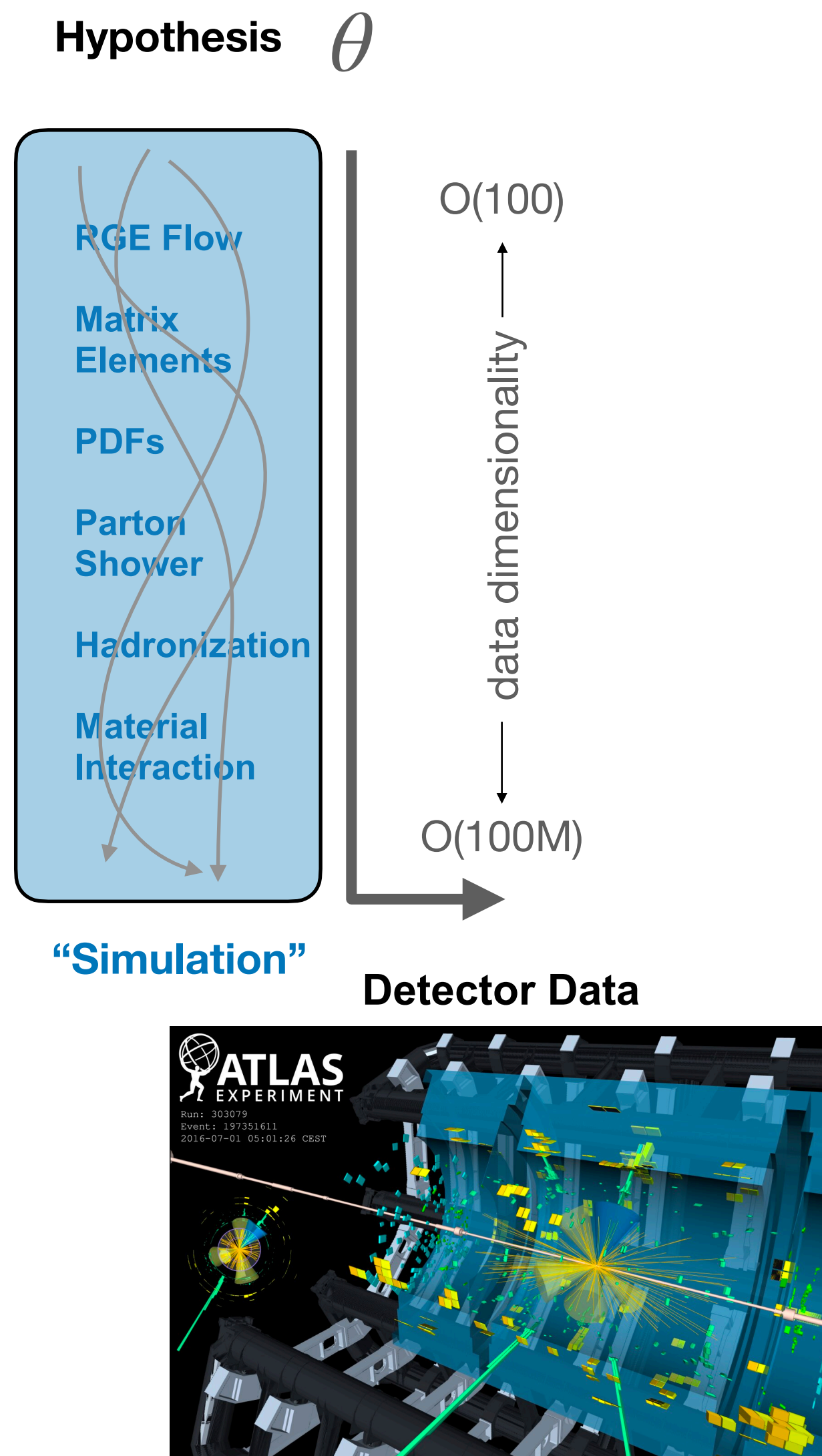
While we understand very well how our data is generated...

$$p(x, z|\theta) = p(x|z_d)p(z_d|z_h)p(z_h|z_p)p(z_p|\theta)$$

...we can't observe the intermediate states z :

$$p(x|\theta) = \int dz \, p(x, z|\theta)$$

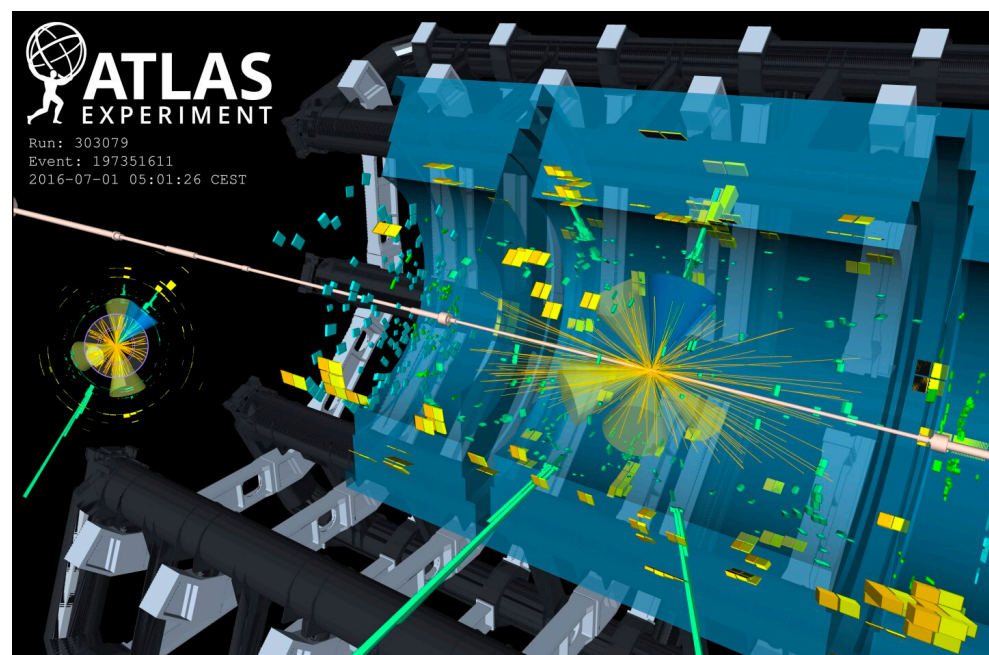
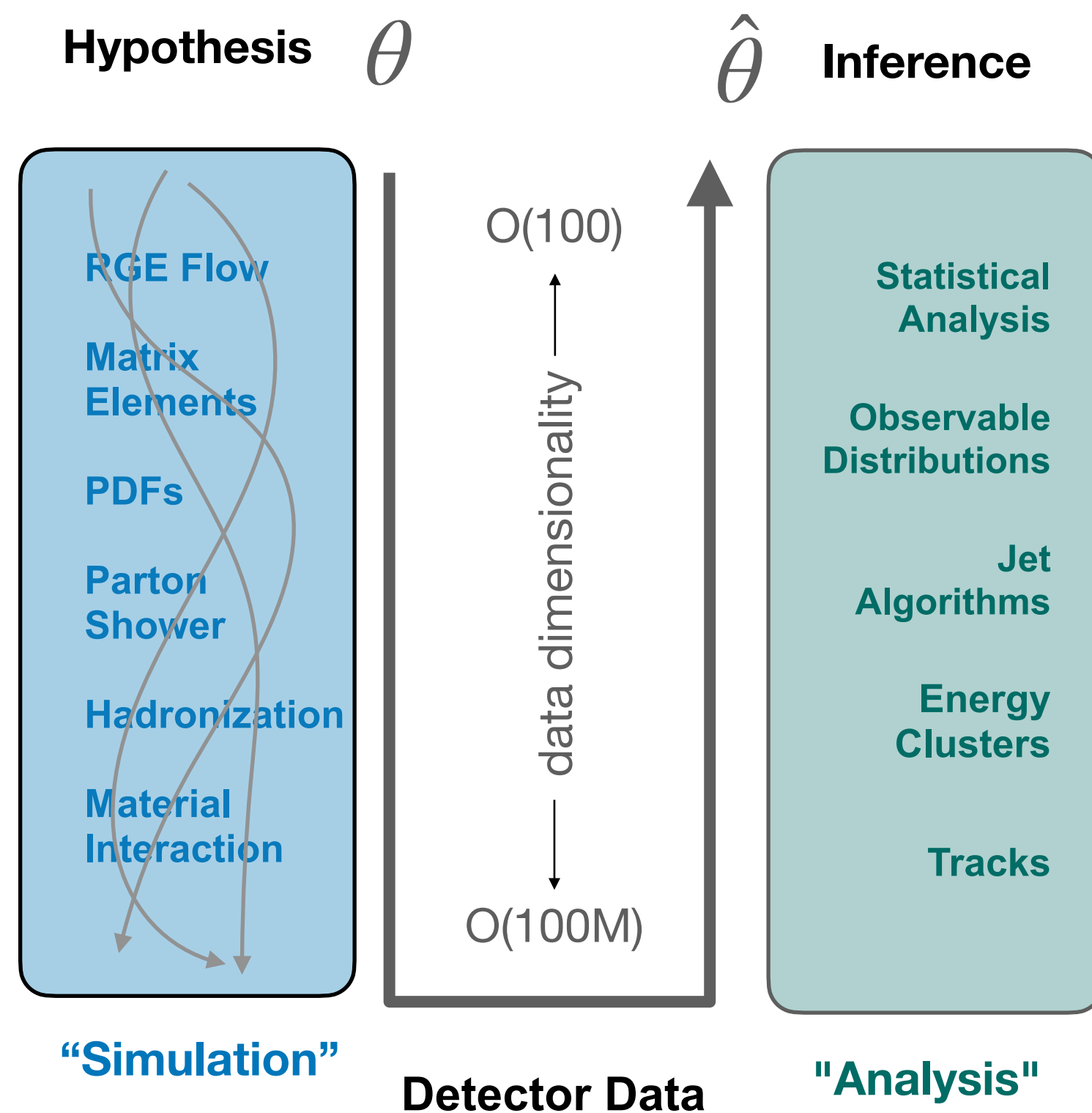
hopeless integral over millions of dim. well-understood physics processes



makes text-book data analysis impossible...

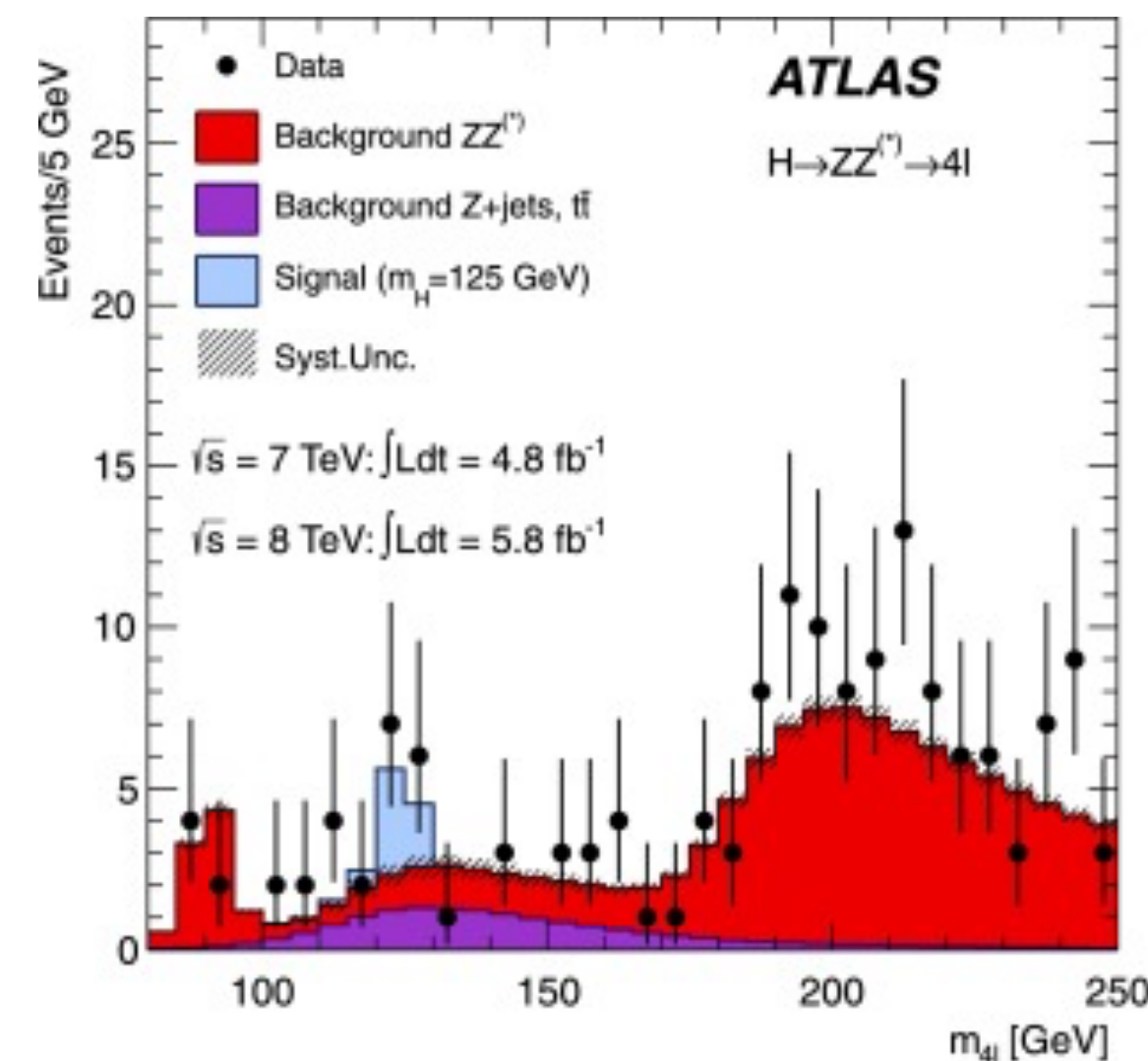
$$p(\theta|x) = \frac{p(x|\theta)}{p(x)}p(\theta)$$

Inference in HNEP is fundamentally challenging



But we can generate sample data: $x \sim p(x | \theta)$ by encoding our physics into **(very costly) simulators**

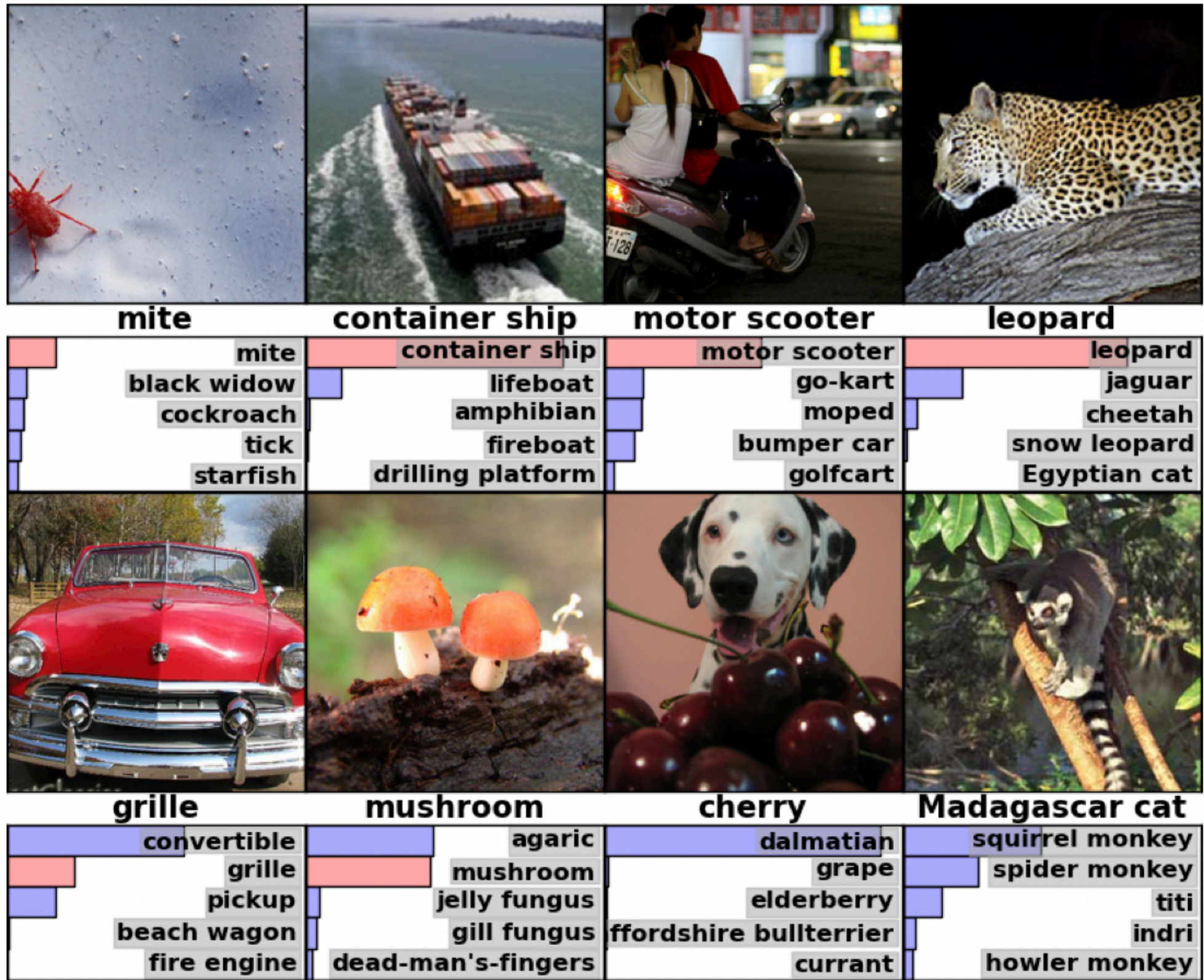
Common Strategy: try to find a good low-dimensional observables: $x \rightarrow y_x = f(x)$



estimate $p(y_x | \theta)$ from samples for inference i.e. $p(\theta | y_x)$

This is the core of **"reconstruction"** and **"analysis"**

July 2012 in Computer Science



ImageNet Classification with Deep Convolutional Neural Networks

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Abstract

We trained a large, deep convolutional neural network to classify the 1.2 million high-resolution images in the ImageNet LSVRC-2010 contest into the 1000 different classes. On the test data, we achieved top-1 and top-5 error rates of 37.5% and 17.0% which is considerably better than the previous state-of-the-art. The neural network, which has 60 million parameters and 650,000 neurons, consists of five convolutional layers, some of which are followed by max-pooling layers, and three fully-connected layers with a final 1000-way softmax. To make training faster, we used non-saturating neurons and a very efficient GPU implementation of the convolution operation. To reduce overfitting in the fully-connected layers we employed a recently-developed regularization method called “dropout” that proved to be very effective. We also entered a variant of this model in the ILSVRC-2012 competition and achieved a winning top-5 test error rate of 15.3%, compared to 26.2% achieved by the second-best entry.

Breakthrough of neural-network based “Deep Learning”

Impressive Progress in the last Decade

*“A painting by Grant Wood of
an astronaut couple,
american gothic style”*

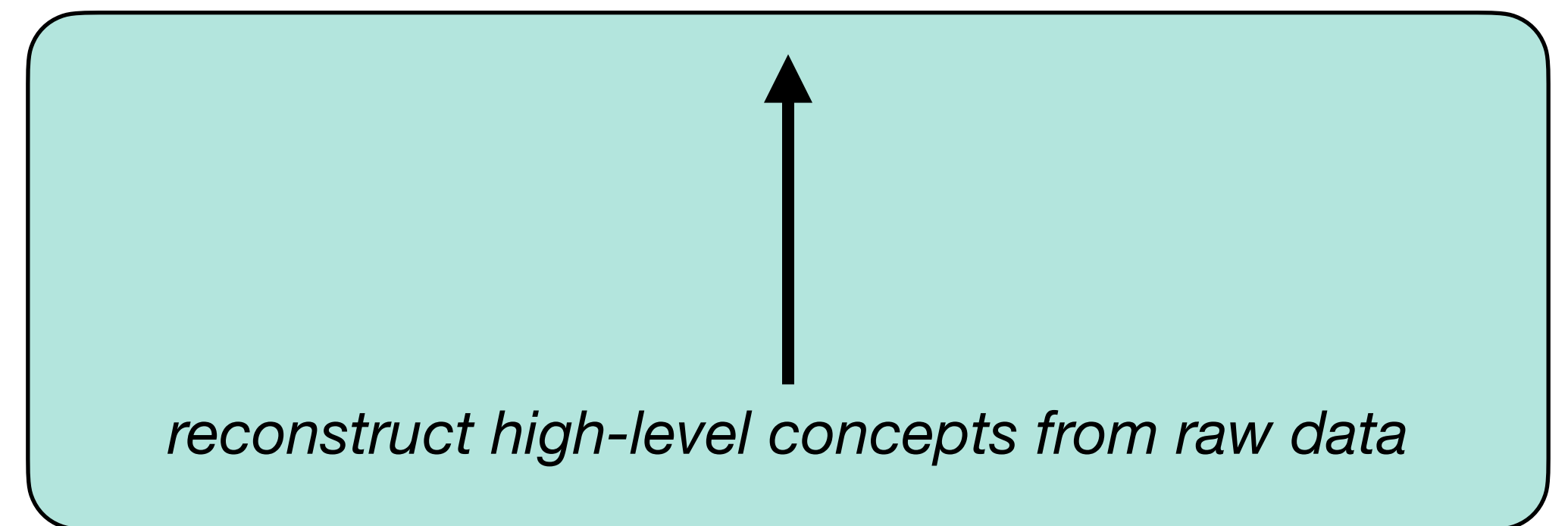
Language

*“This is a picture of Barack Obama”
“His foot is positioned on the right side of the scale”
“The scale shows a higher weight”*

generate low-level data from high-level concepts



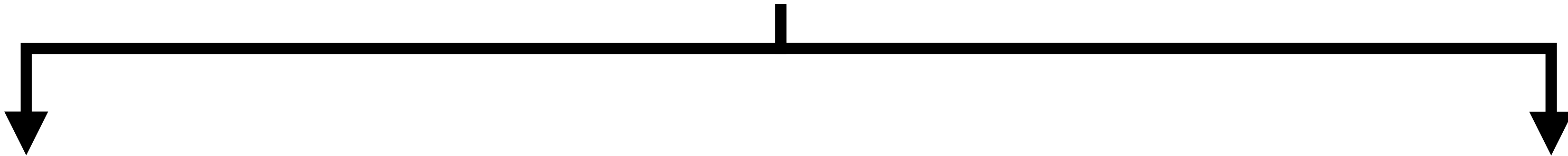
Pixels



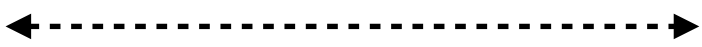
reconstruct high-level concepts from raw data



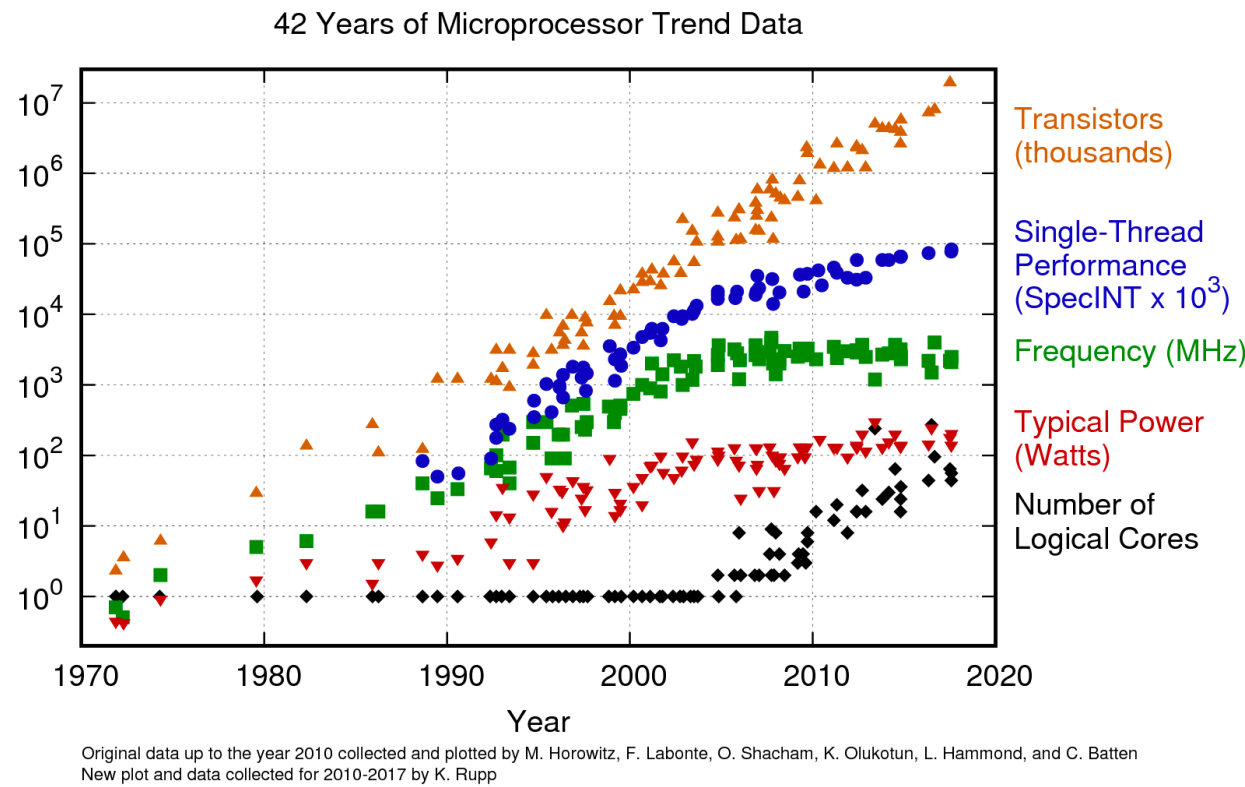
ML Opportunities in Fundamental Physics



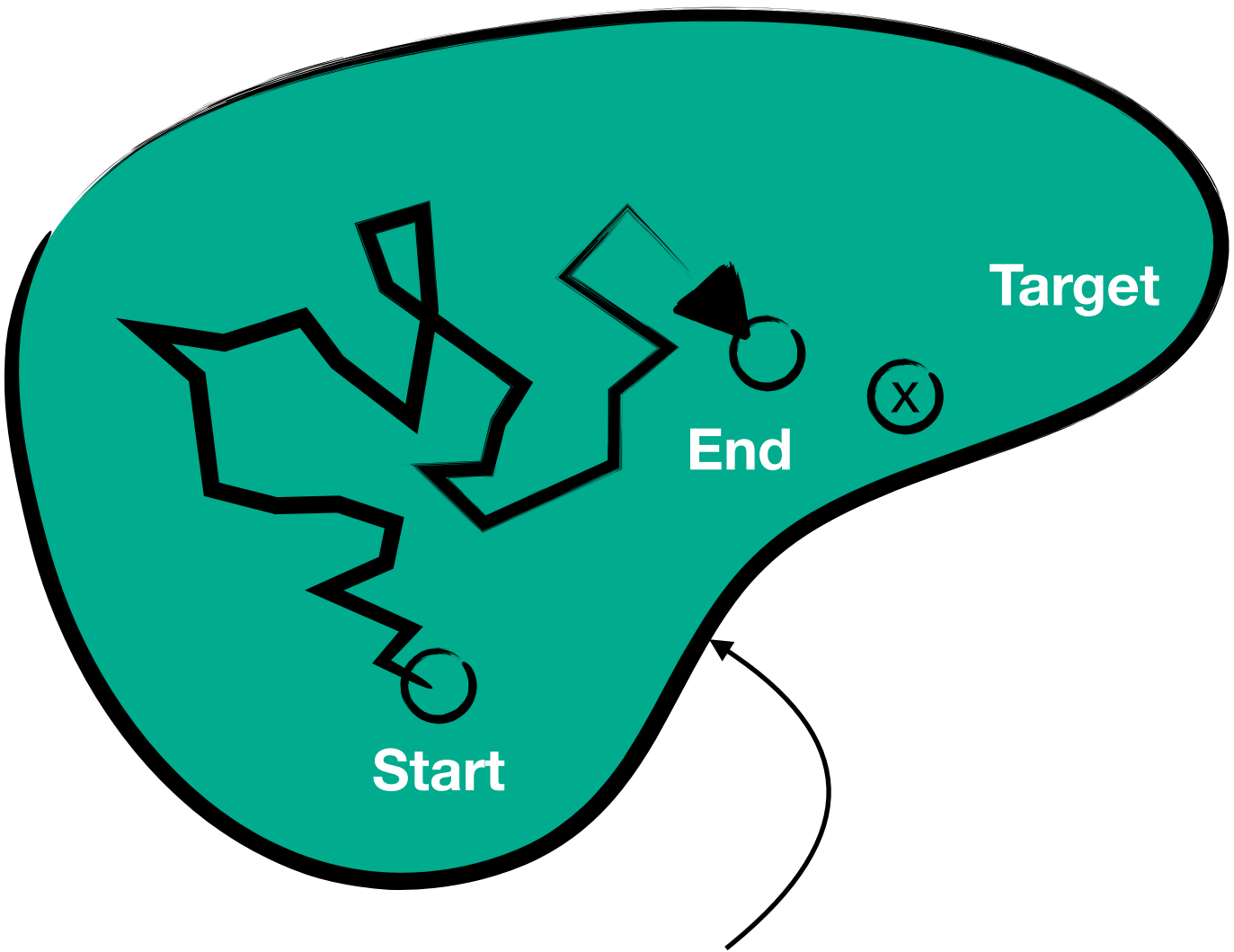
Acceleration of Computation
(e.g. sometimes by searching for a good approximation)



Search for new (better) Algorithms
(e.g. targeted search based on samples)



*simulation side: the physics is fixed:
nothing to search for → speed up simulation*

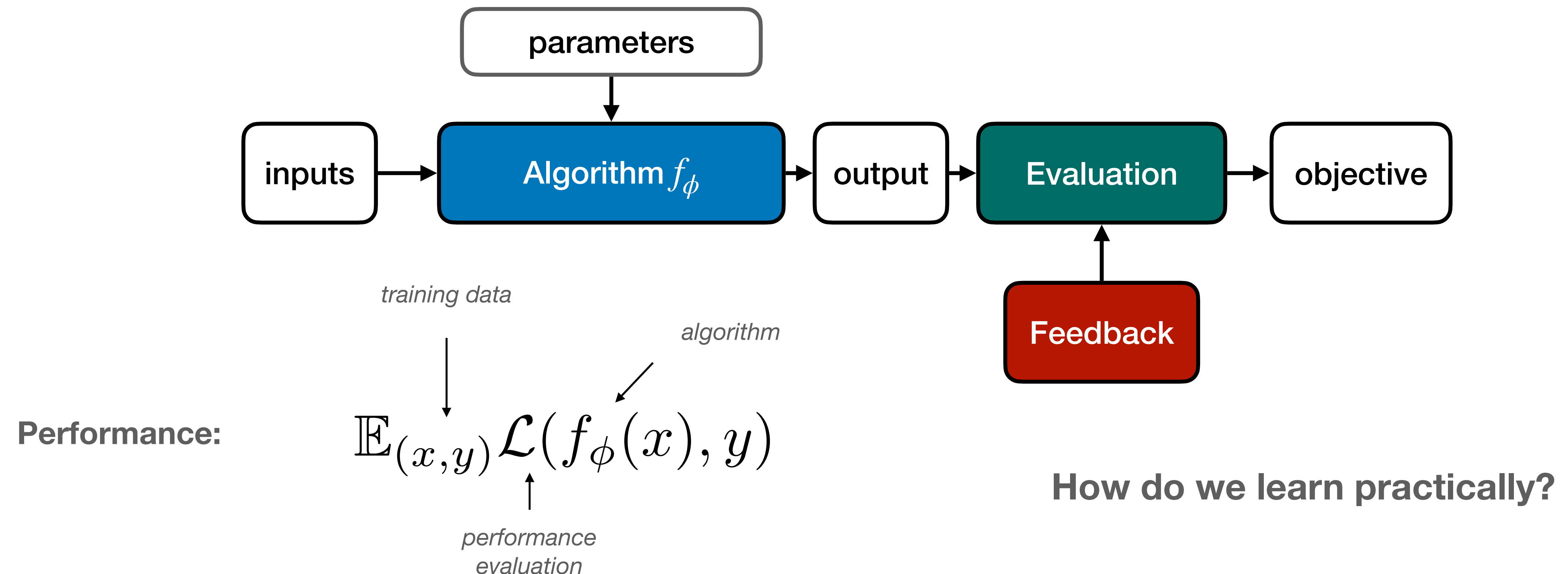


space of possible algorithms

*up to us to find best observables
→ search for best reconstruction*

Lightning Summary of ML

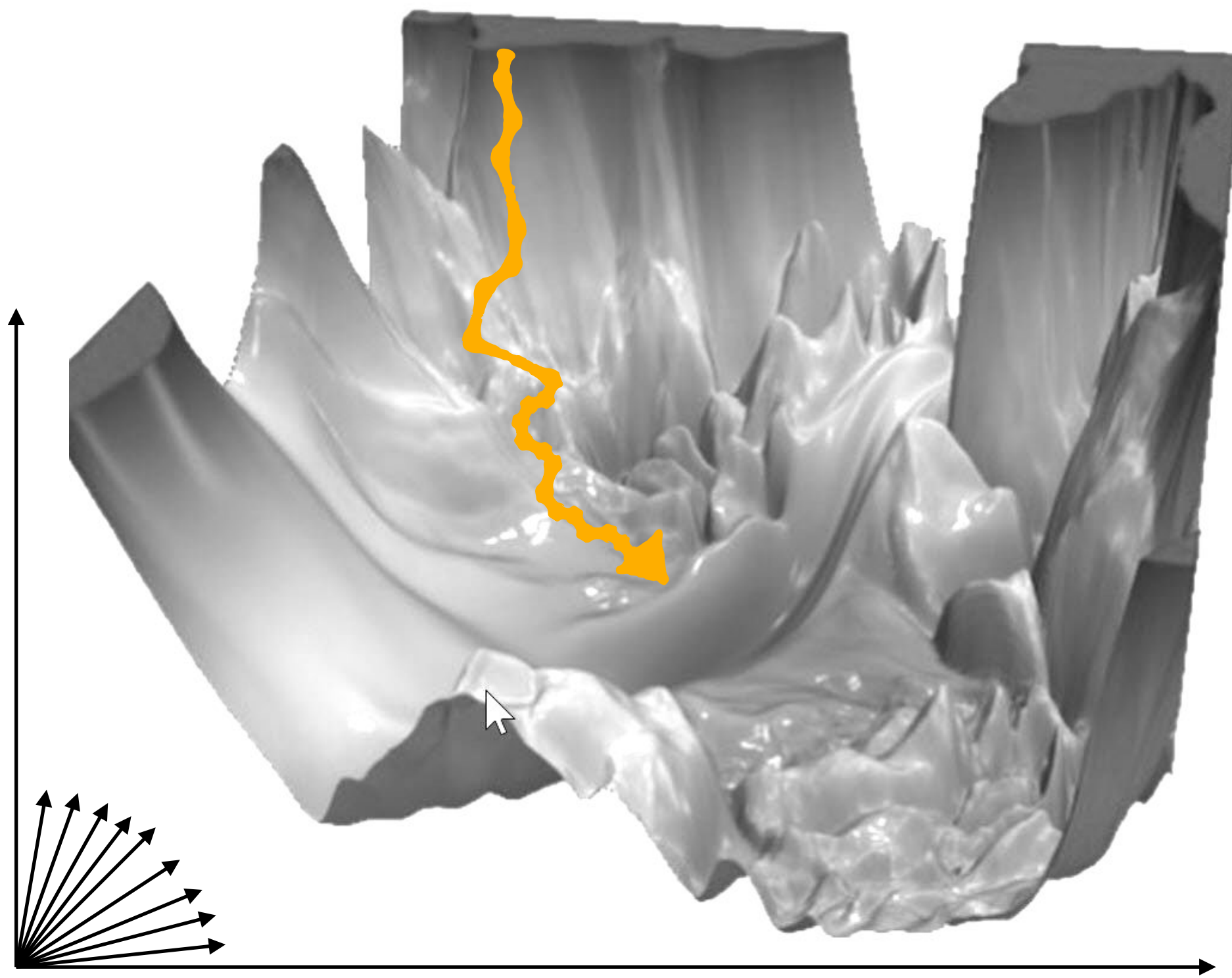
Learning: data-driven search for a function with optimal performance in a huge
Space of Algorithms



Lightning Summary of ML

search space should be large enough → trillions of parameters! How could this work?

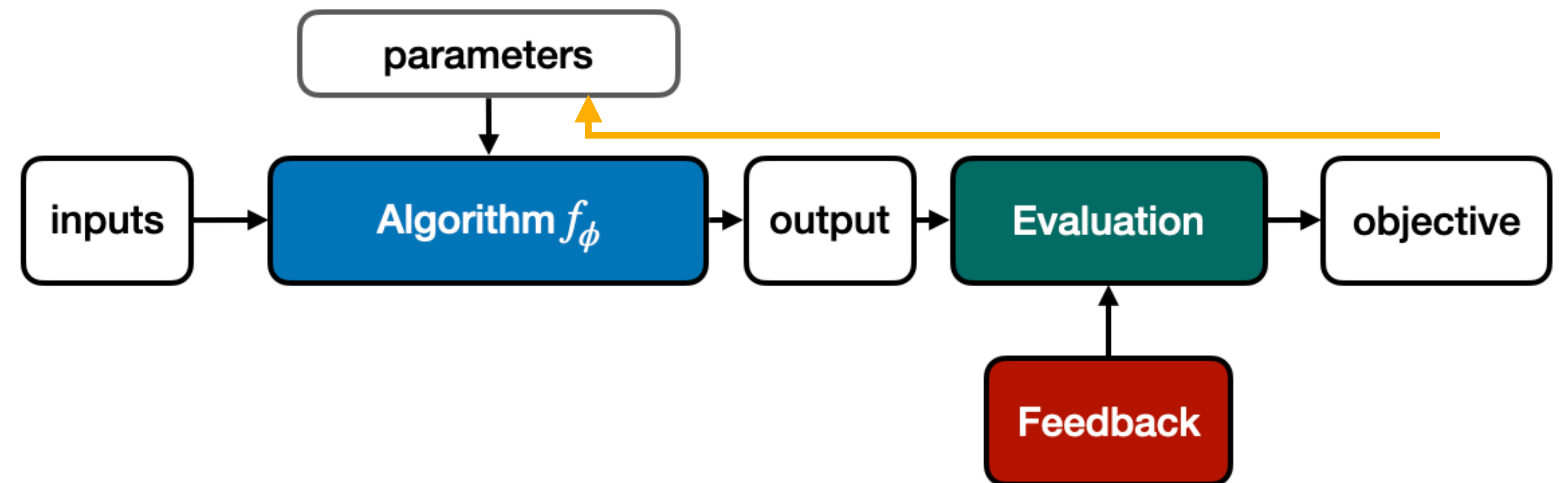
→ gradient-based optimization (“good sense of direction”)



ResNet-56-meshnet

To deal with hyper-planes in a 14-dimensional space, visualize a 3D space and say 'fourteen' to yourself very loudly. -Hinton (DL pioneer)

$$\frac{\partial L}{\partial \phi} = \frac{\partial L}{\partial f} \frac{\partial f}{\partial \phi}$$

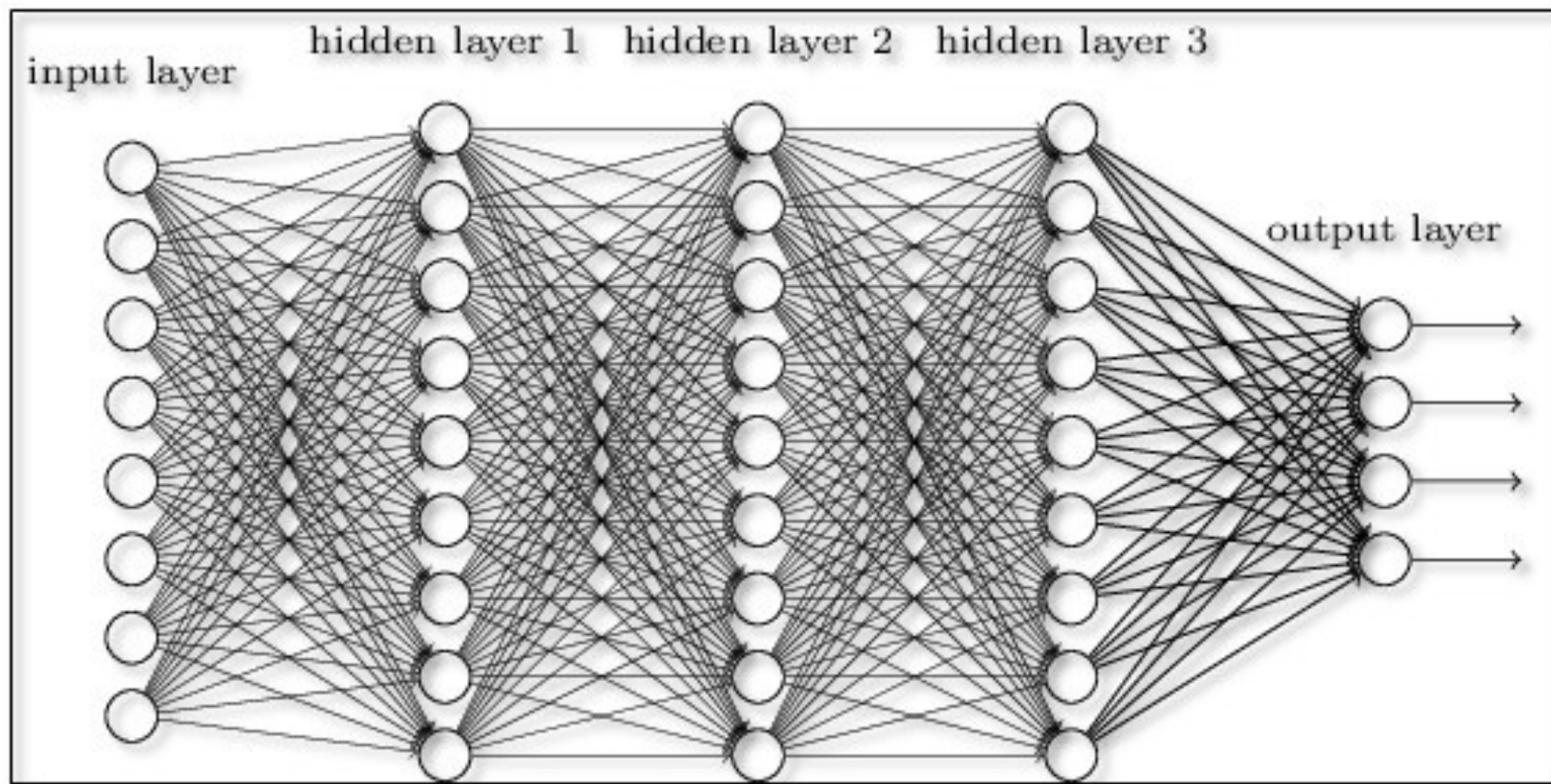


→ requires **algorithms** and **evaluation** to be differentiable

Finding the right Search Space

At first

fixed but generic, large and **easily differentiable** function class:



*manual derivation of efficient
gradient computation*

Increasingly

domain-specific, arbitrary computation
encoding e.g. symmetries, dynamics, ...

$$R_g y = f(R_g x) \quad \dot{x} = f(x)$$



[M. Bronstein]

?

Differentiable Programming

The key: programming languages whose programs are **inherently differentiable**

- ***avoid overhead*** of computer algebra (symbolic differentiation)
- ***exact gradients*** instead of numerical approx. (unstable in high dimensions)

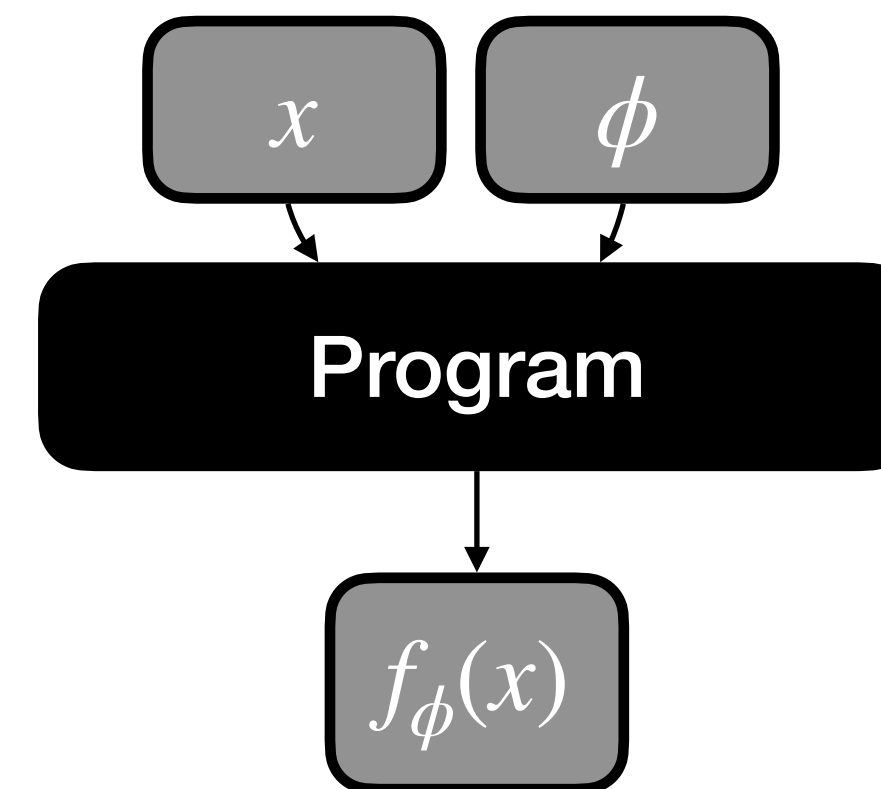
```
import jax
import jax.numpy as jnp

def func(x):
    y = x
    for i in range(4):
        y += x[0]**2 + jnp.sin(x[1]) + jnp.exp(-x[2])
    y = y.sum()
    return y
```

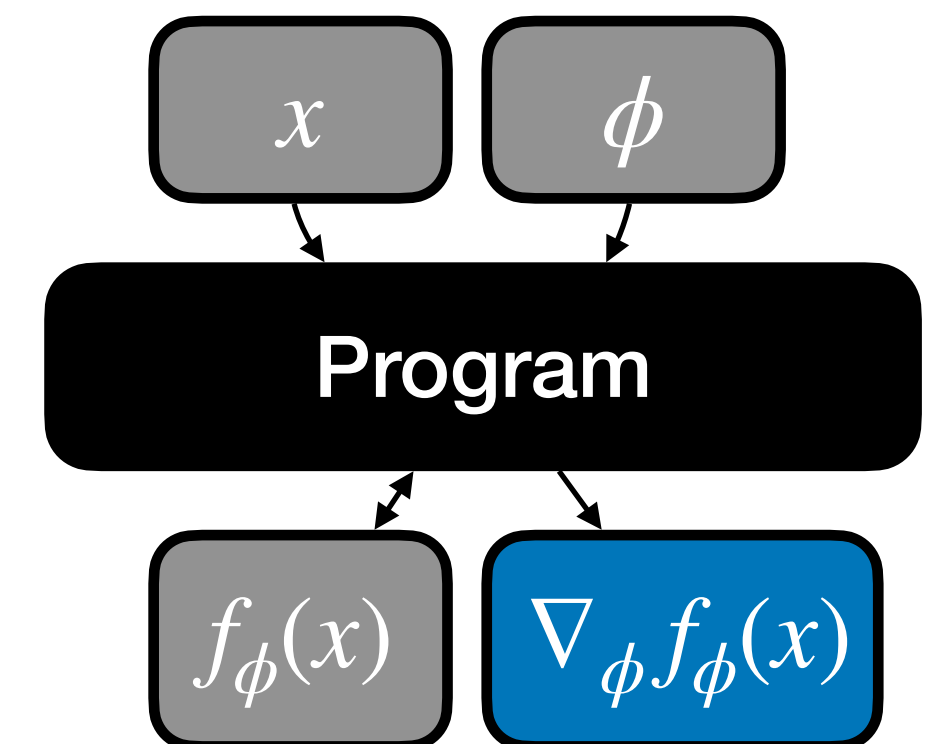
exact gradients!

```
gfunc = jax.value_and_grad(func)
gfunc(jnp.array([2., 3., -2]))

(DeviceArray(141.36212, dtype=float32),
 DeviceArray([ 49.          , -10.8799095, -87.66867 ]))
```



standard
programming



differentiable
programming

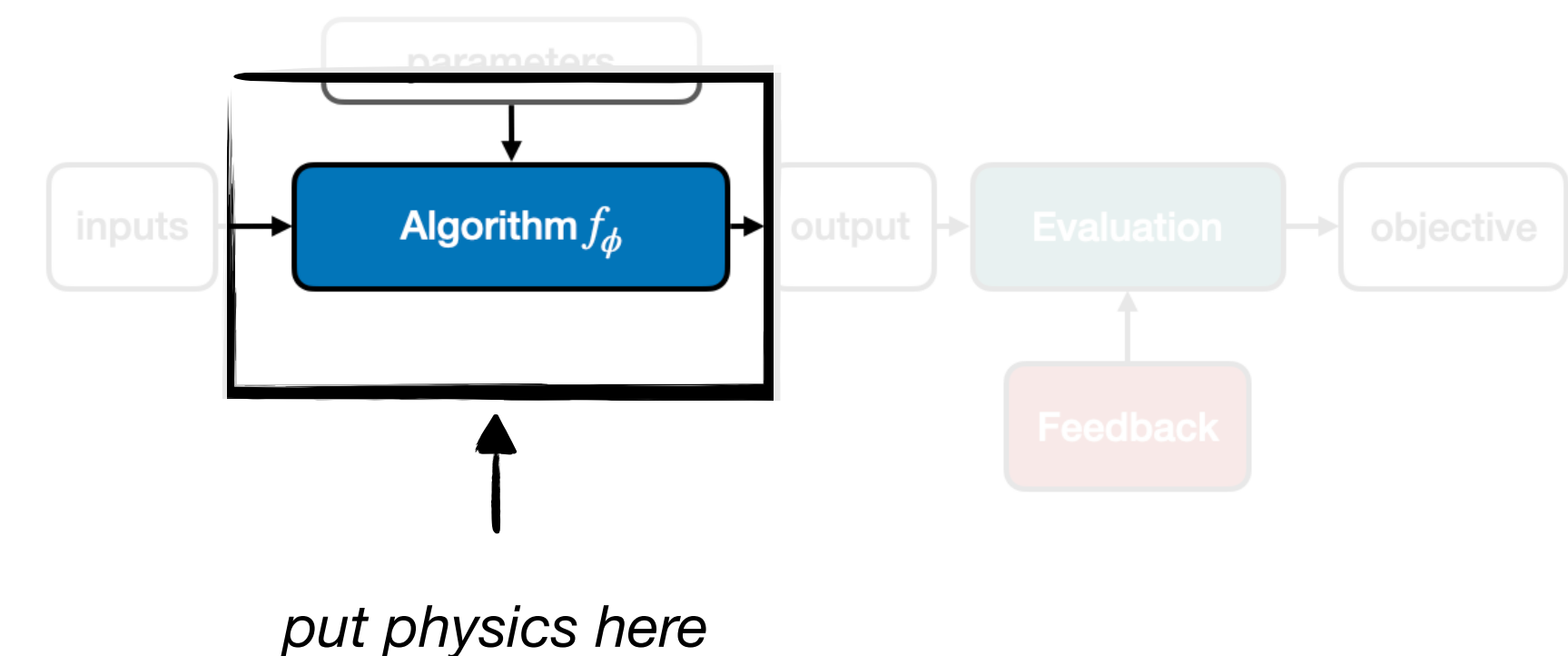
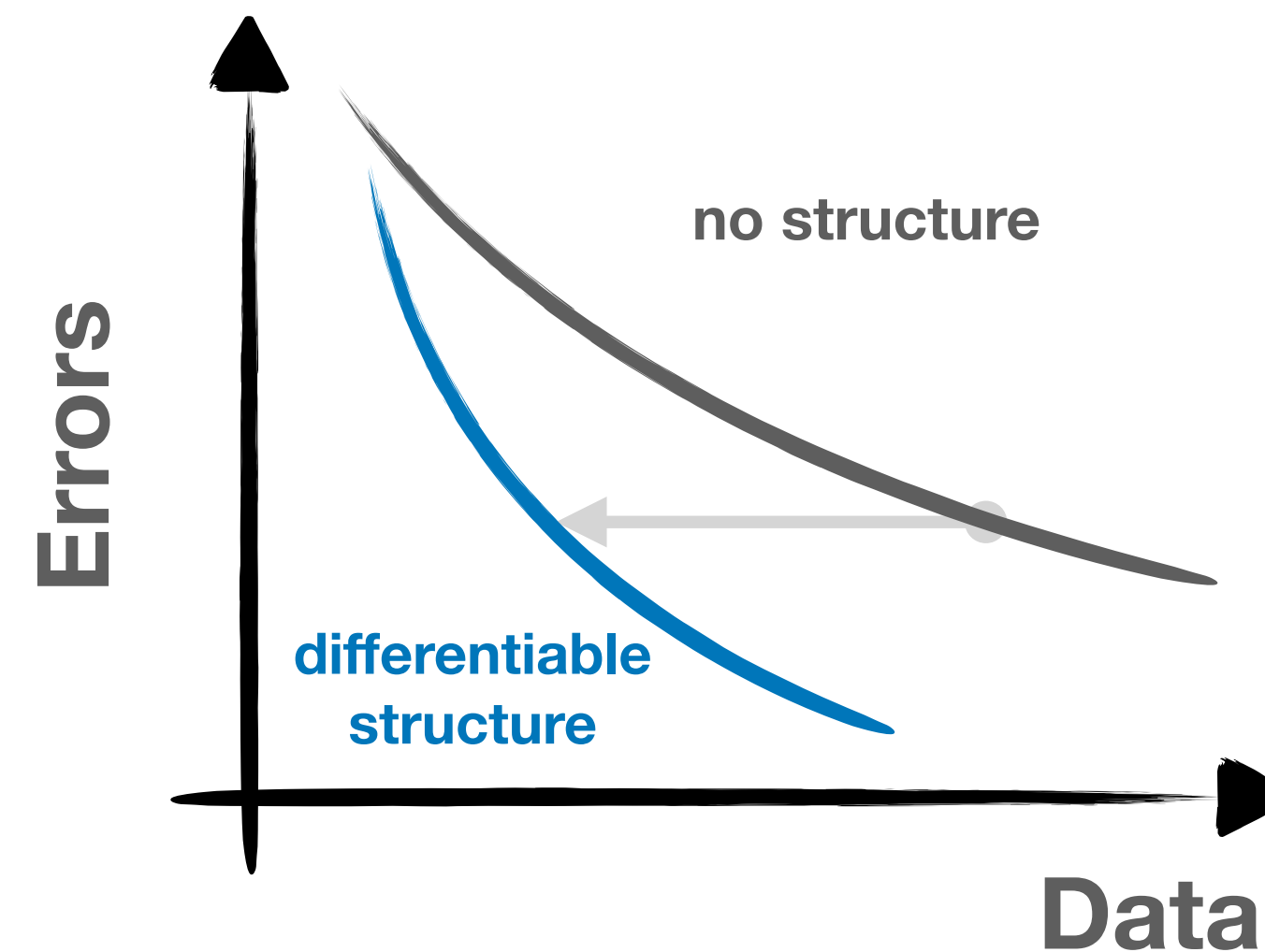
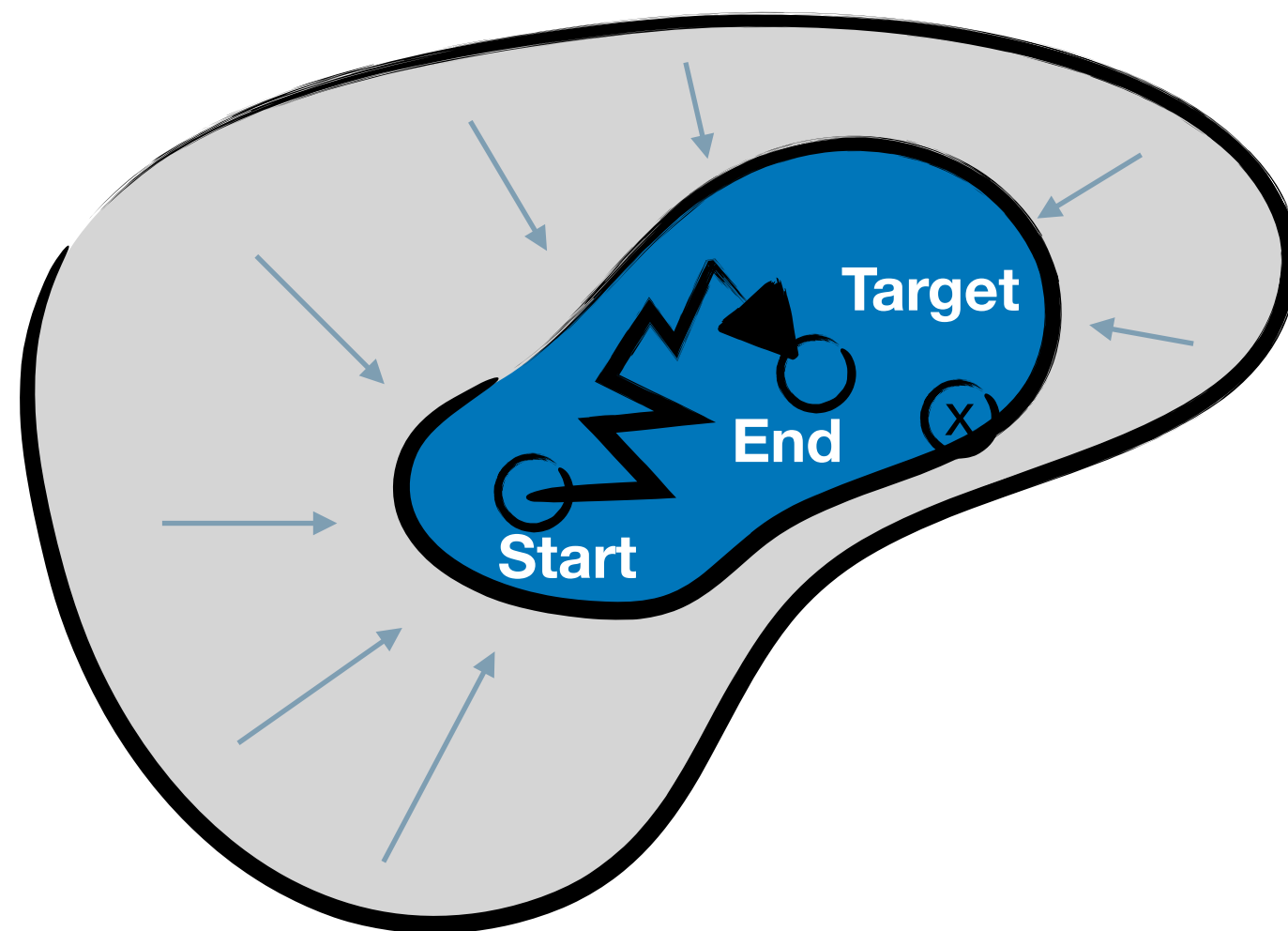


... but also C++, Fortran, ... (see backup)

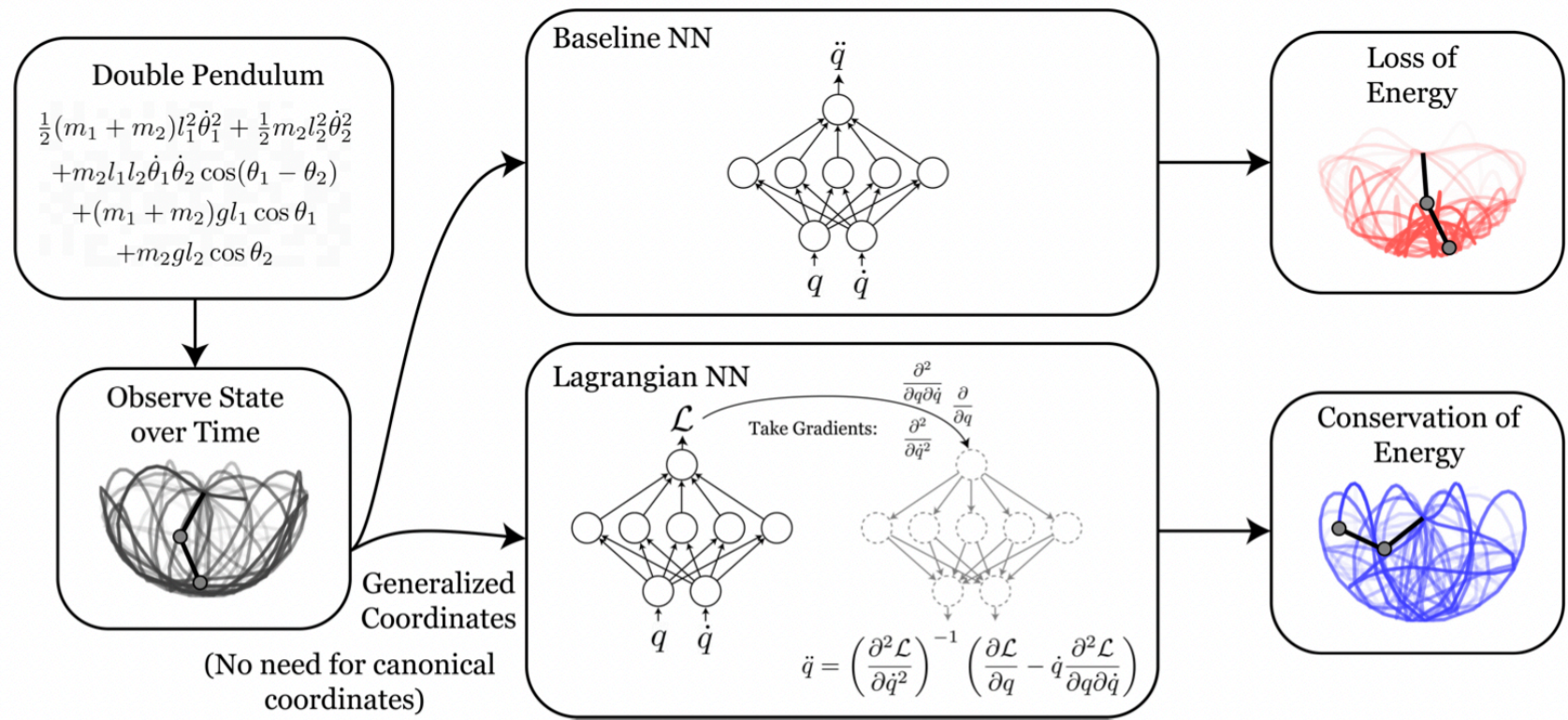
Differentiable Programming in ML

Immediate Gains from DiffProg: allows us to add physics into ML models

- **bias towards good solutions by constraining solution space**
- hard-coded knowledge does not need to be learned from data (efficiency)

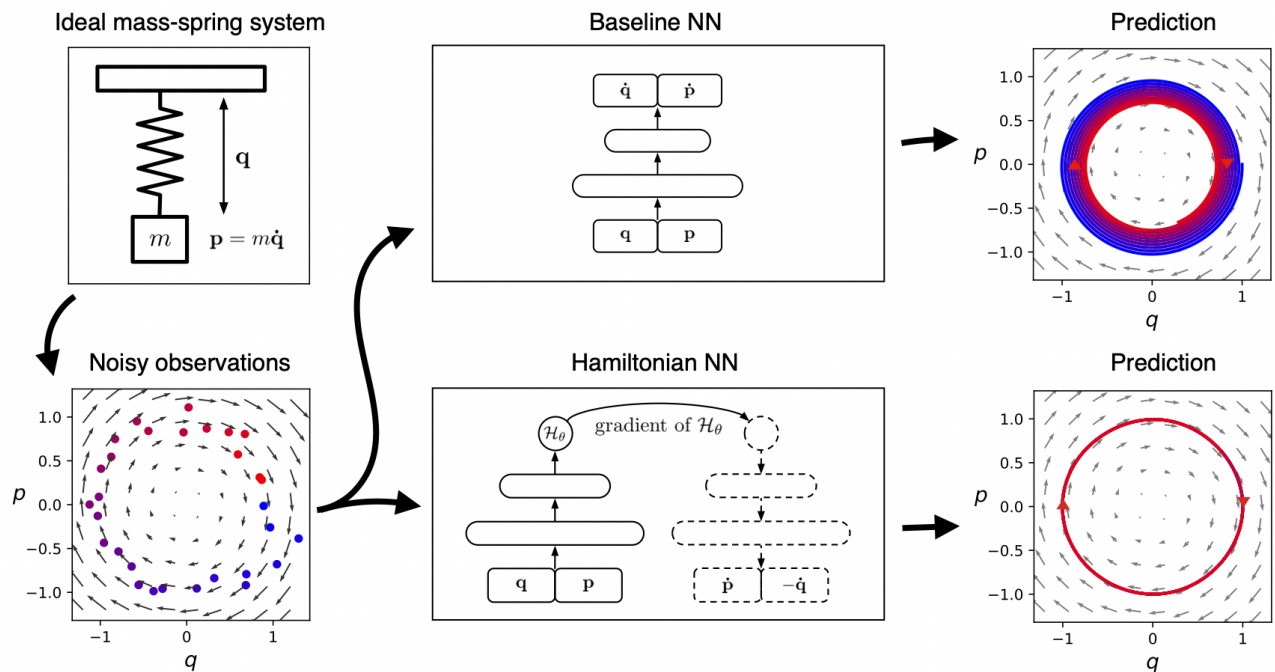
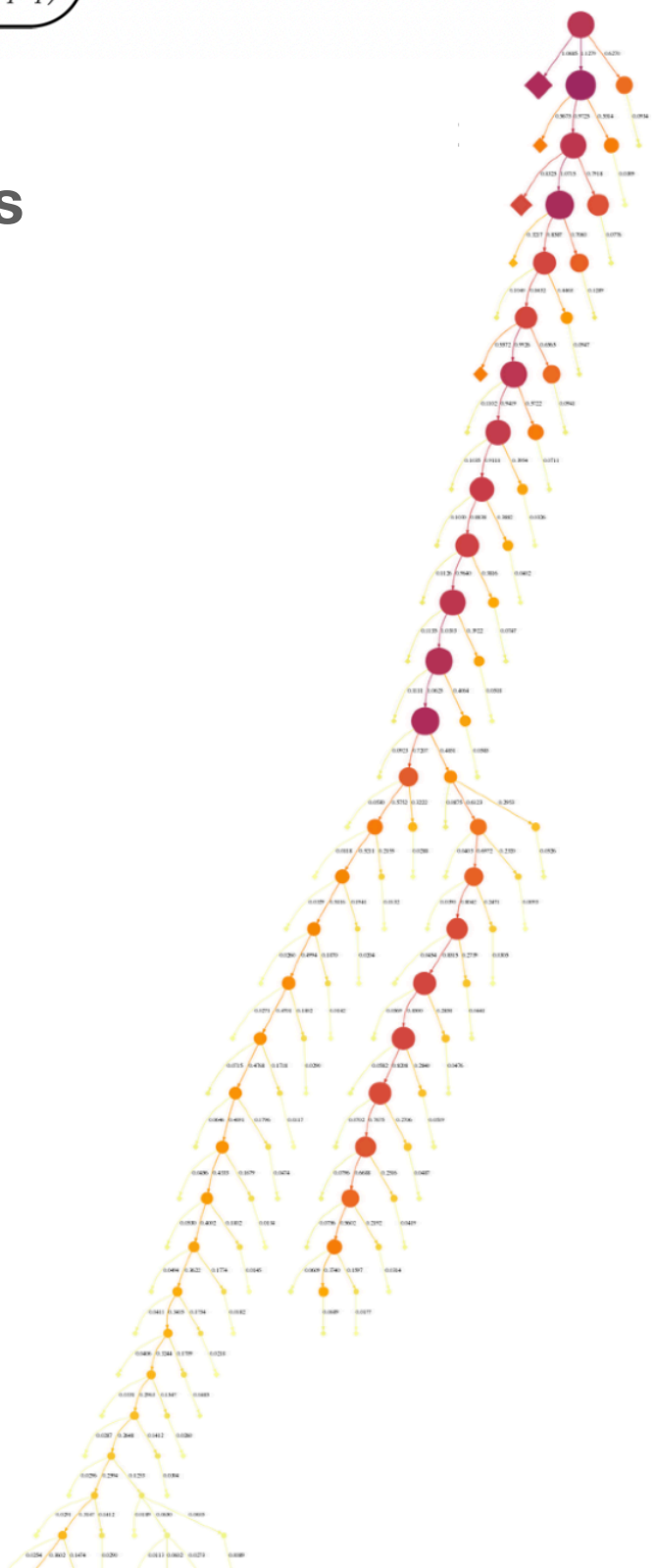


Differentiable Programming in ML

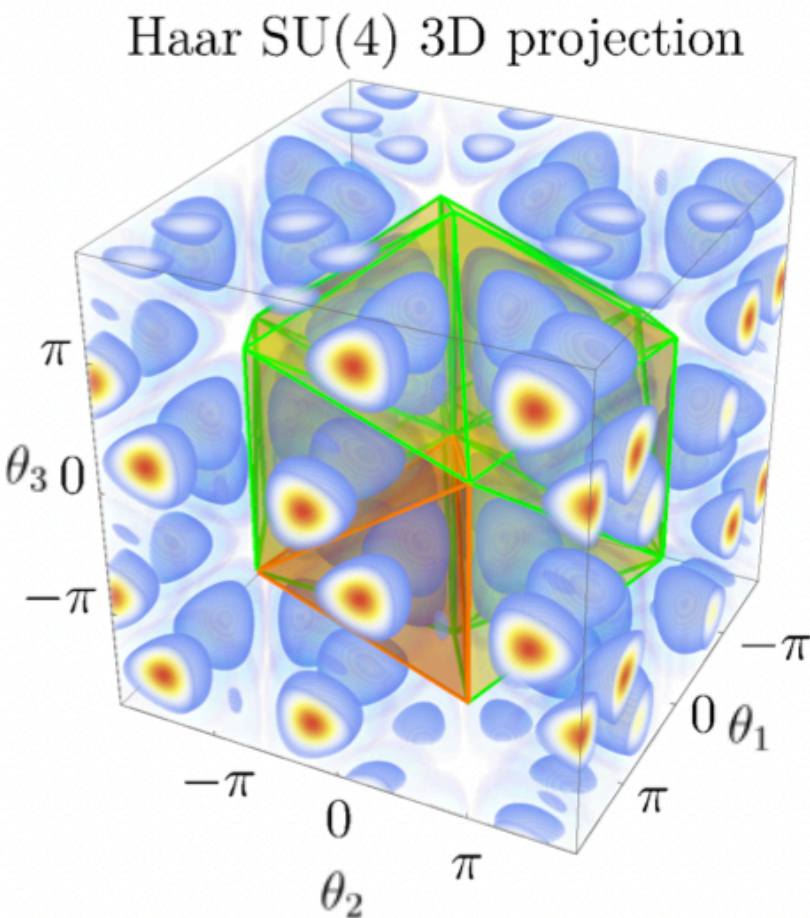


Lagrangian Neural Nets
arXiv: 2003.04630

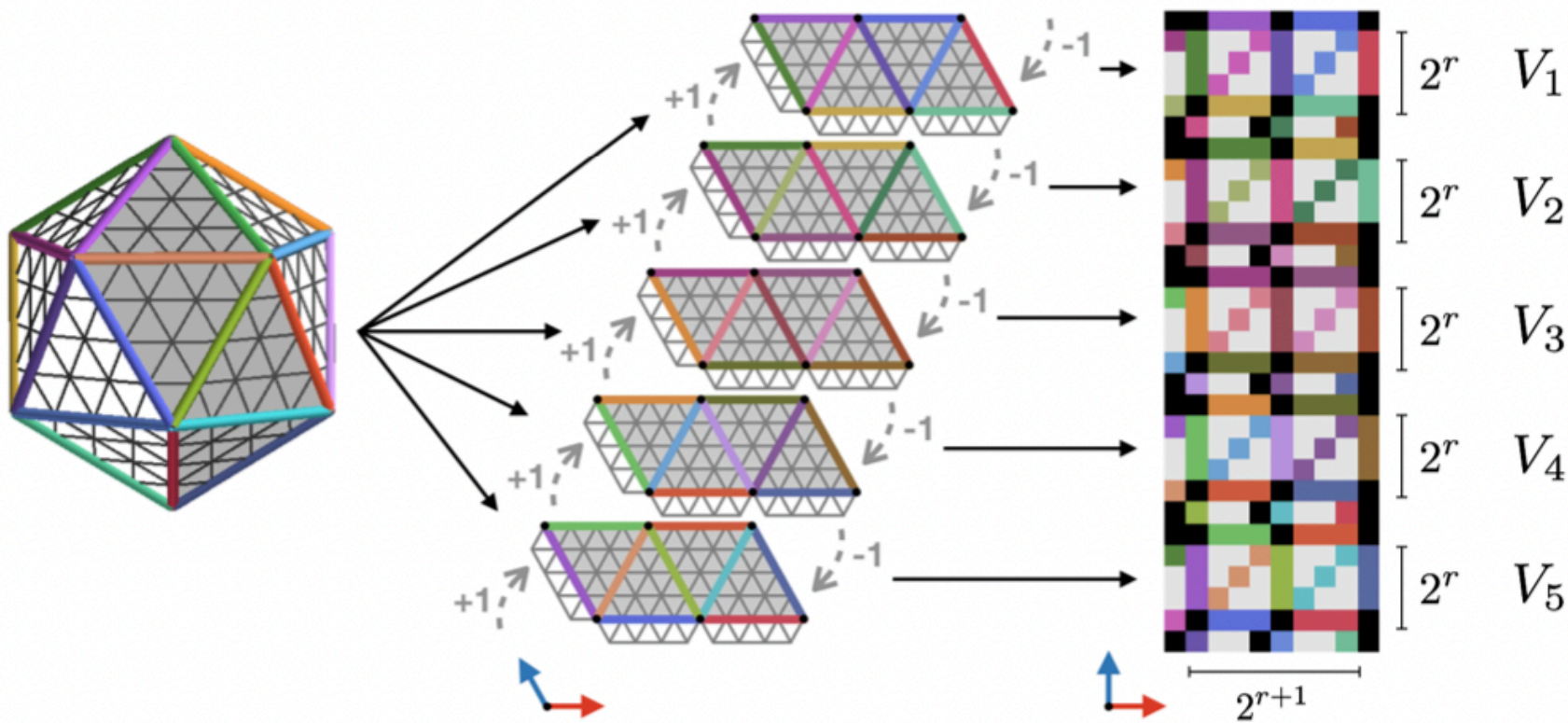
Neural Nets with QCD-like Structure
arXiv:1702.00748



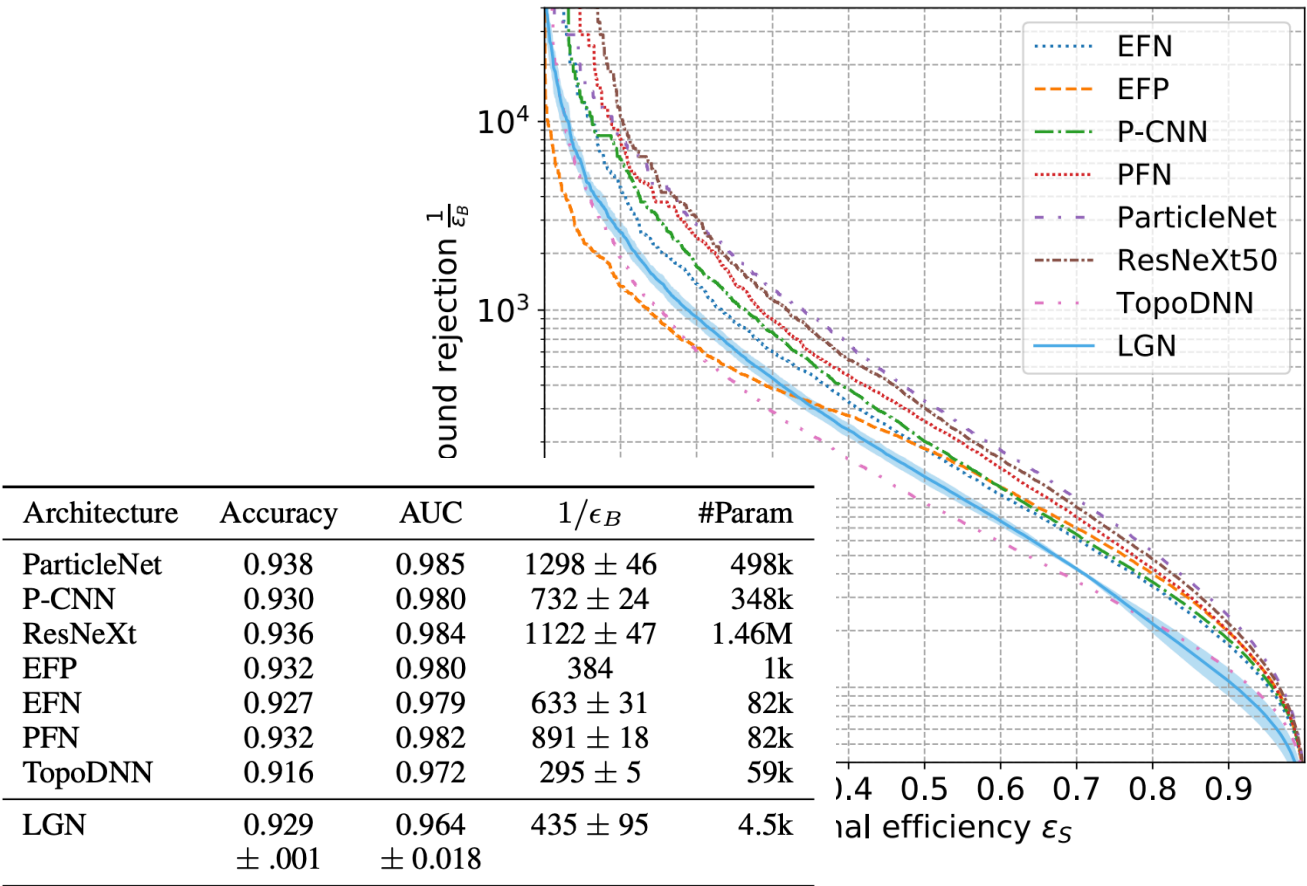
Hamiltonian Neural Nets
arXiv:1906.01563



SU(N)-Equivariant Normalizing Flows



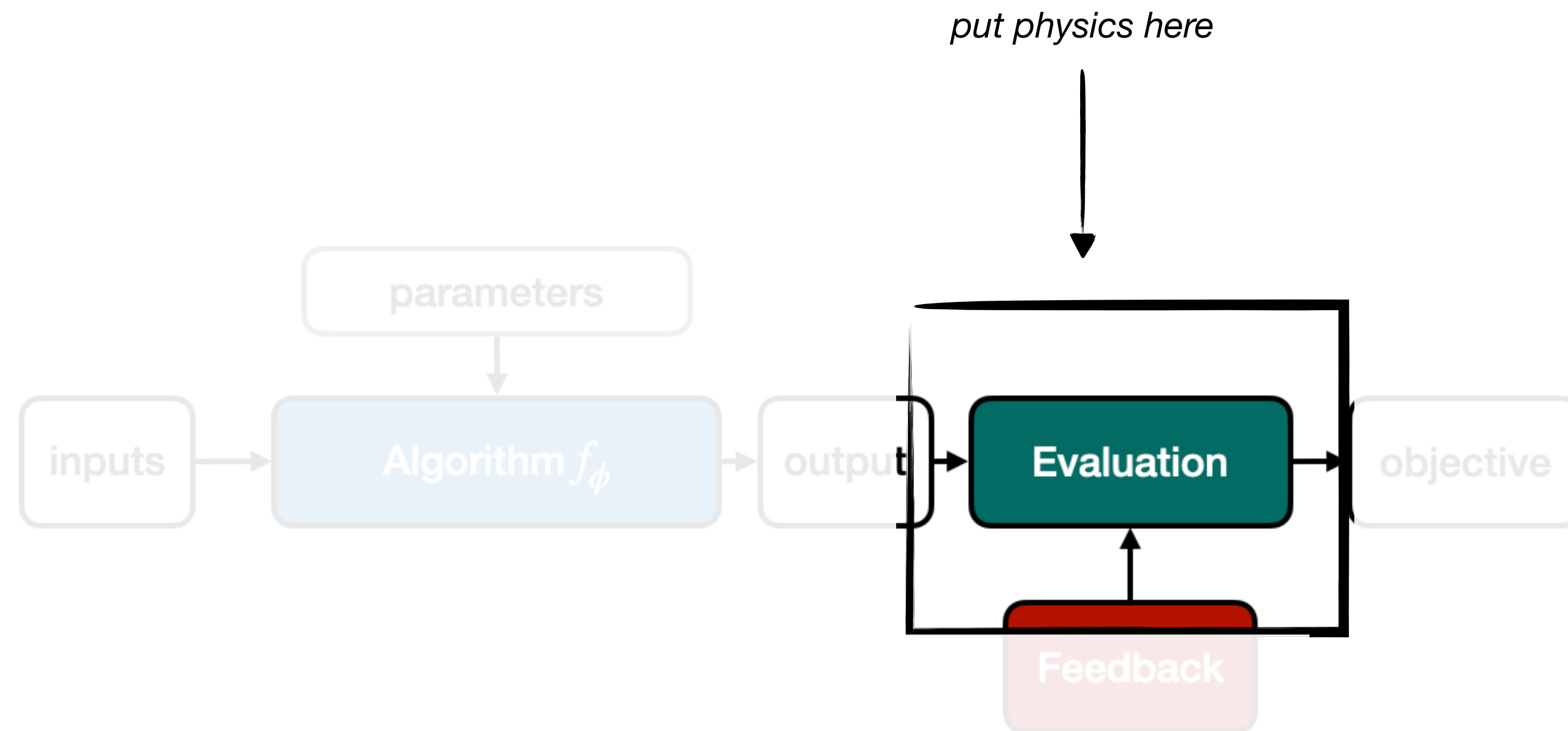
Gauge-Equivariant Convolutional Neural Networks



Lorentz-Invariance
arXiv:2006.04780

Differentiable Programming in ML

Complementary Approach: add physics-driven *evaluation*

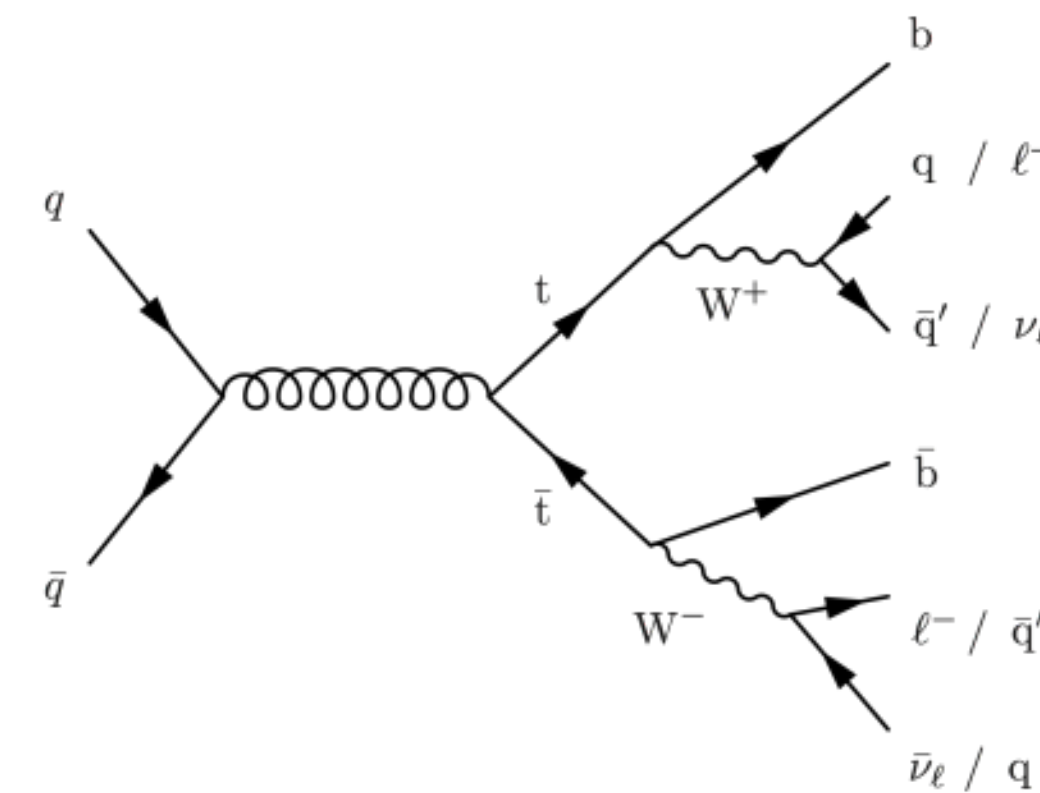


Differentiable Programming in ML

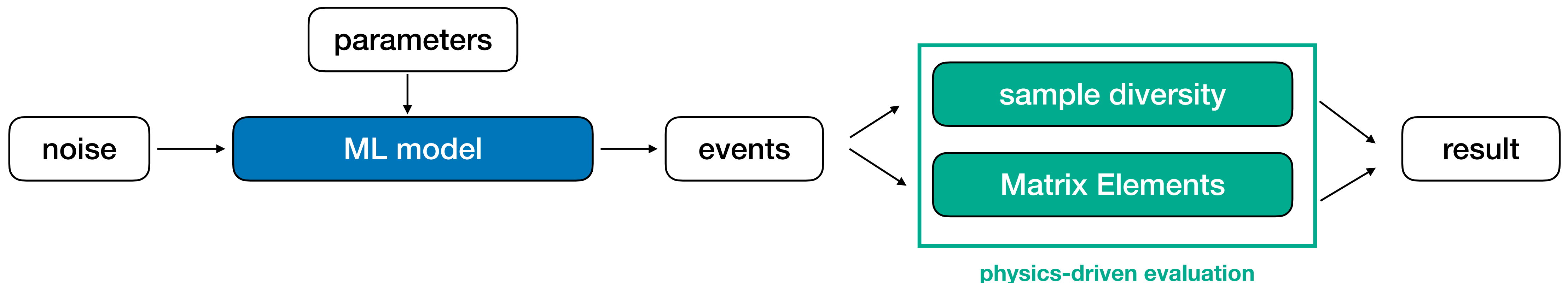
Training Fast Simulators: *produce events at correct relative proportions*

At parton level, events should follow Matrix Element proportions

$$\sigma(x, \theta) = \sum_i |\mathcal{M}_i(x, \theta)|^2$$

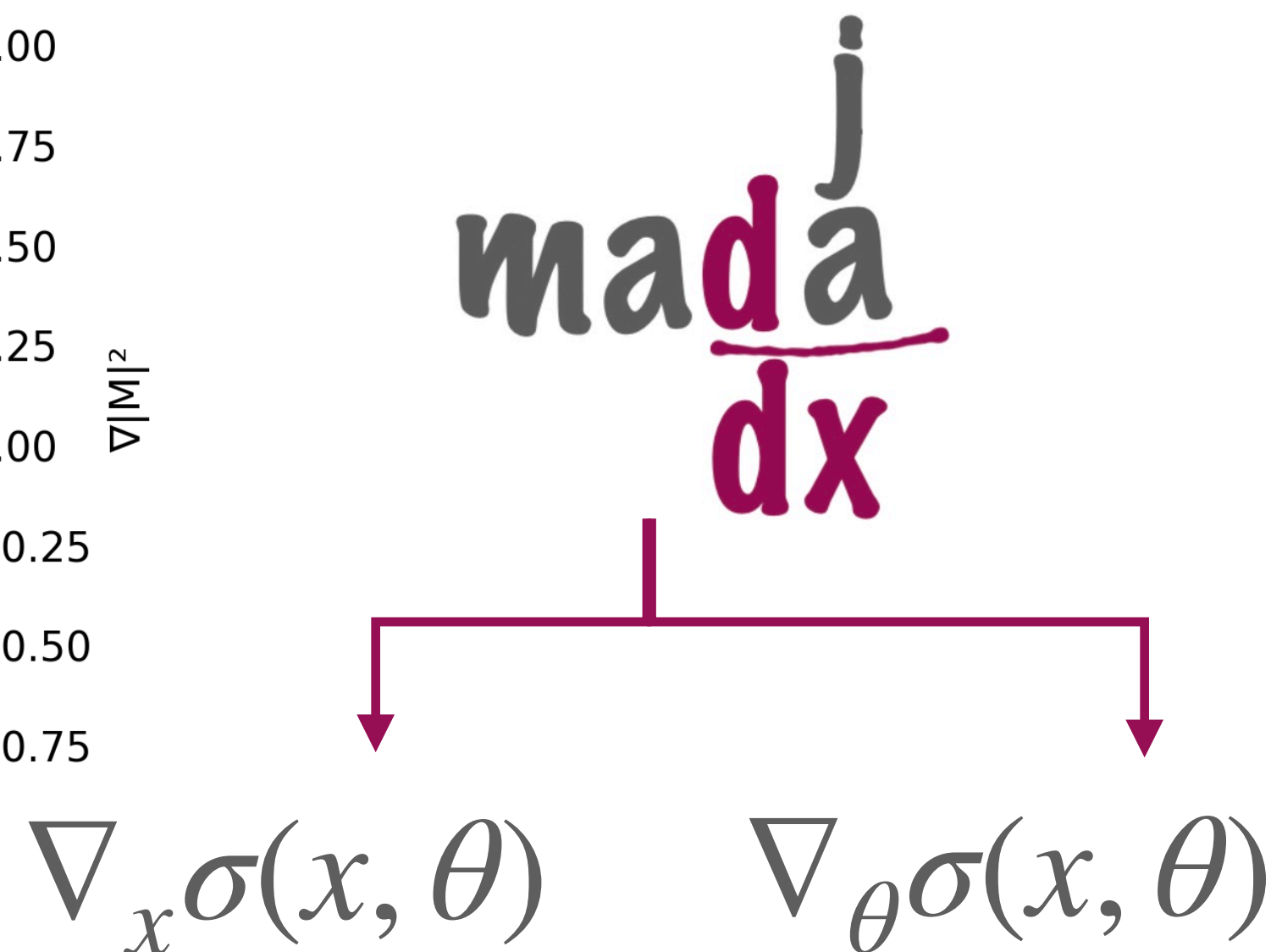
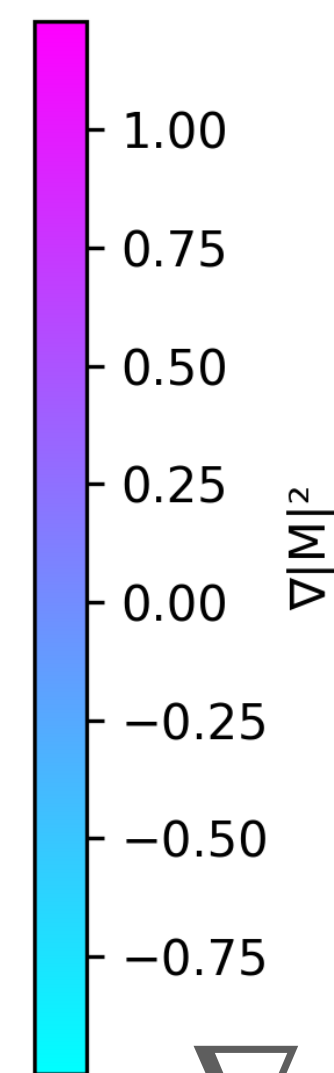
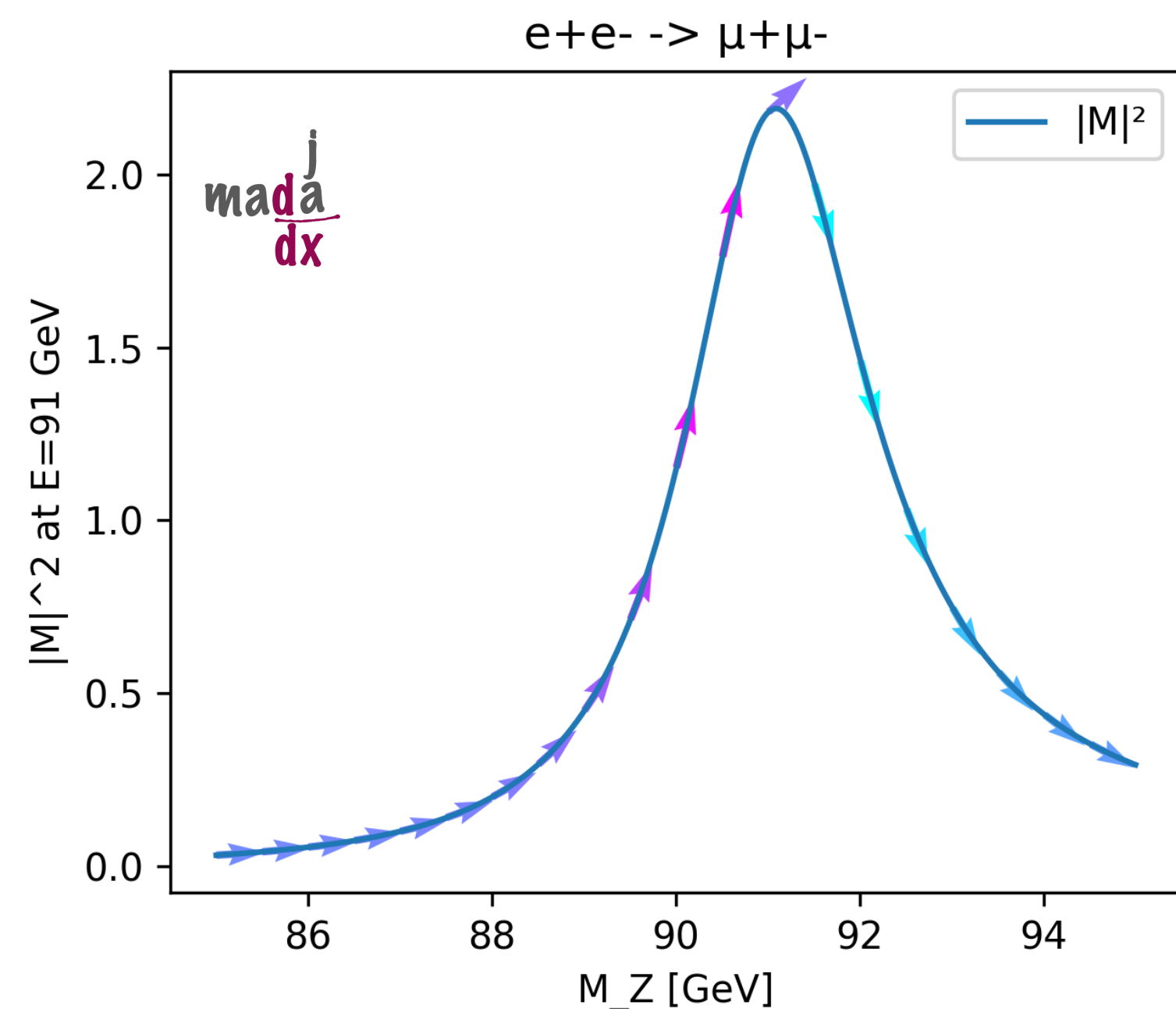


If we have **differentiable Matrix Elements** $|\mathcal{M}|^2(\{\vec{p}_i\}, \theta)$ we can check directly



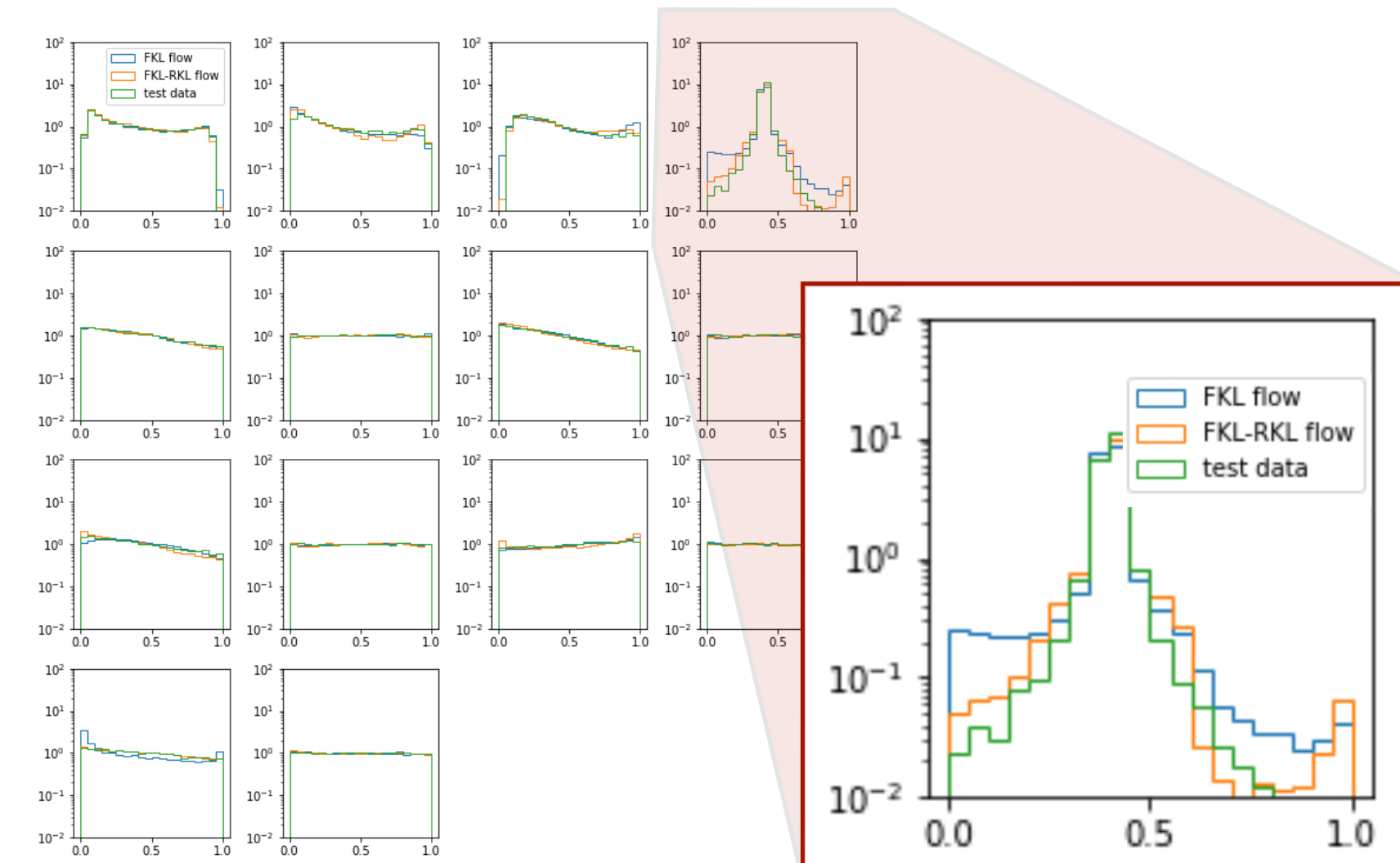
Differentiable Programming in ML

MadJax: MadGraph calculations (originally FORTRAN) transpiled into differentiable programming language (JAX) → **usable as evaluation function during training**



**phase-space
derivatives**

**theory Parameter
derivatives**



*better description of density than
pure ML training*

`mg5_aMC -mode=madjax_me_gen -f ee_to_mumu.mg5`

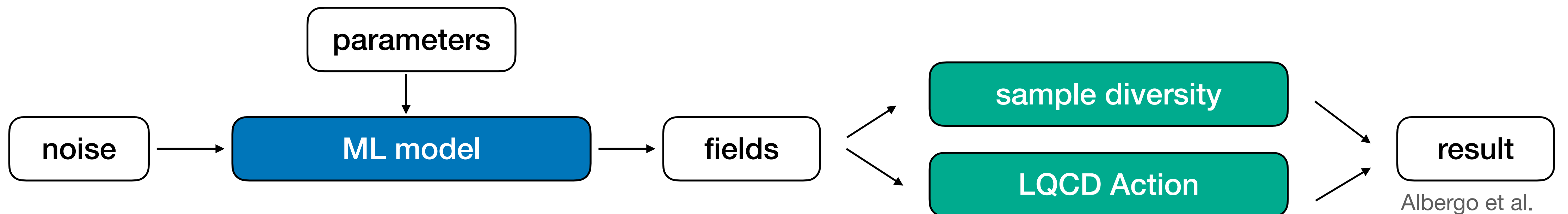
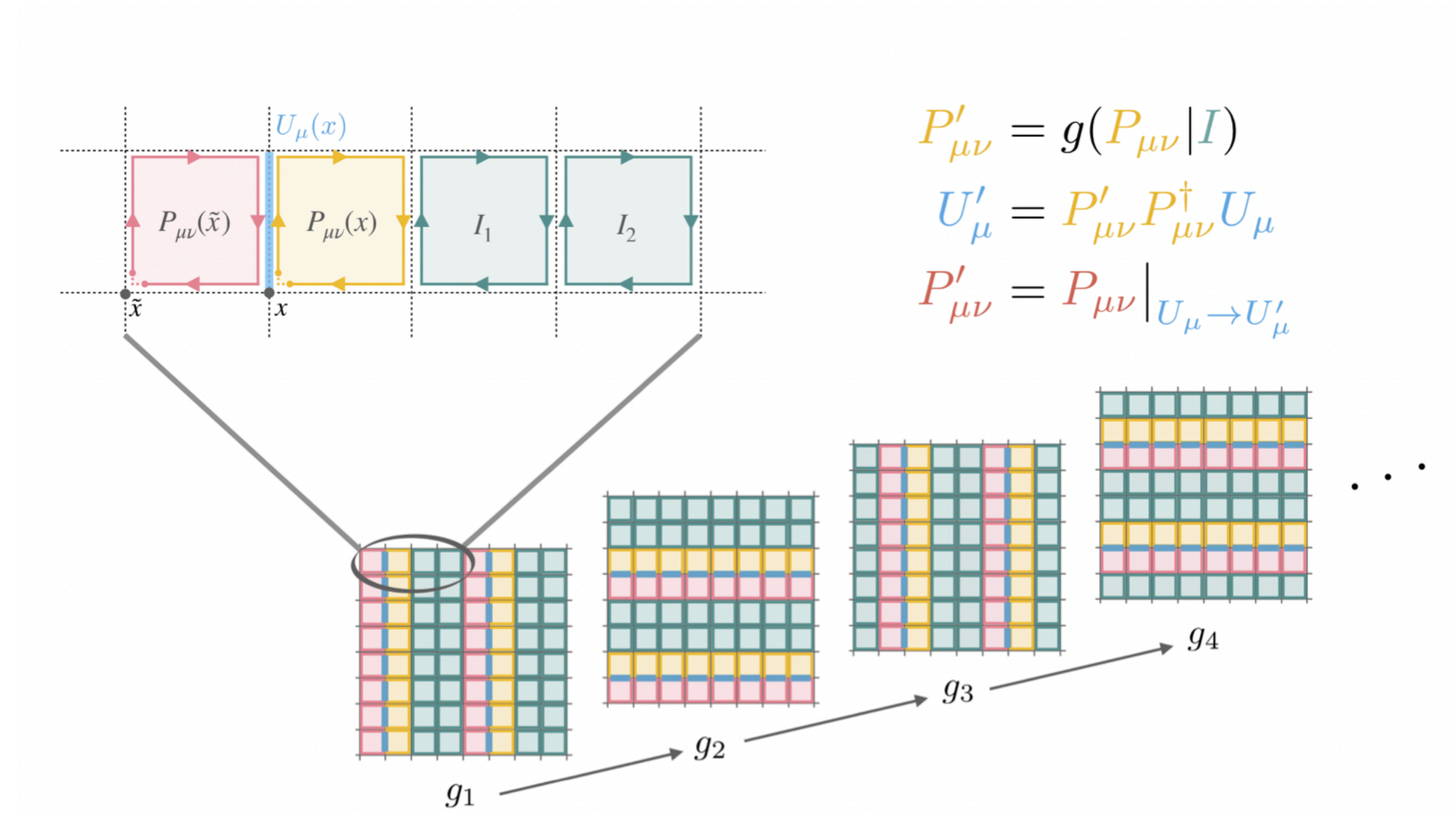
[LH, M. Kagan]
arxiv:2203.00057

Differentiable Programming in ML

Same approach in Lattice QCD:

Learn **proposal distribution** for sampling of fields on a lattice (for MCMC / IS)

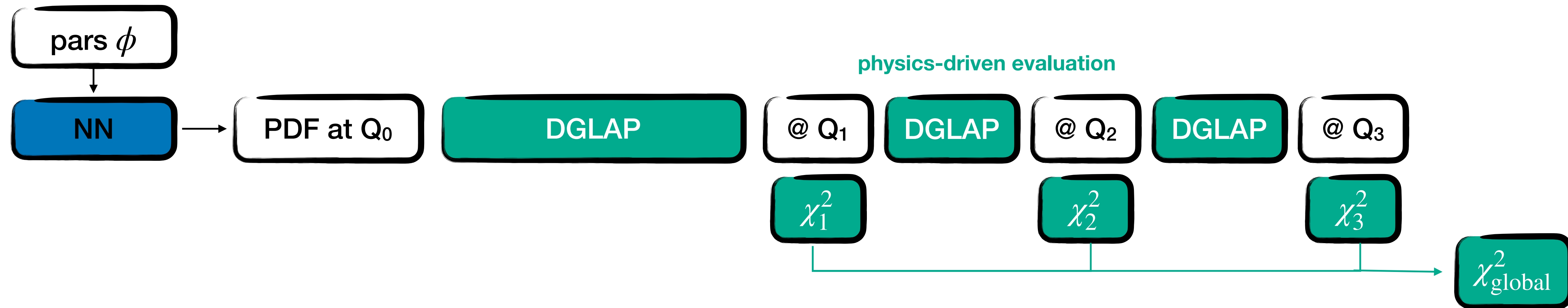
- encode symmetries in ML sampler
- evaluate on LQCD action in DiffProg language (pytorch)



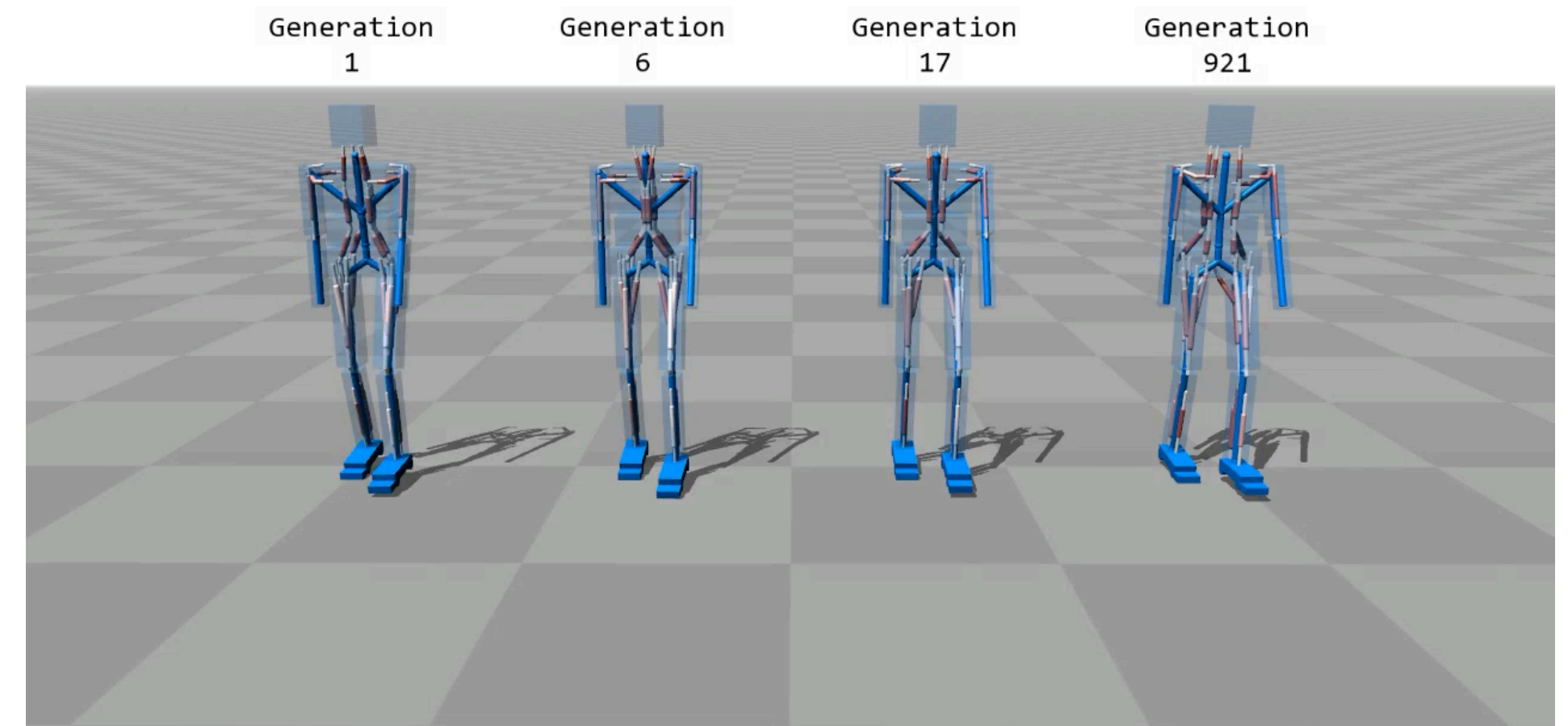
Differentiable Programming in ML

Parton Density Functions: DP can train NNPDF as it was meant to be trained

One of the early use-cases of NNs in HEP: PDF parametrizations



Curiosity:
traditionally **not(!) trained via gradient-descent**
→ too difficult to get gradients
→ use genetic algorithms (mutation + select)
→ works but is slow



genetic algorithms

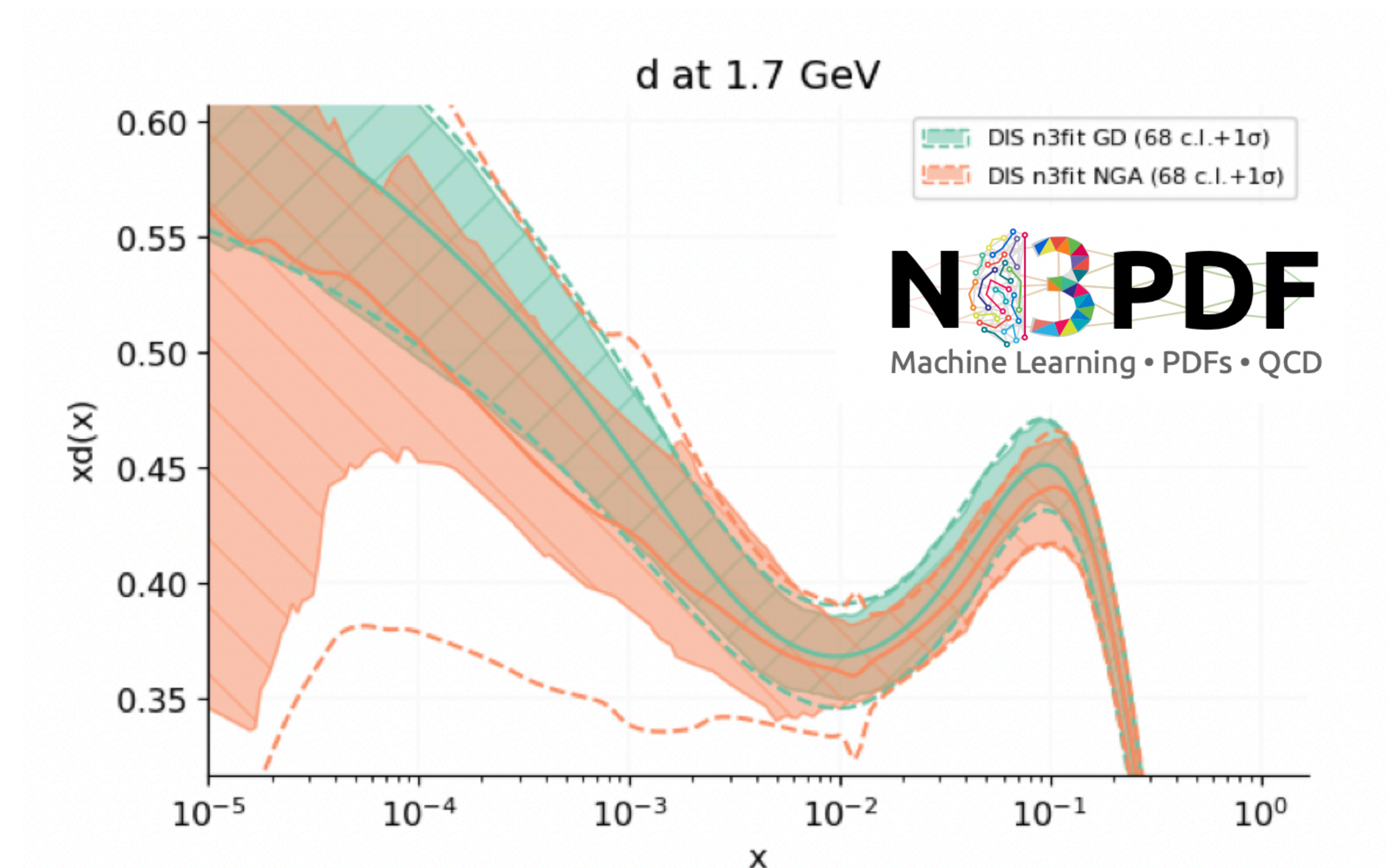
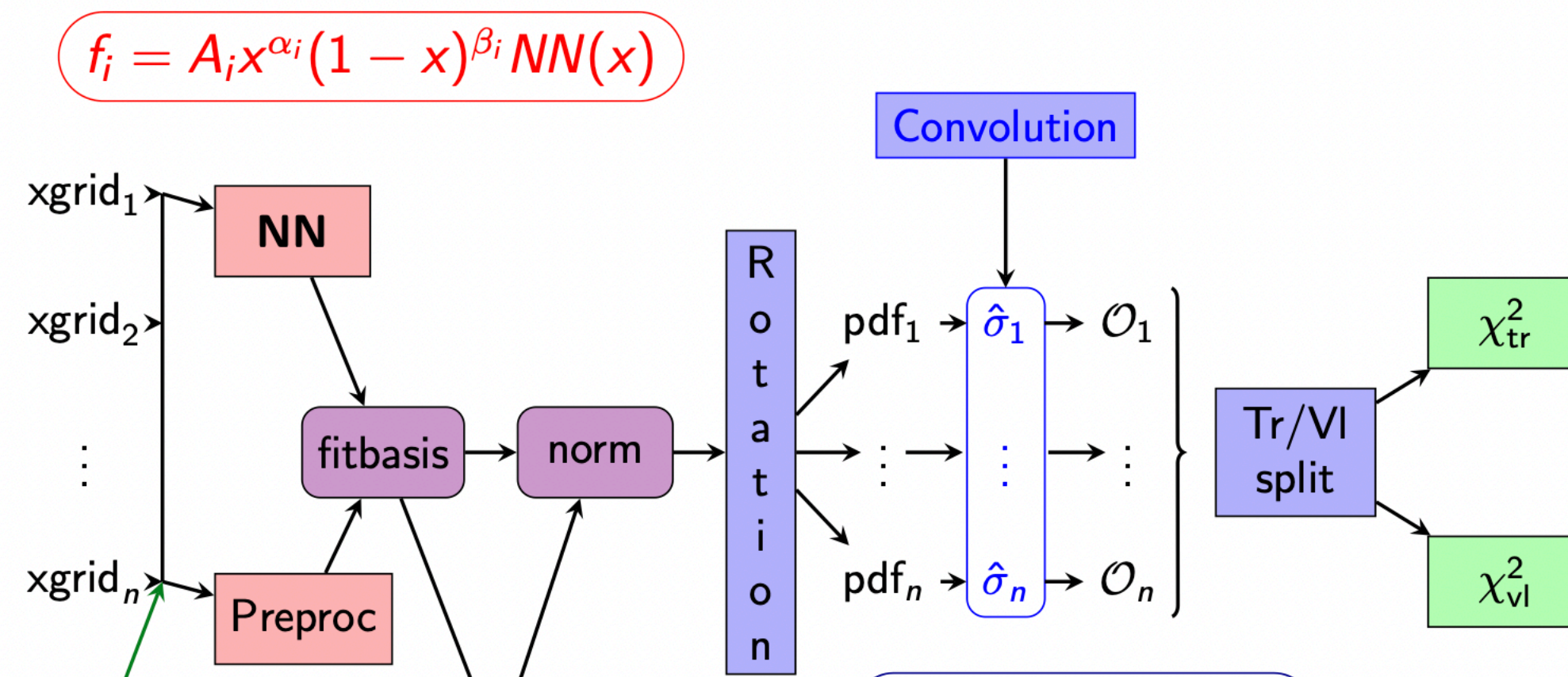
[Source]

Differentiable Programming in ML

More recently: PDF evolution kernels implemented in DiffProg (Tensorflow)

- allows finally for a gradient-based training of NN

For all fits shown in this paper we utilize **gradient descent (GD)** methods to substitute the previously used **genetic algorithm**. This change can be shown to greatly **reduce the computing cost** of a fit while maintaining a very similar (and in occasions improved) χ^2 -goodness. The less stochastic nature of GD methods also produces more stable fits than its GA counterparts. **The main reason why the GD methods had not been tested before** were due to the **difficulty of computing the gradient** of the loss function (mainly due to the convolution with the fastkernel tables) in a efficient way. This is one example on how the usage of new technologies can facilitate new studies thanks to **differentiable programming** and distributed computing.

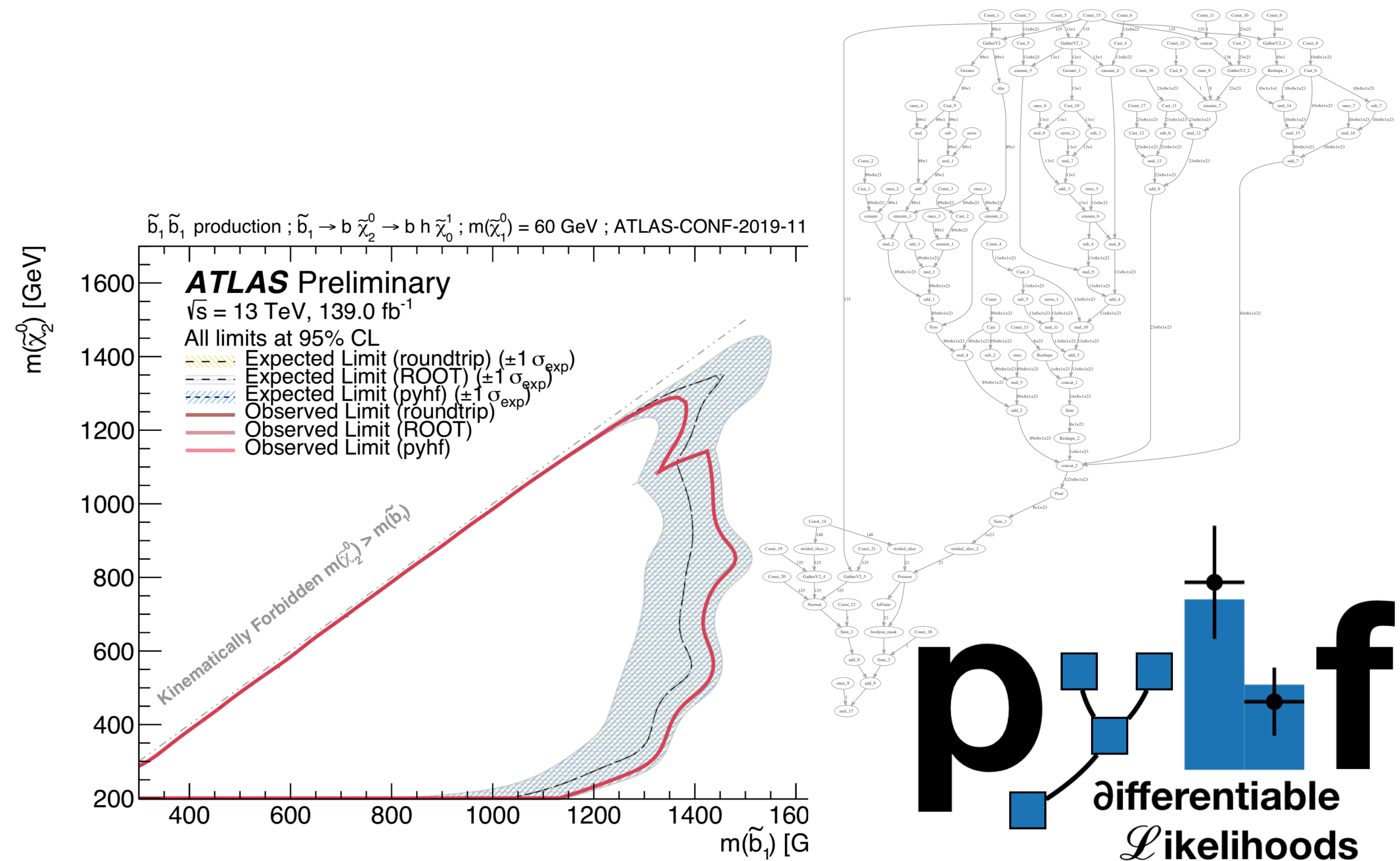


Differentiable Programming Beyond ML

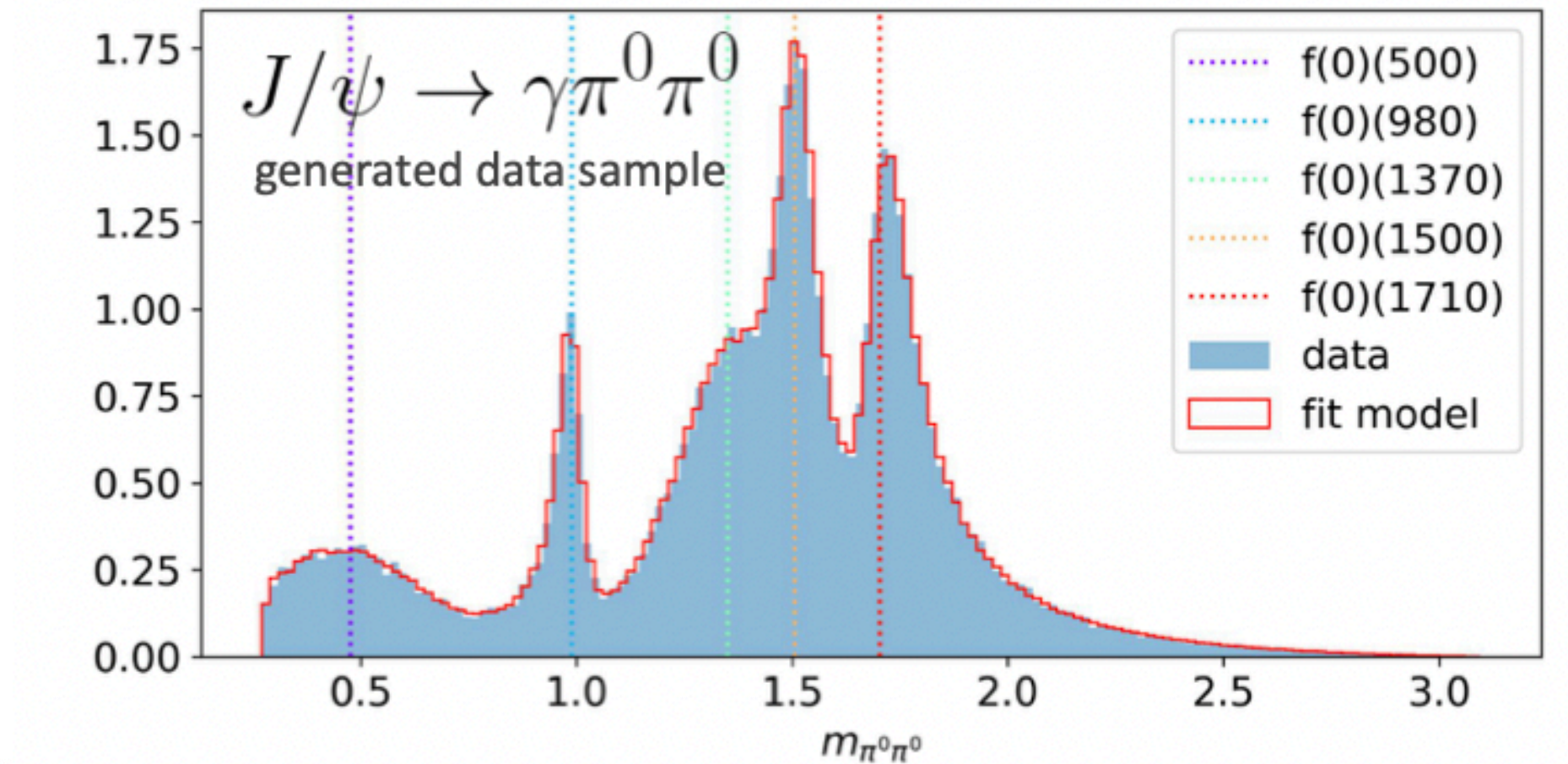
Gradients useful far beyond ML: e.g. complex fits via differentiable programming

Binned Likelihoods (LHC, EIC, Belle-II, ...)

Partial Wave Analysis



pyhf [LH, G. Start, M. Feickert]



```
some_amplitude = model.components[
    R"A_{D^0_{\{0\}}_{\{0\}}} \to K^+_{\{0\}}_{\{0\}} a_{\{0\}}(980)^{\{0\}}_{\{0\}}; a_{\{0\}}(980)^{\{0\}}_{\{0\}} \to K^{+}_{\{+\}_{\{0\}}} K^{-}_{\{-\}_{\{0\}}}"
]
```

$$C_{D^0 \rightarrow K_0^0 a_0(980)^0; a_0(980)^0 \rightarrow K_0^+ K_0^-} \Gamma_{a_0(980)^0} m_{a_0(980)^0} \sqrt{B_0^2 \left((d_{a_0(980)^0})^2 q_{122}^2 (m_{12}^2) \right) D_{0,0}^0(-\phi_{1+2}, \theta_{1+2}, 0) D_{0,0}^0(-\phi_{1,1+2}, \theta_{1,1+2}, 0)}$$

$$= \frac{C_{D^0 \rightarrow K_0^0 a_0(980)^0; a_0(980)^0 \rightarrow K_0^+ K_0^-} \Gamma_{a_0(980)^0} m_{a_0(980)^0}}{i \Gamma_{a_0(980)^0} (m_{a_0(980)^0})^2 \sqrt{\frac{(m_{12}^2 - (m_1 - m_2)^2)(m_{12}^2 - (m_1 + m_2)^2)}{m_{12}^2}} - m_{12}^2 + (m_{a_0(980)^0})^2}}$$

$$= \frac{0.074}{-m_{12}^2 + 0.96 - \frac{0.599 \sqrt{m_{12}^2 - 0.975}}{m_{12}}}$$

ComPWA [R. deBoer, M. Mikhasenko]

Speaking of Genetic Algorithms...

Speaking of Genetic Algorithms...

Automated Antenna Design with Evolutionary Algorithms

Gregory S. Hornby

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University of California Santa Cruz, Mailstop 269-3, NASA Ames Research Center, Moffett Field, CA

Al Globus

San Jose State University

Derek S. Linden

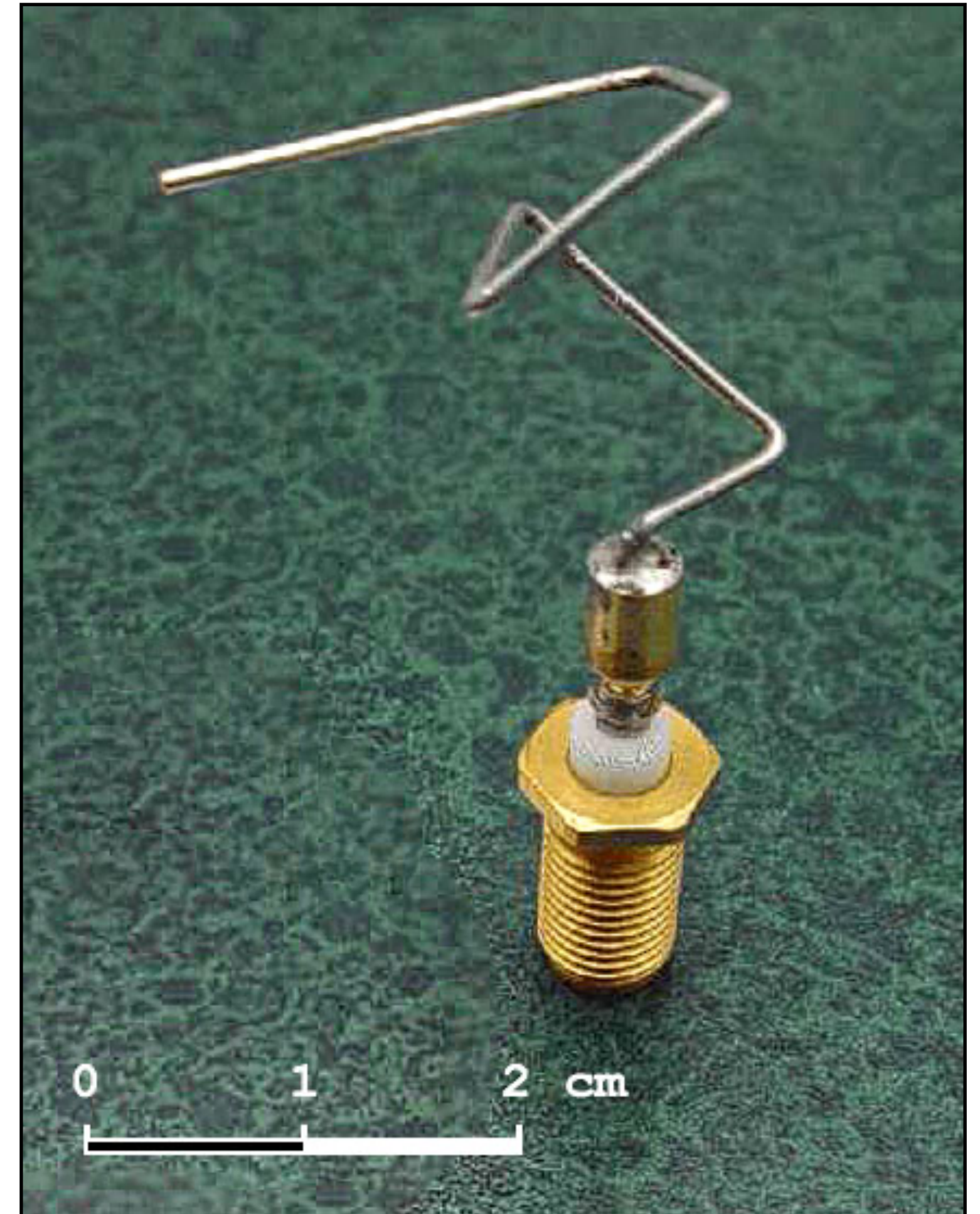
JEM Engineering, 8683 Cherry Lane, Laurel, Maryland 20707

Jason D. Lohn

NASA Ames Research Center, Mail Stop 269-1, Moffett Field, CA 94035

Whereas the current practice of designing antennas by hand is severely limited because it is both time and labor intensive and requires a significant amount of domain knowledge, evolutionary algorithms can be used to search the design space and automatically find

The current practice of designing and optimizing antennas by hand is limited in its ability to develop new and better antenna designs because it requires significant domain expertise and is both time and labor intensive.

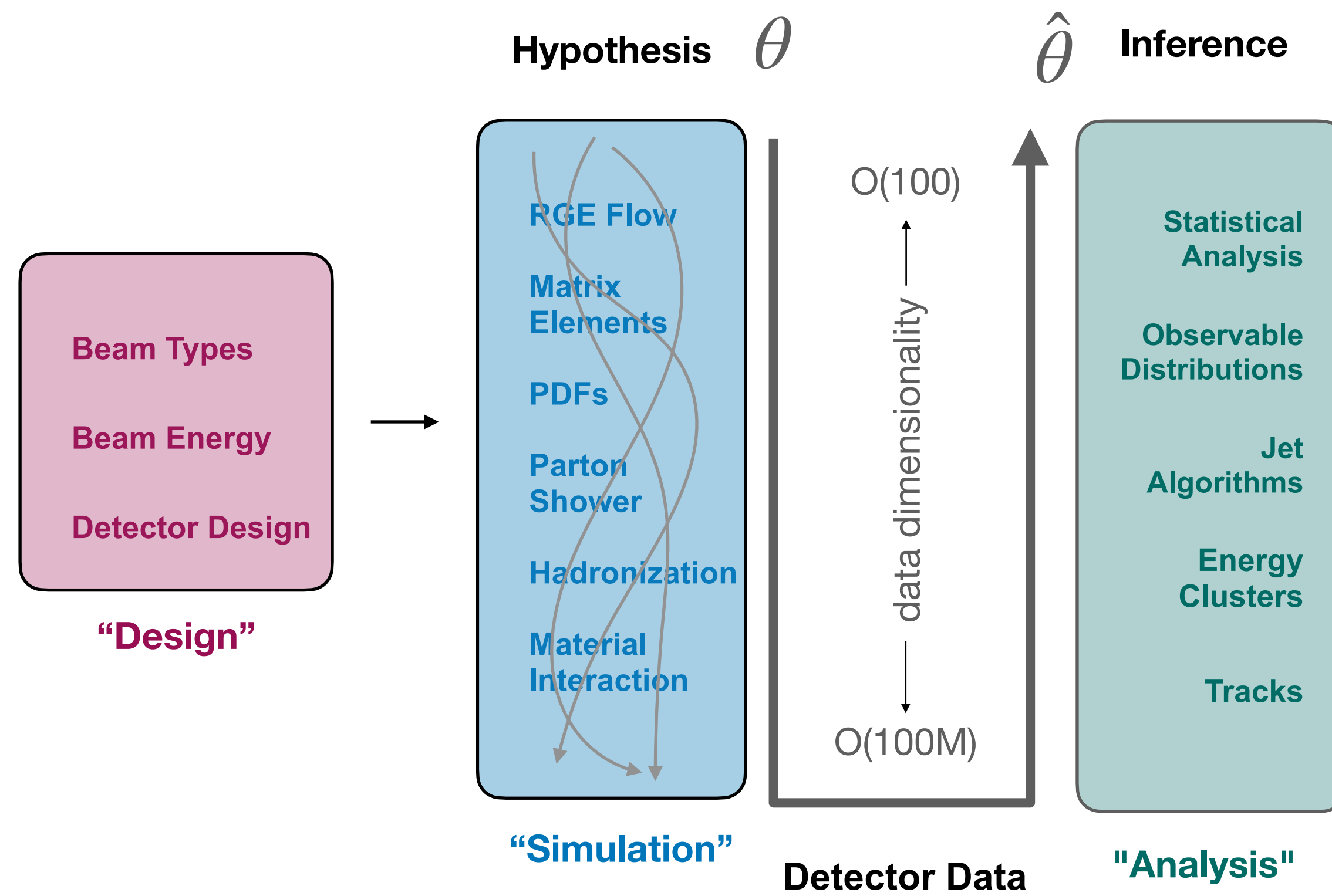


Algorithmic Optimization of Hardware?

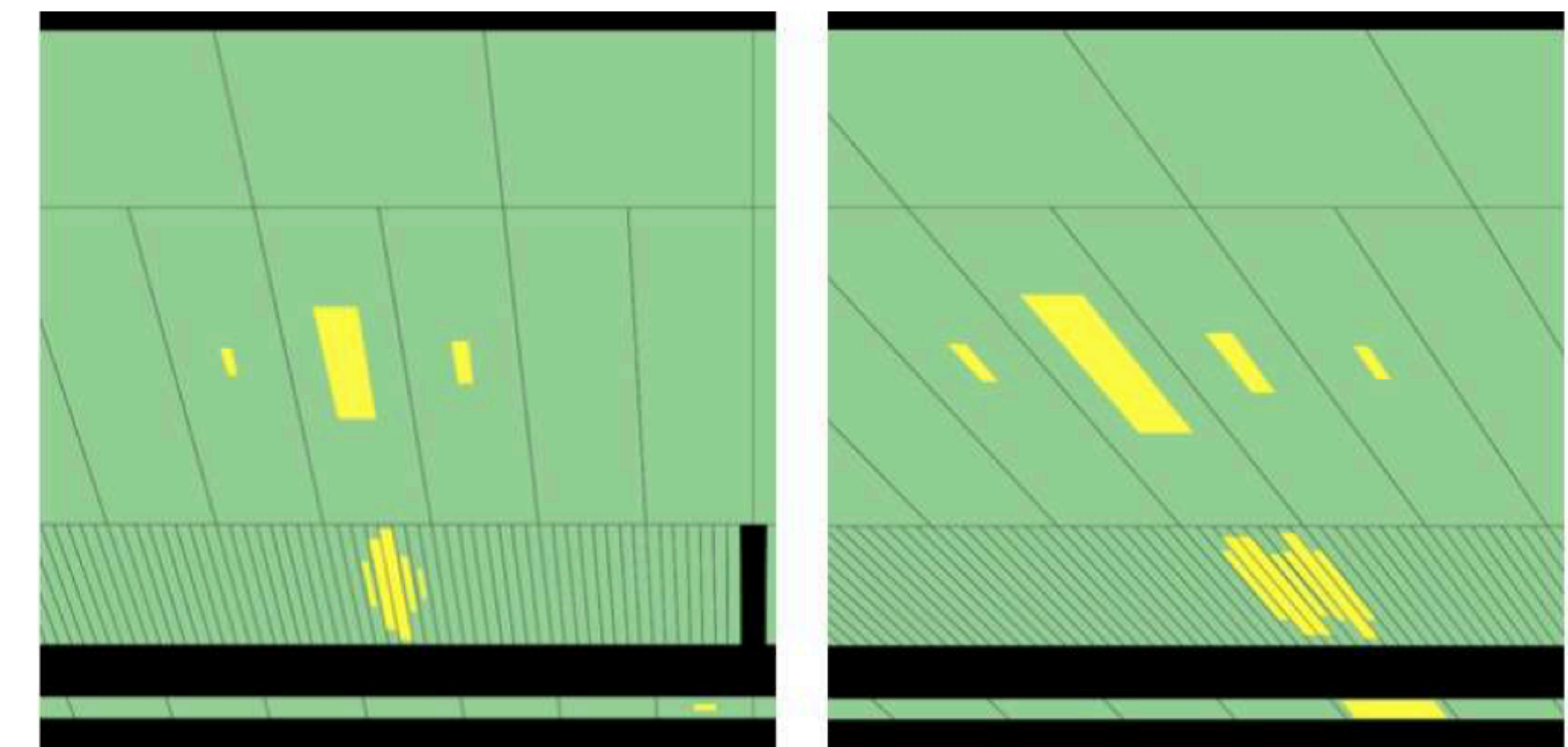
One more thing to tune:

Beyond reconstruction & analysis, we have an additional knob we can tune:

- the experiment design itself!



Example: ATLAS Calorimeter hand-designed for Higgs Discovery (Photon Pointing)



excellent photon identification and jet background rejection, by exploiting its fine longitudinal segmentation, thereby improving the signal to background ratio. Further, the diphoton invariant mass, defined as

$$m_{\gamma\gamma} = \sqrt{2E_1E_2(1 - \cos\theta)}$$

where E_1 , E_2 are the two photon energies and θ is the angle

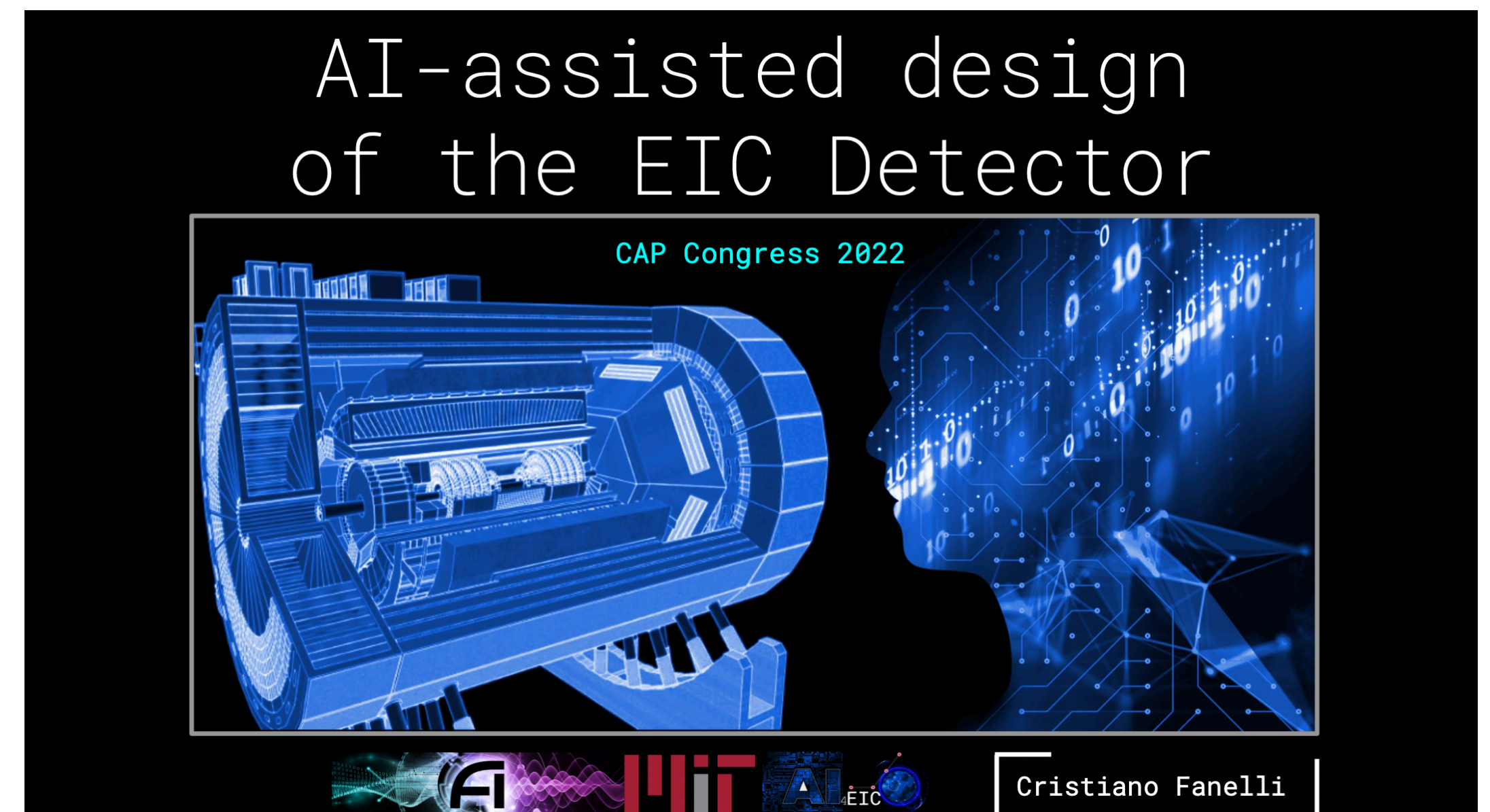
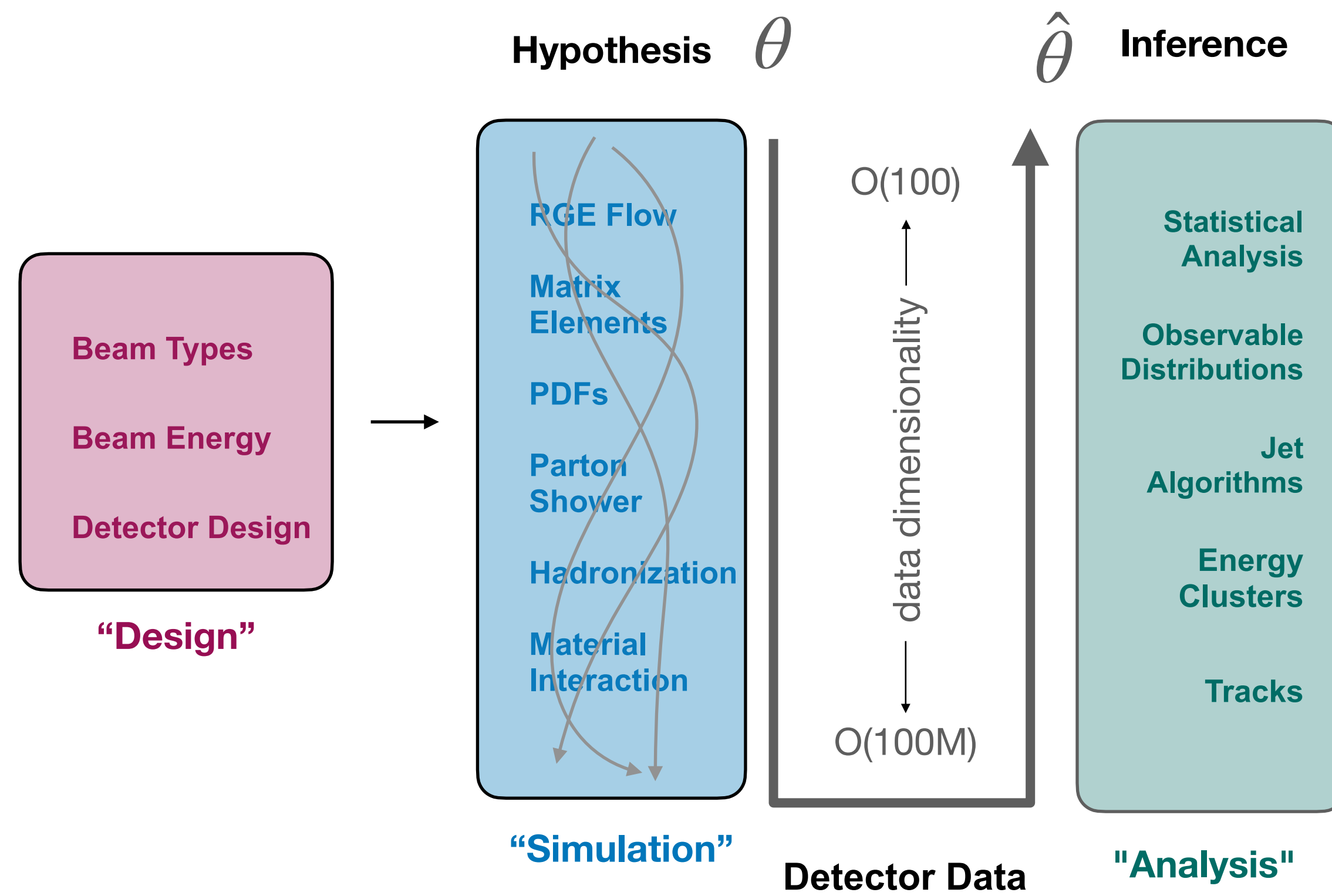
[Nikiforou, 1306.6756]

One more thing to tune:

Beyond reconstruction & analysis, we have an additional knob we can tune:

- the experiment design itself!

New Detectors are coming, can ML help design them?

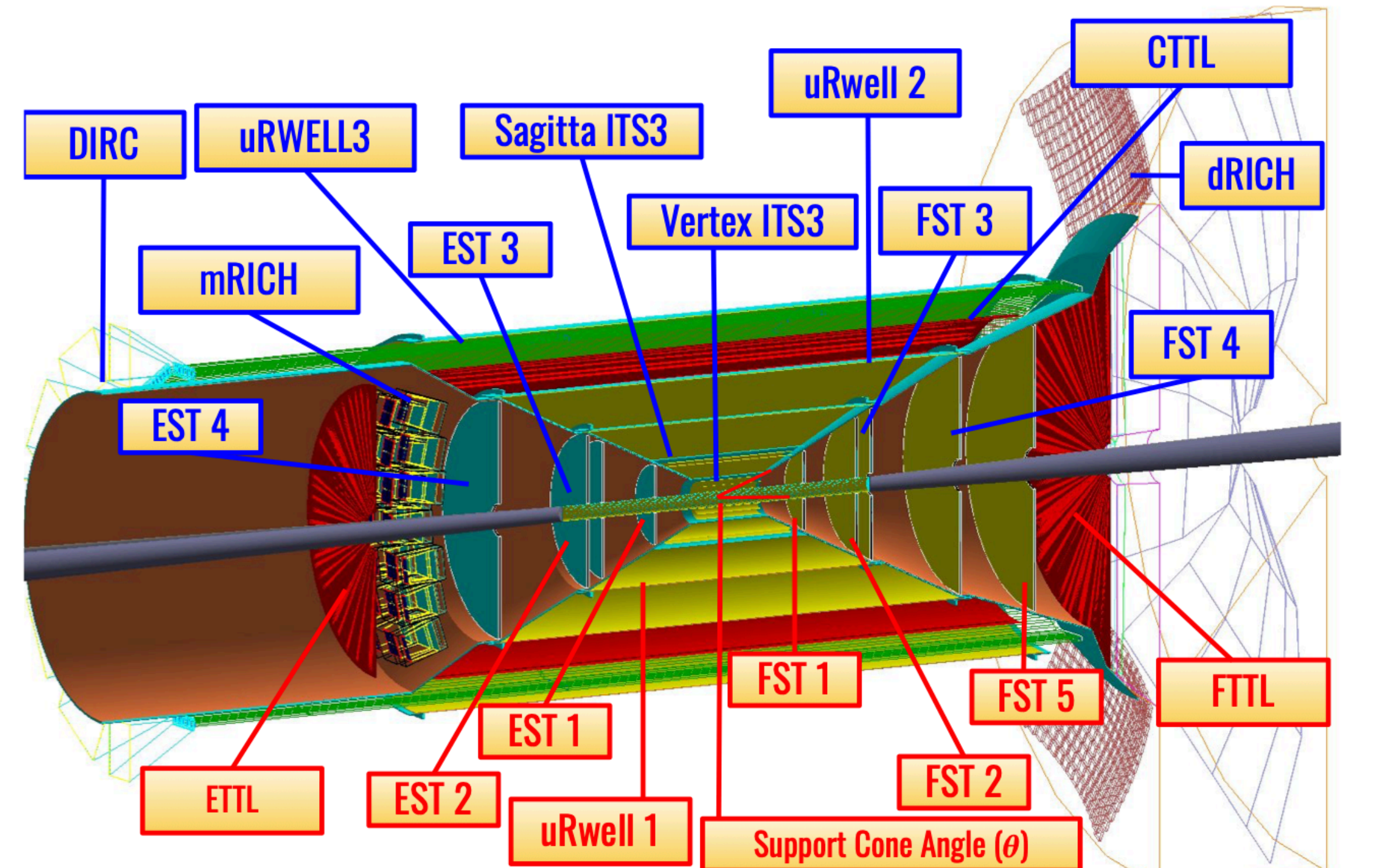
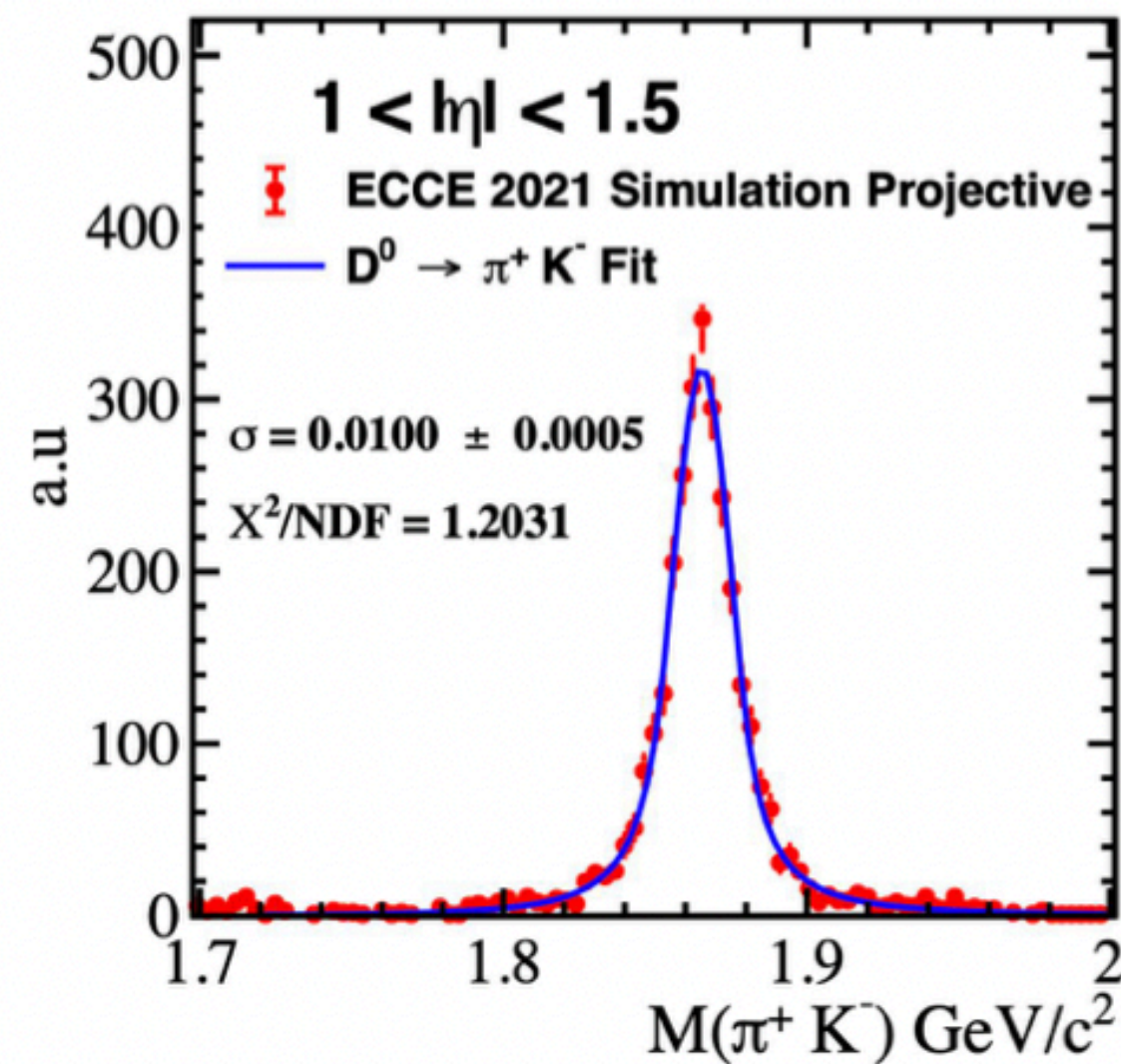
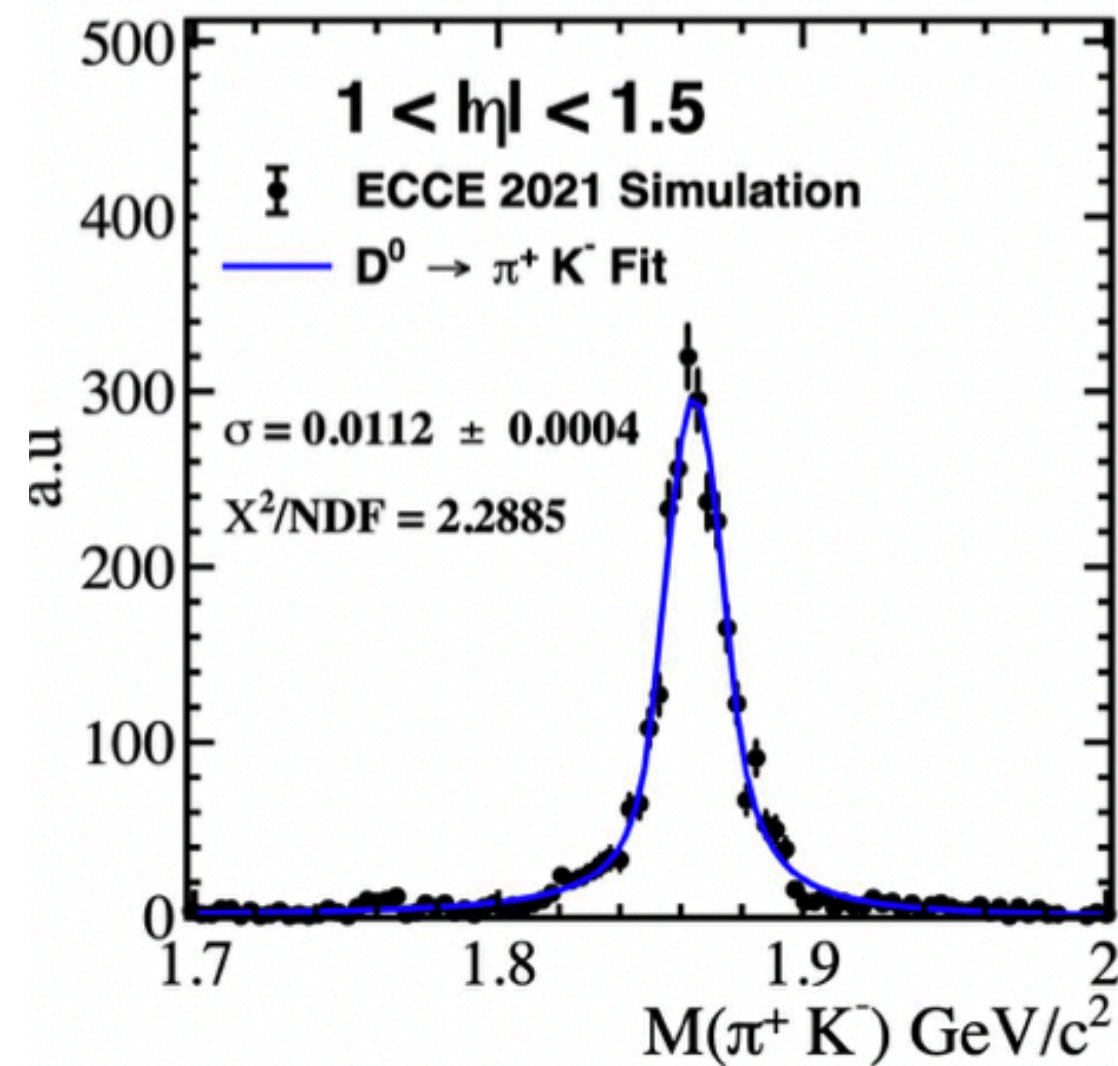


[AI4EIC]

One more thing to tune:

Genetic Algorithms yield e.g. projective design of tracking system

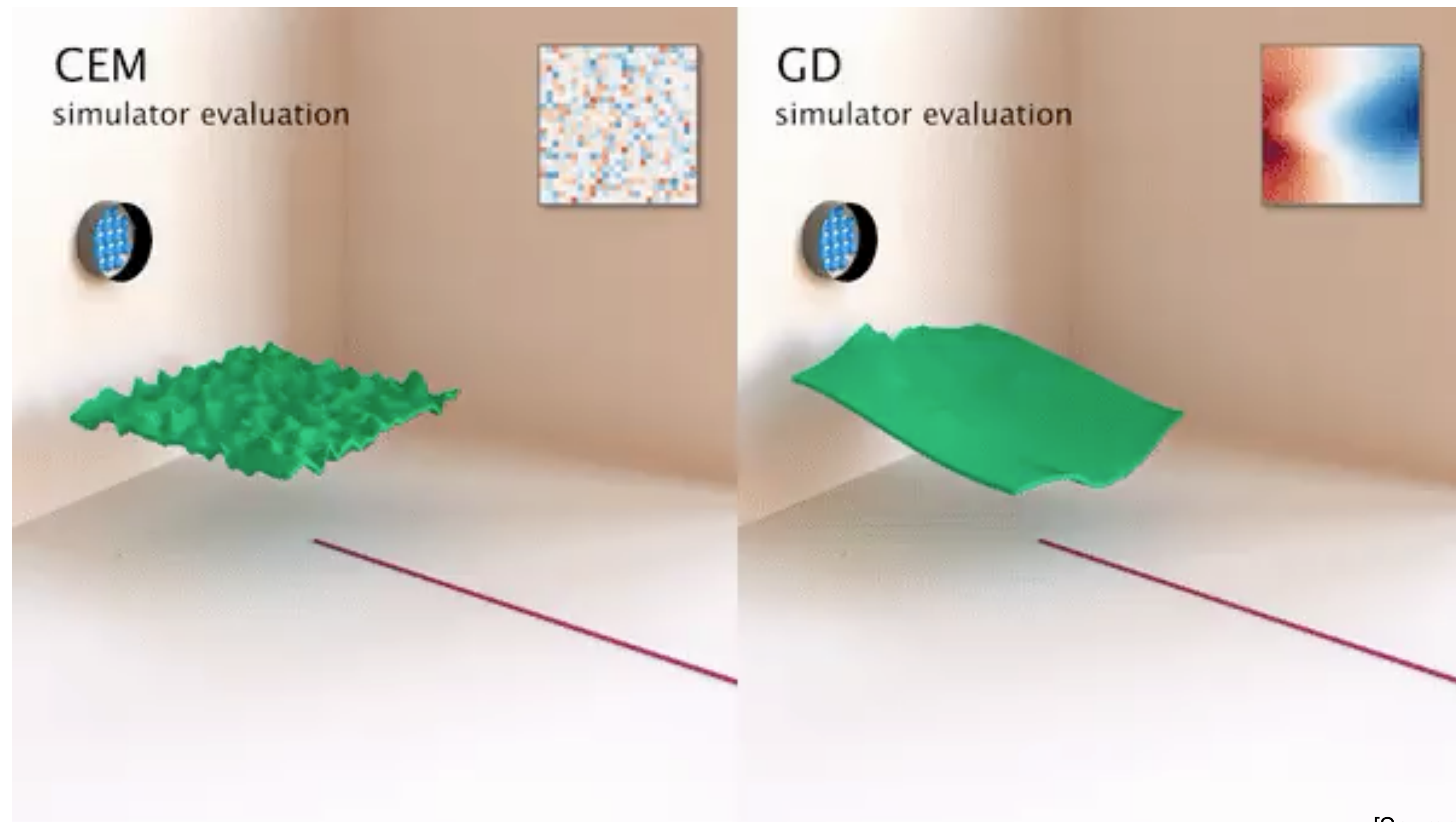
→ ongoing R&D: 10% improvement in resolution



arxiv:2205.09185

Can a gradient-based optimization work / improve?
(similar to NNPDF example?)

An Example from outside Physics



[Source]

unoptimized design

optimized design



Differentiable Design Optimization

Key difficulty: HEP simulation is highly stochastic and discrete (decays, showers,...)
→ need gradient over complex expectation over data and event histories

$$\nabla_{\phi} \mathbb{E}_x[f(x)]_{\phi} = \nabla_{\phi} \int dx \mathbb{1}_{f(x)} \int dz p(x|z, \phi) p(z|\theta, \phi)$$

gradient wrt to fit paramets expected performance probability of data under design ϕ

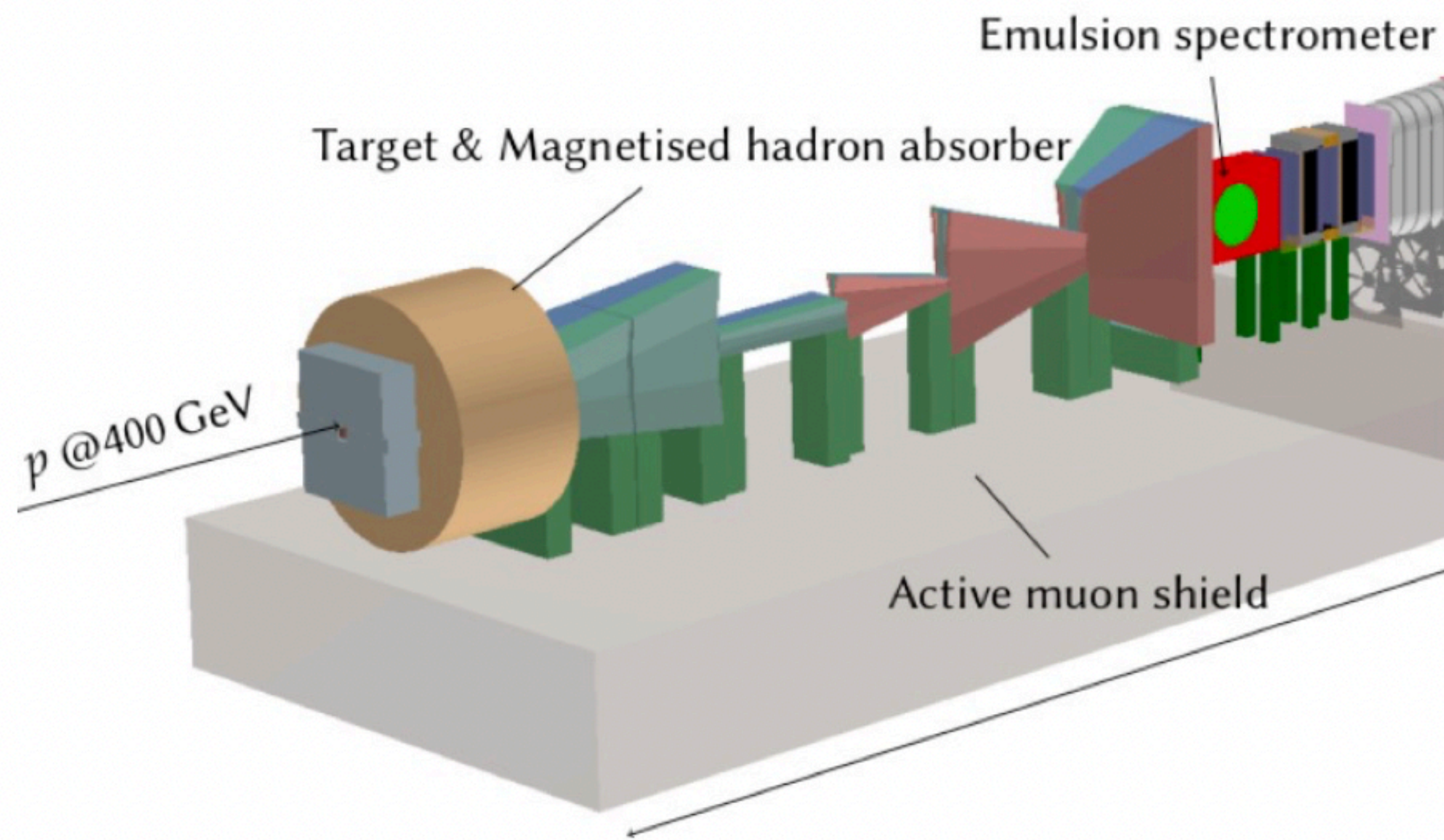
Ways to gradient-based training

- replace true simulator with smooth, differentiable “surrogate” (ML generative model)
- neural network based proposal, train on gradients of policy instead of simulation

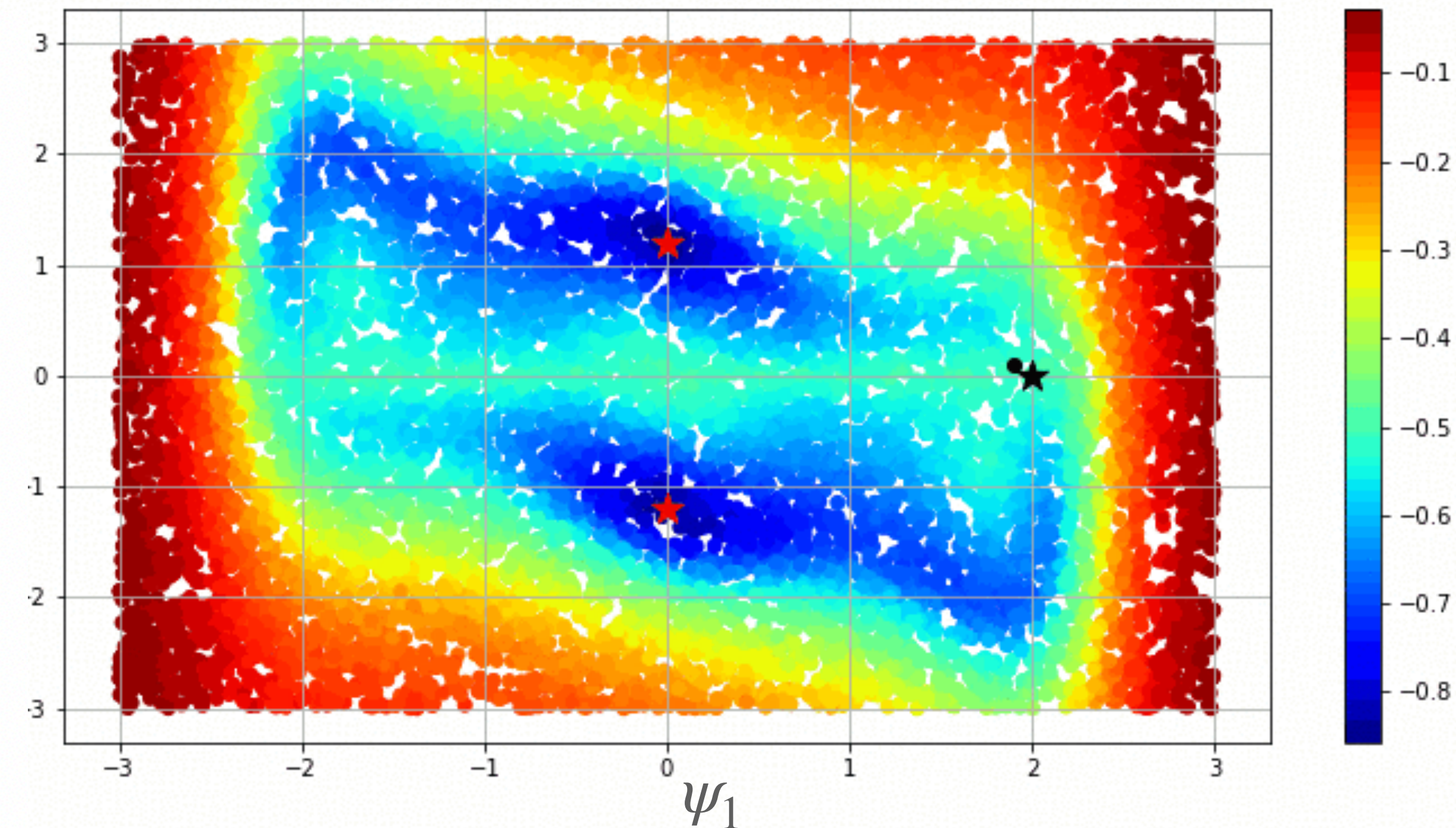
Differentiable Design Optimization

Example: Optimize Muon shielding in SHiP

- local differentiable proxy + gradient descent



O Lantwin

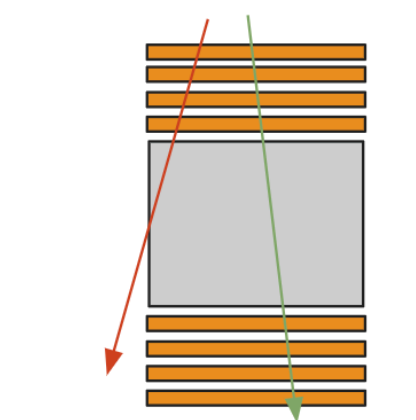


[see A.Ustyuzhanin's Talk in last year's QCHS]

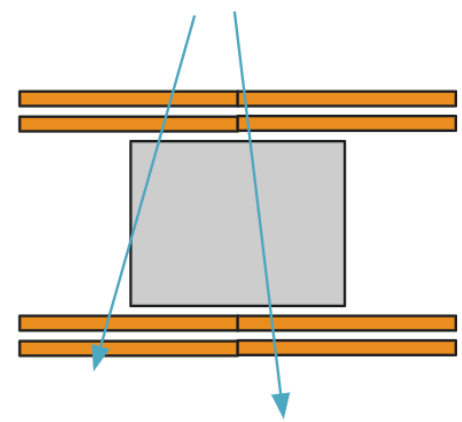
Differentiable Design Optimization

Example: End-to-end differentiable Muon Tomography Design Optimization

- instead of surrogate, implement a detector simulation in diffprog language
- fast convergence to good design

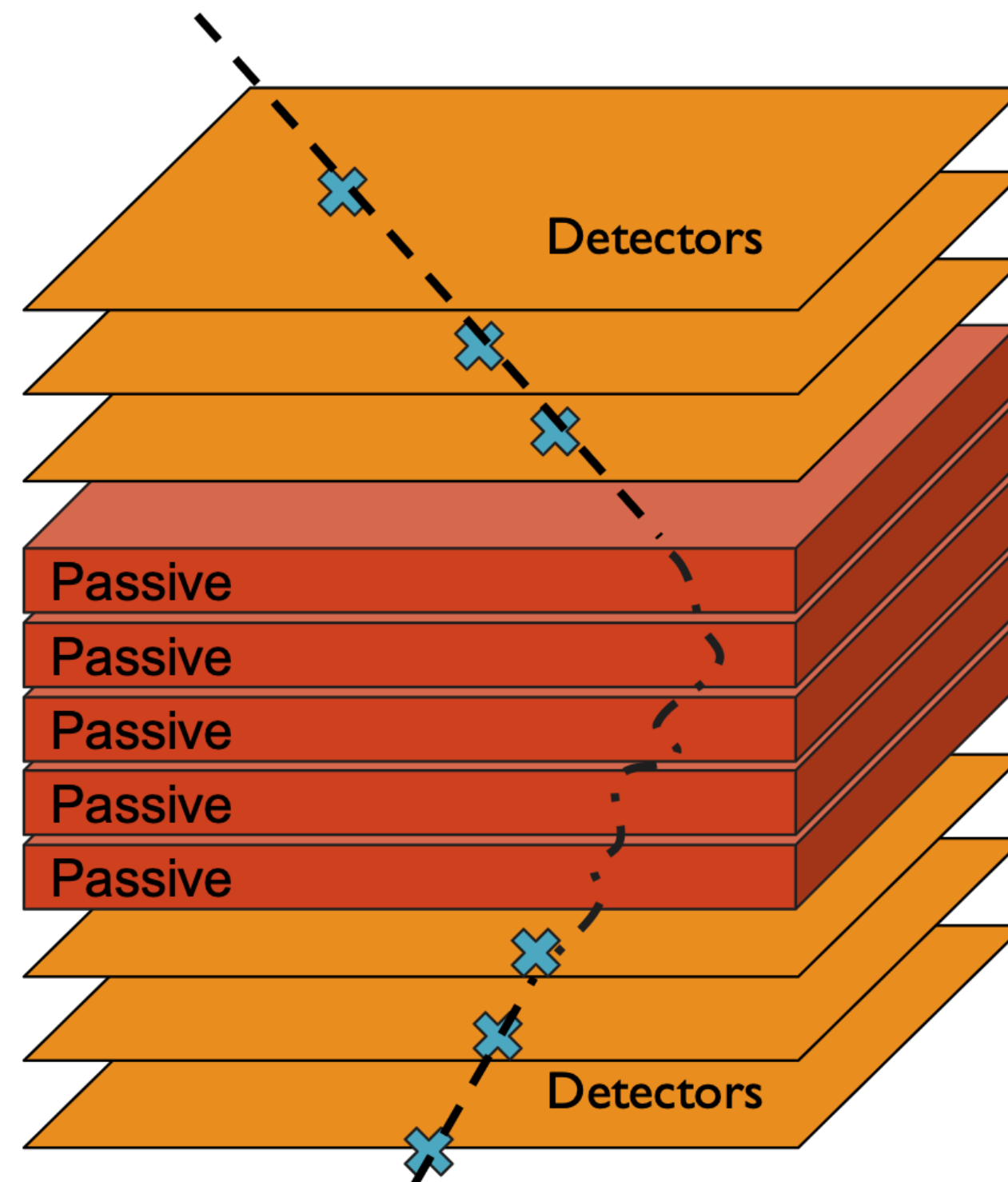


Example 1:
Muons
measured
precisely but
less efficiently

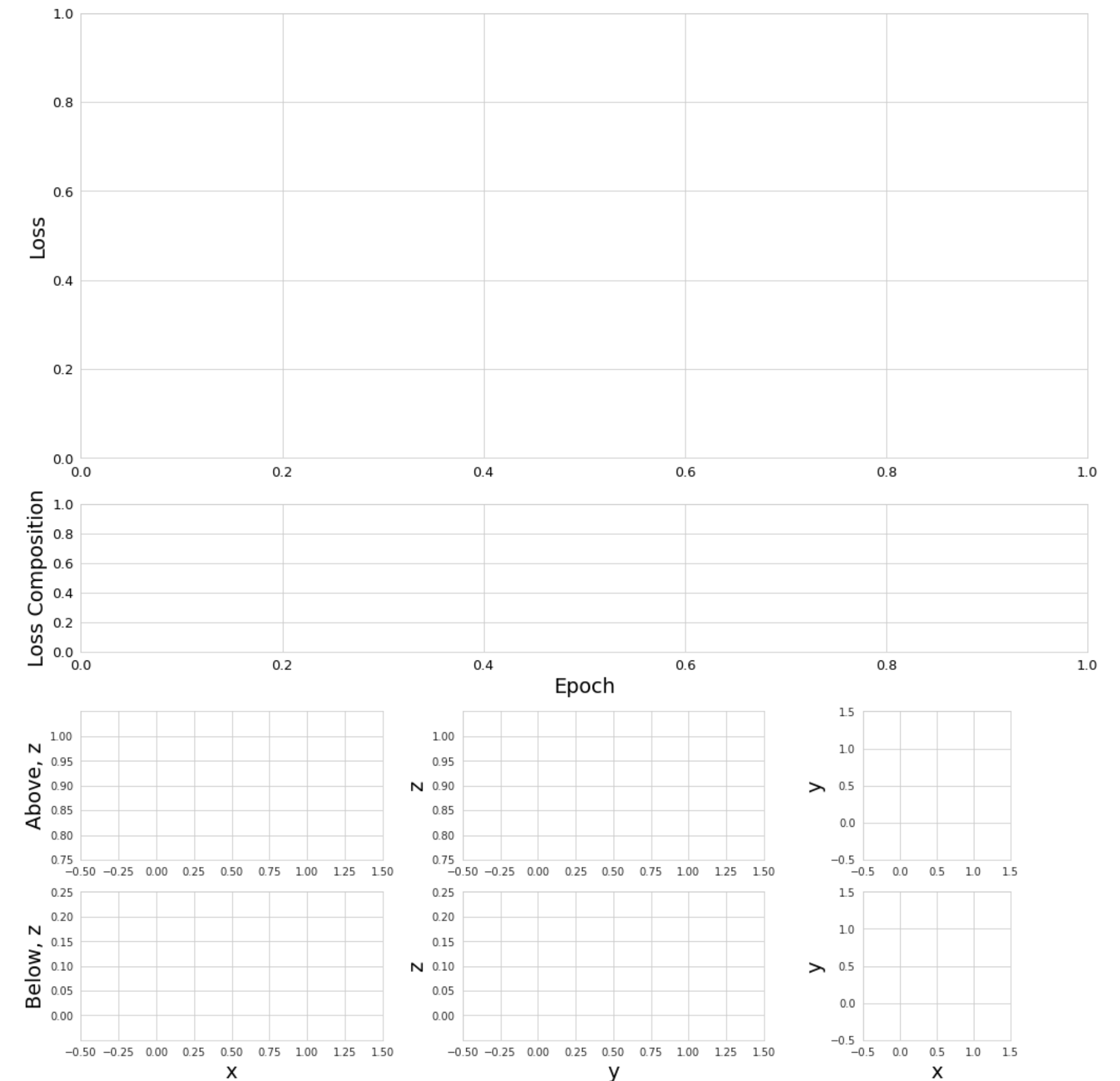


Example 2:
Muons
measured
less precisely
but more
efficiently

[G.Strong]



[see G. Strong's presentation Thursday Track H]



Differentiable Design Optimization

Differentiable Simulators & Design Optimization: very early days

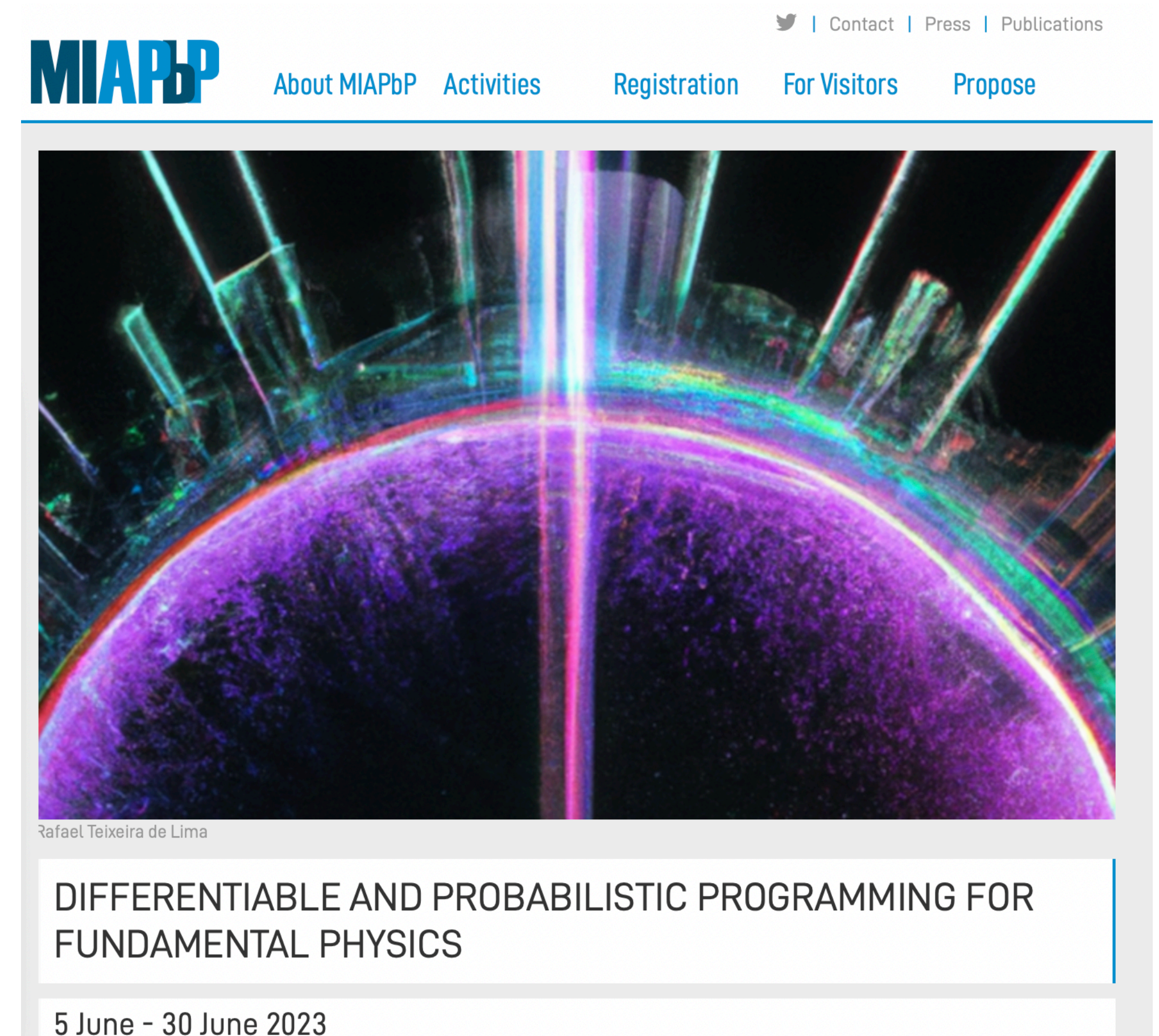
→ a lot of foundational work to be done - join!



The banner for the Second MODE Workshop on Differentiable Programming for Experiment Design. It features the MODE logo with a red star and green/orange swoosh. Logos for JENAA, iris hep, NSF, NuPECC, and APPEC are displayed. Text includes: "Second MODE Workshop on Differentiable Programming for Experiment Design", "12-16 Sept 2022", "OAC conference center, Kolymbari, Crete, Greece.", "Europe/Zurich timezone", and a search bar.

| | |
|----------------------|--|
| Overview | <i>In case of issues please contact Dr. Pietro Vischia at the email address below.</i> |
| Scientific Programme | This workshop is part of the activities of the MODE Collaboration and of the SIVERT project . |
| Call for Abstracts | MODE stands for " <i>Machine-learning Optimized Design of Experiments</i> ". |
| Timetable | |
| Contribution List | |
| Book of Abstracts | |
| Registration | Location: The workshop will take place at the OAC (https://www.oac.gr/en/) in Kolymbari, Crete (Greece). Information on the accommodation available in a dedicated page . |
| Participant List | At the same page you will find the procedure for young participants to ask for financial support: we have limited availability to cover part of the travel expenses and waiving of the conference fee for some selected young participants. Priority will be given to participants |
| Code of Conduct | |
| Travel information | |

<https://indico.cern.ch/event/1145124/>



The MIAPbP website header includes the MIAPbP logo and navigation links: "About MIAPbP", "Activities", "Registration", "For Visitors", "Propose", and social media links "Contact", "Press", "Publications". Below the header is a large image of a particle detector with a purple and blue glow. The text "Rafael Teixeira de Lima" is visible below the image. The main title is "DIFFERENTIABLE AND PROBABILISTIC PROGRAMMING FOR FUNDAMENTAL PHYSICS" and the dates are "5 June - 30 June 2023".

<https://www.munich-iapbp.de/probabilistic-programming>

Summary

HNEP Analysis is dominated by simulation & optimization problems

- fast simulation, search for best observables
- ripe for significant improvement by ML methods

Differentiable Programming:

- one of the underlying secrets of Deep Learning, lots of interest in recent years
- allows a more nuanced look at ML: **encode physics** into model & evaluation

Generalizing from ML: we can abilities of diff. prog. to solve non-ML tasks

- nascent field of ML and/or gradient-based experimental design optimization e.g. for EIC