

A parametric study on the initial transverse stability of suspension ships

CoTech#90

Jialin Han¹

Motohiko Murai²

1. Faculty of Engineering, Yokohama National University

2. Faculty of Environment and Information Sciences, Yokohama National University

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Introduction



A: Nauti-Craft

References[1]



C: Proteus

References[3]



E: Wave Harmonizer 7

References[5]



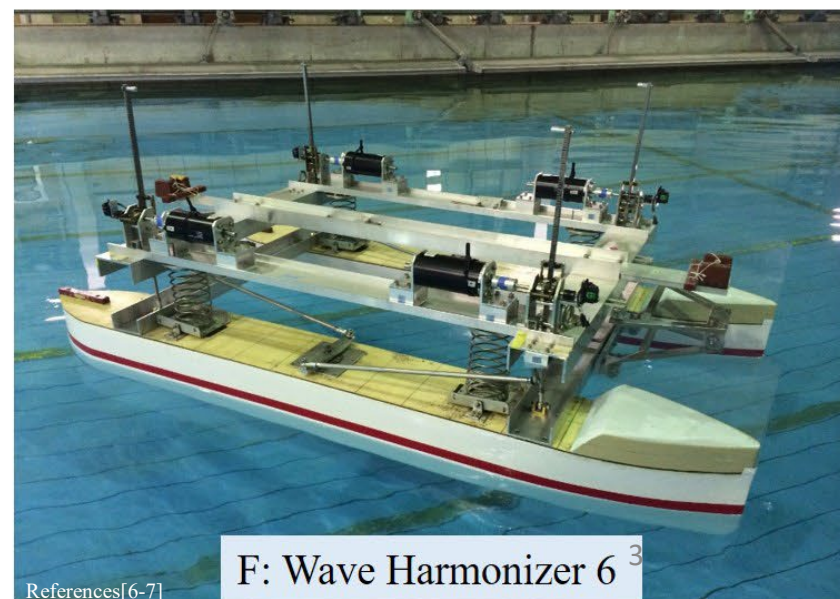
B: Martini 1.5

References[2]



D: WAM-V 16

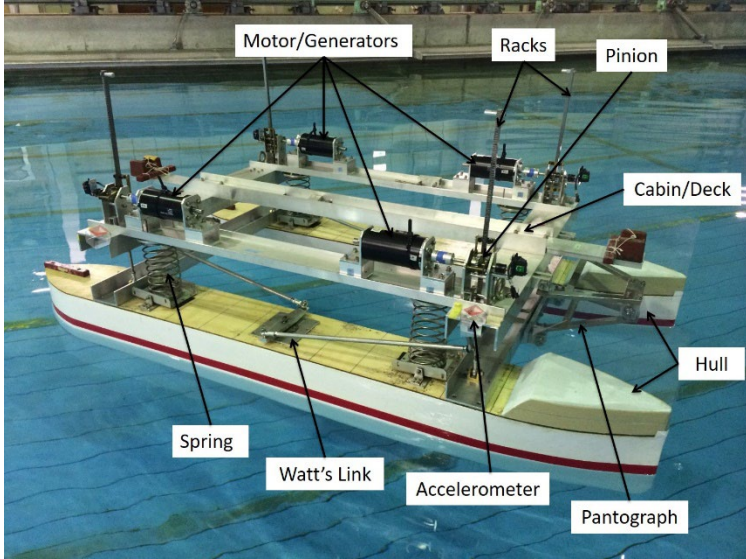
References[4]



F: Wave Harmonizer 6³

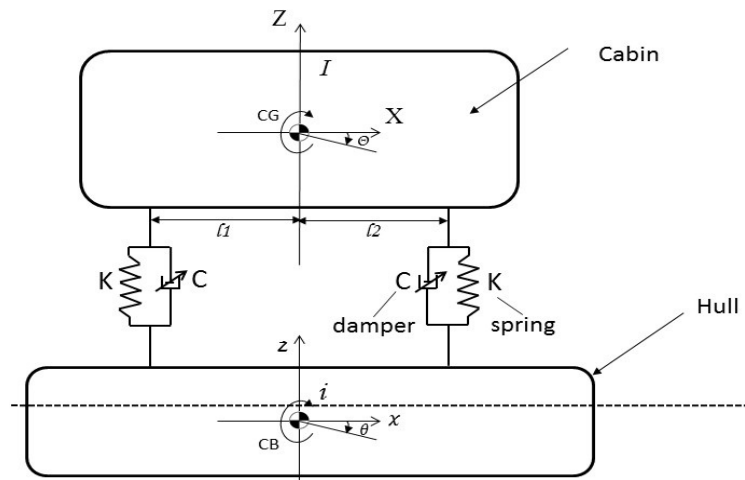
References[6-7]

• What is a suspension ship?

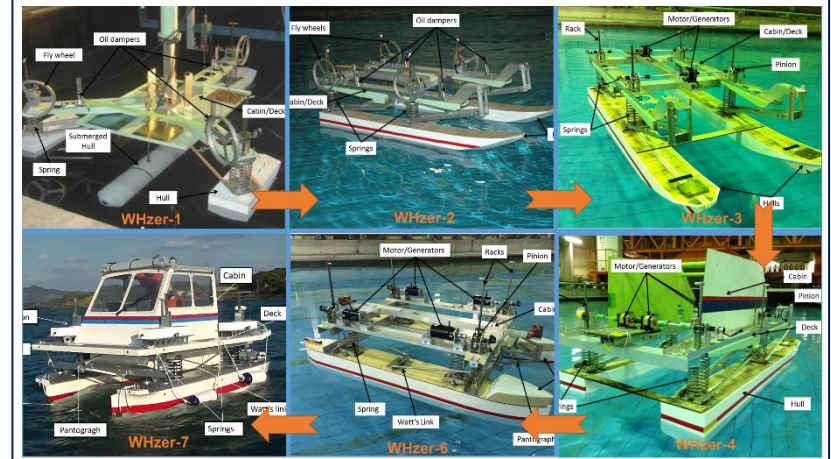


- ✓ 9 degree-of-freedom;
- ✓ Heave, pitch, and roll motions of the cabin are separable from those motions of the hull; while relative yaw, sway, and surge between the two are constrained;
- ✓ The motion of the cabin and the hull can be modified by using appropriate control systems.

• Why use suspensions on a ship?



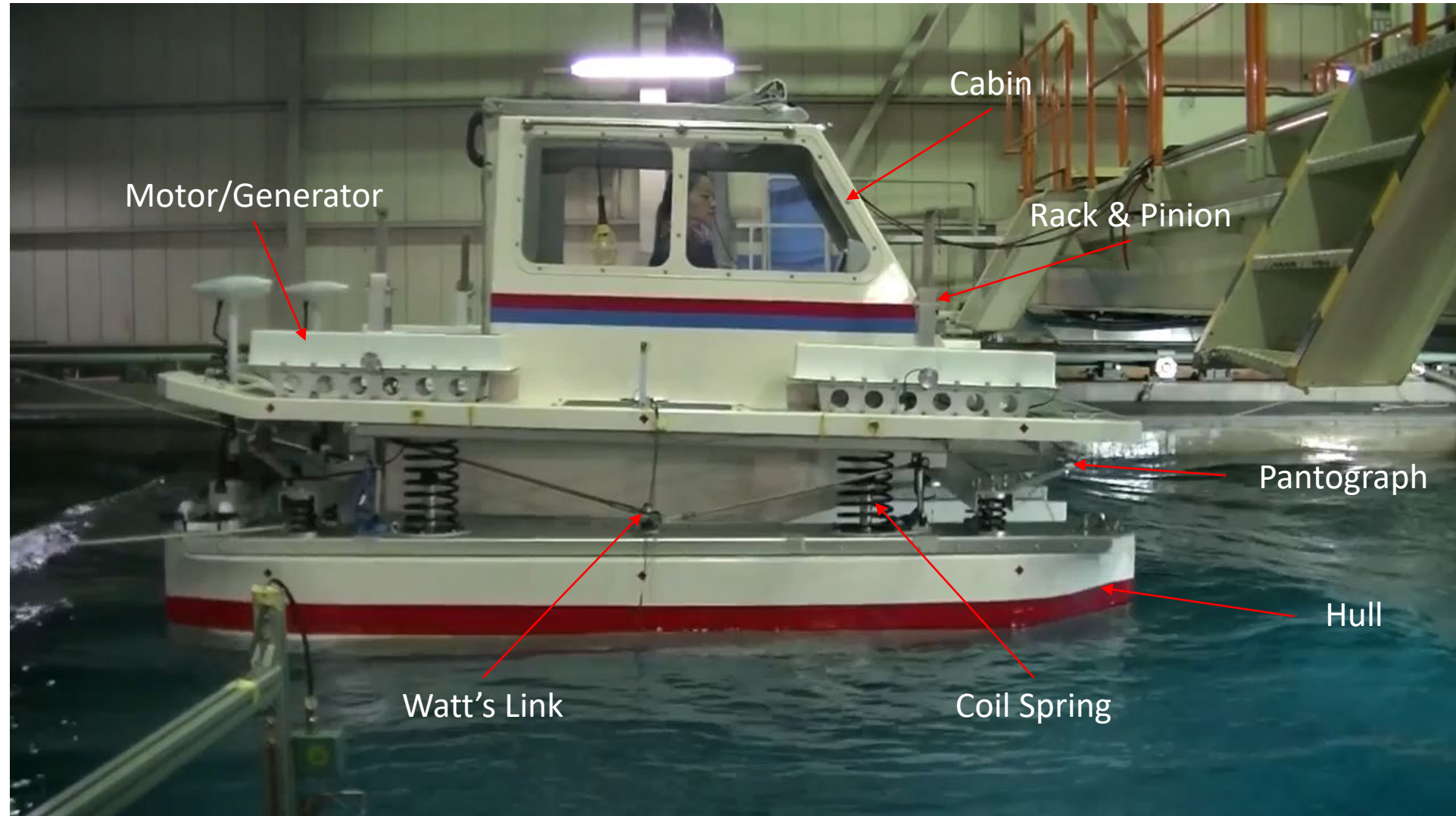
• What are the objectives of this study?



- ✓ Several types of suspension ships have been developed and tested in a towing tank.
- ✓ Control strategies have been proposed and verified in those experiments.
- ❑ Investigate **characteristics** of the initial transverse stability of suspension ships;
- ❑ Provide a deeper **insight** into the structure design of suspension ships.

Design Principle of Suspension Ships

Safe
&
Comfortable



Feature of suspension ships

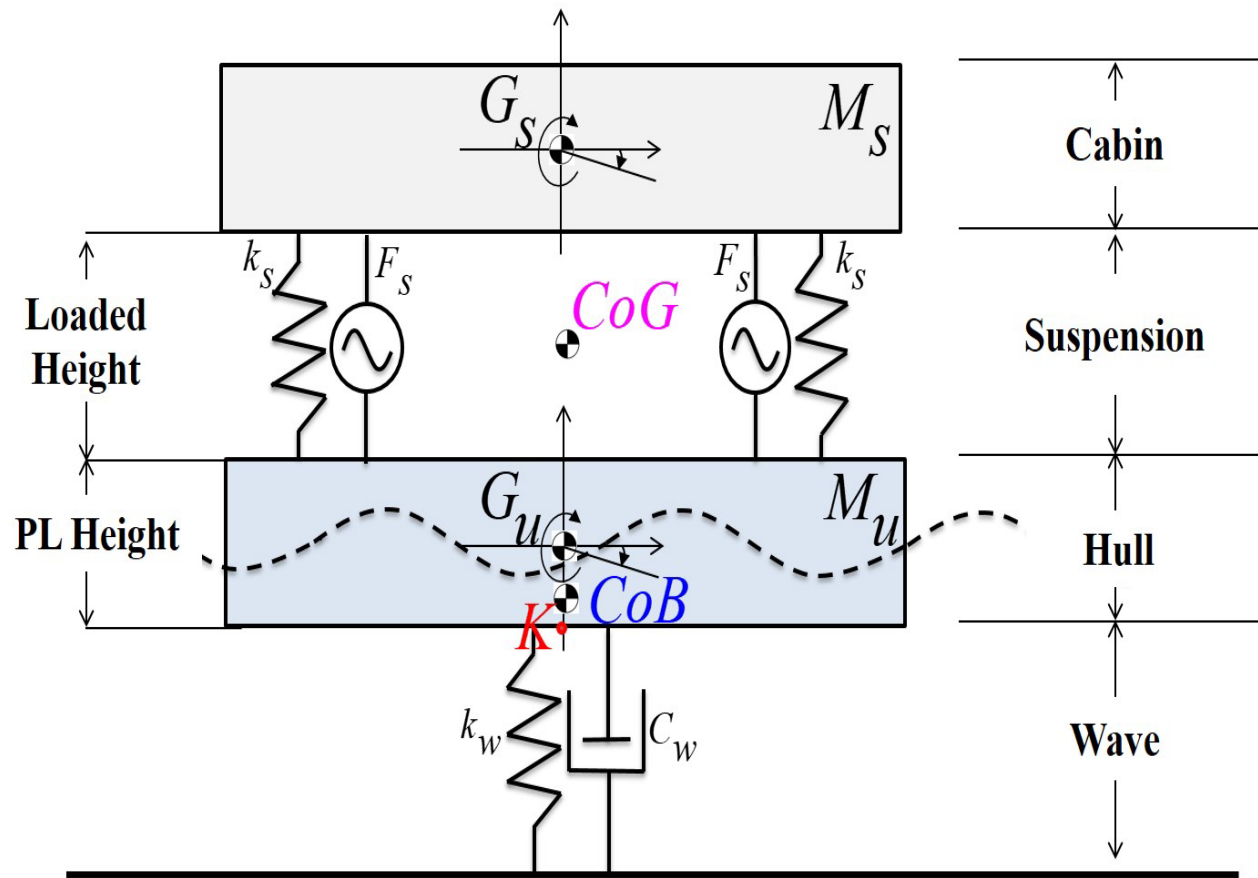


Fig.1 Structure diagram of suspension ships.

- **Dynamic Mass ratio:**

$$q = \frac{M_s}{M_u}$$

M_s : Sprung mass; M_u : Unsprung mass

- **Static Mass ratio:**

$$p' = \frac{M_{cabin}}{M_{hull}}$$

M_{cabin} : mass of cabin; M_{chull} : mass of hull;

- **Loaded Height:**

$$H_L(k_s, L_f, M_s)$$

k_s : spring stiffness; L_f : free length of spring

- **Placement Location Height:**

$$H_{PL}$$

- **Beam of Ship:**

$$B_{hull}, BoA$$

Initial Transverse Stability (GM)

Table 1. Design specifications of a suspension model

| Item | Value |
|------------------------------------|------------------------|
| mass of cabin M_1 | 2.5 kg |
| mass of suspension M_3 | 2.6 kg |
| mass of hull M_2 | 1.3 kg |
| spring stiffness k_s | 235 N/m |
| free length of spring L_f | 0.22 m |
| Diameter of spring | 0.05 m |
| Dimension of cabin L_1, H_1, B_1 | L0.5 m H0.20 m B0.15 m |
| Dimension of hull L_2, H_2, B_2 | L0.5 m H0.15 m B0.15 m |

Metacentric height GM:

$$GM = KB + BM - KG$$

where, $KB = \frac{d}{2}$, $BM = \frac{I_L}{\nabla}$, $KG = \frac{M_1KG_1 + M_2KG_2 + M_3KG_3}{M_1 + M_2 + M_3}$

$GM = -0.2387 < 0$ **unstable!**

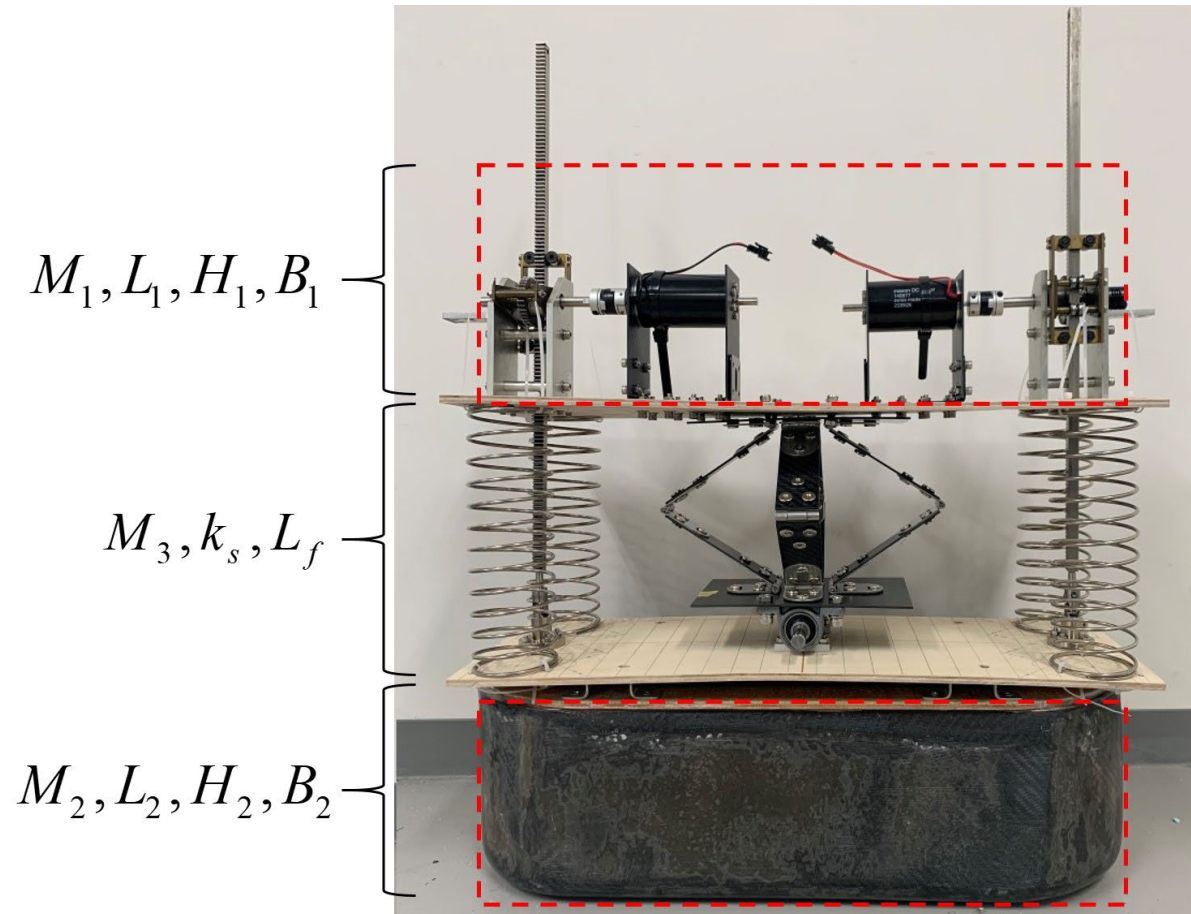
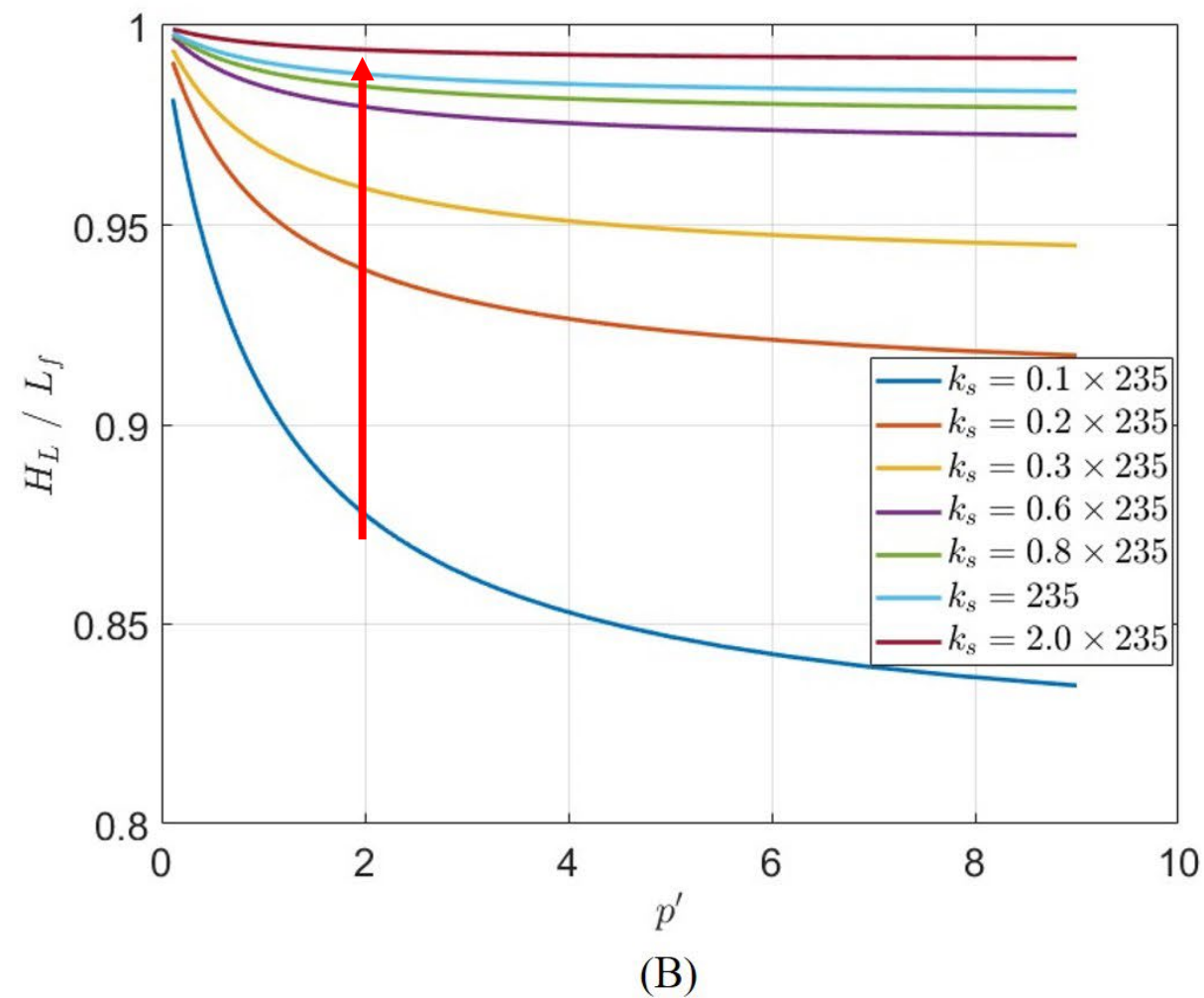
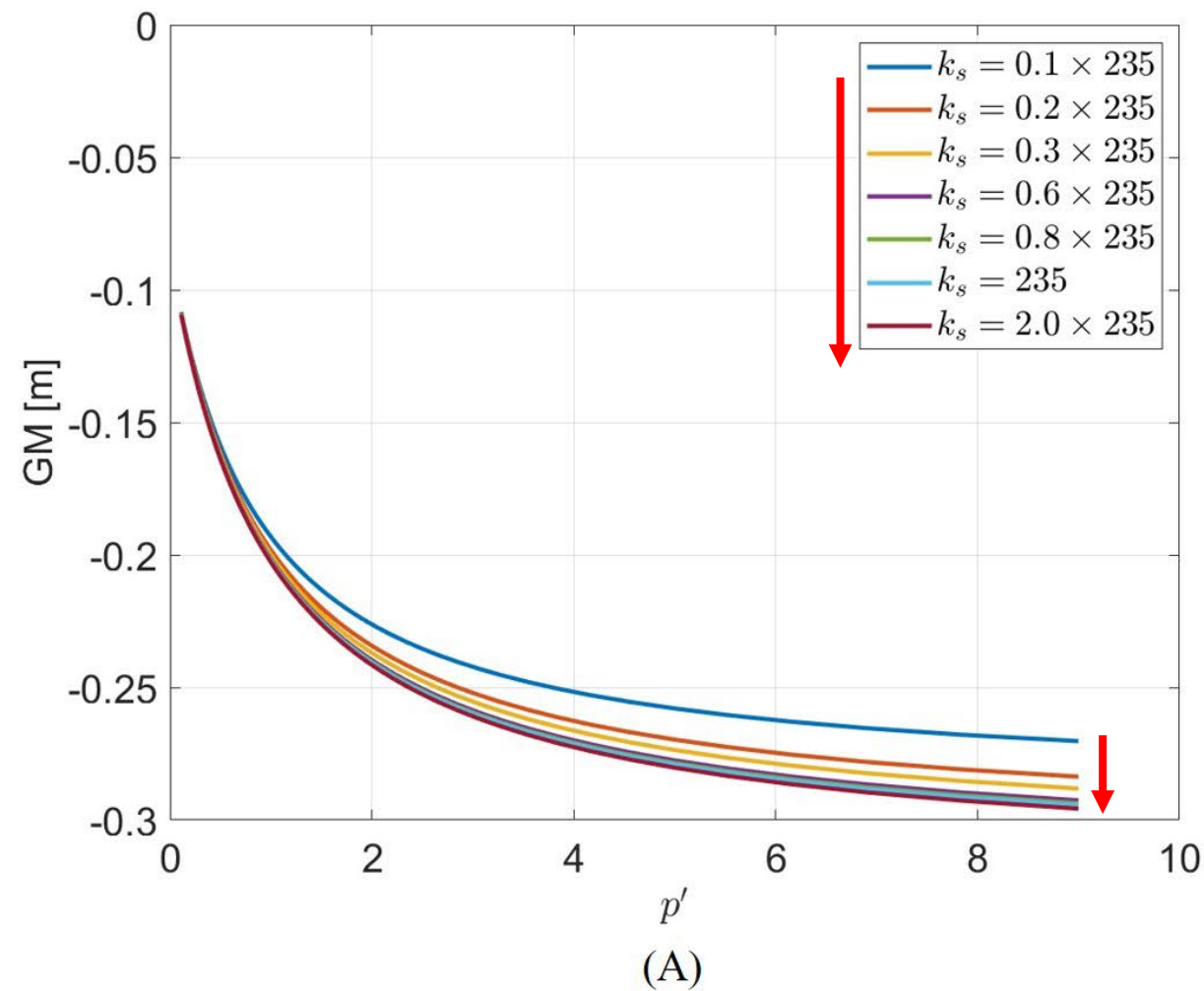
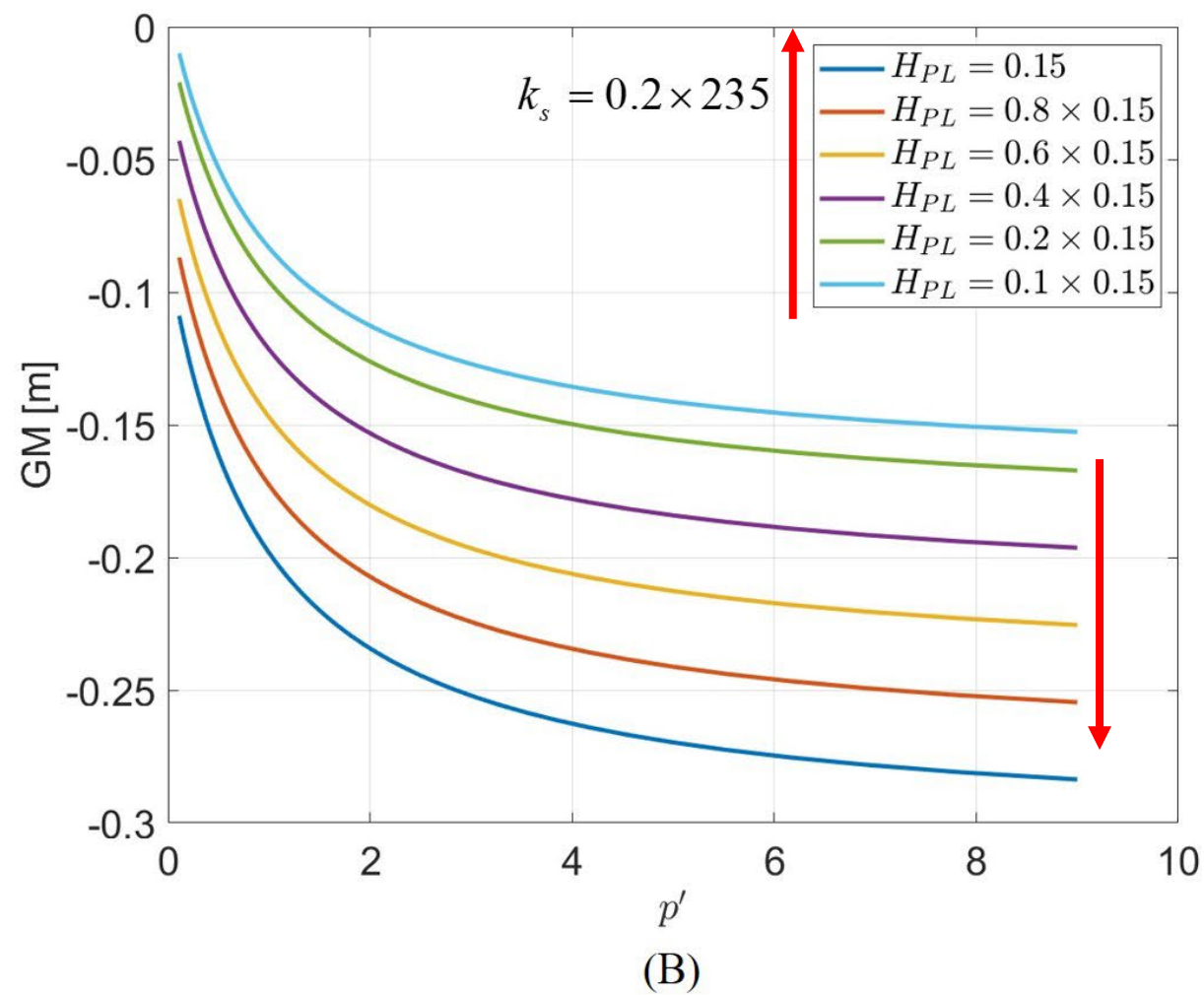
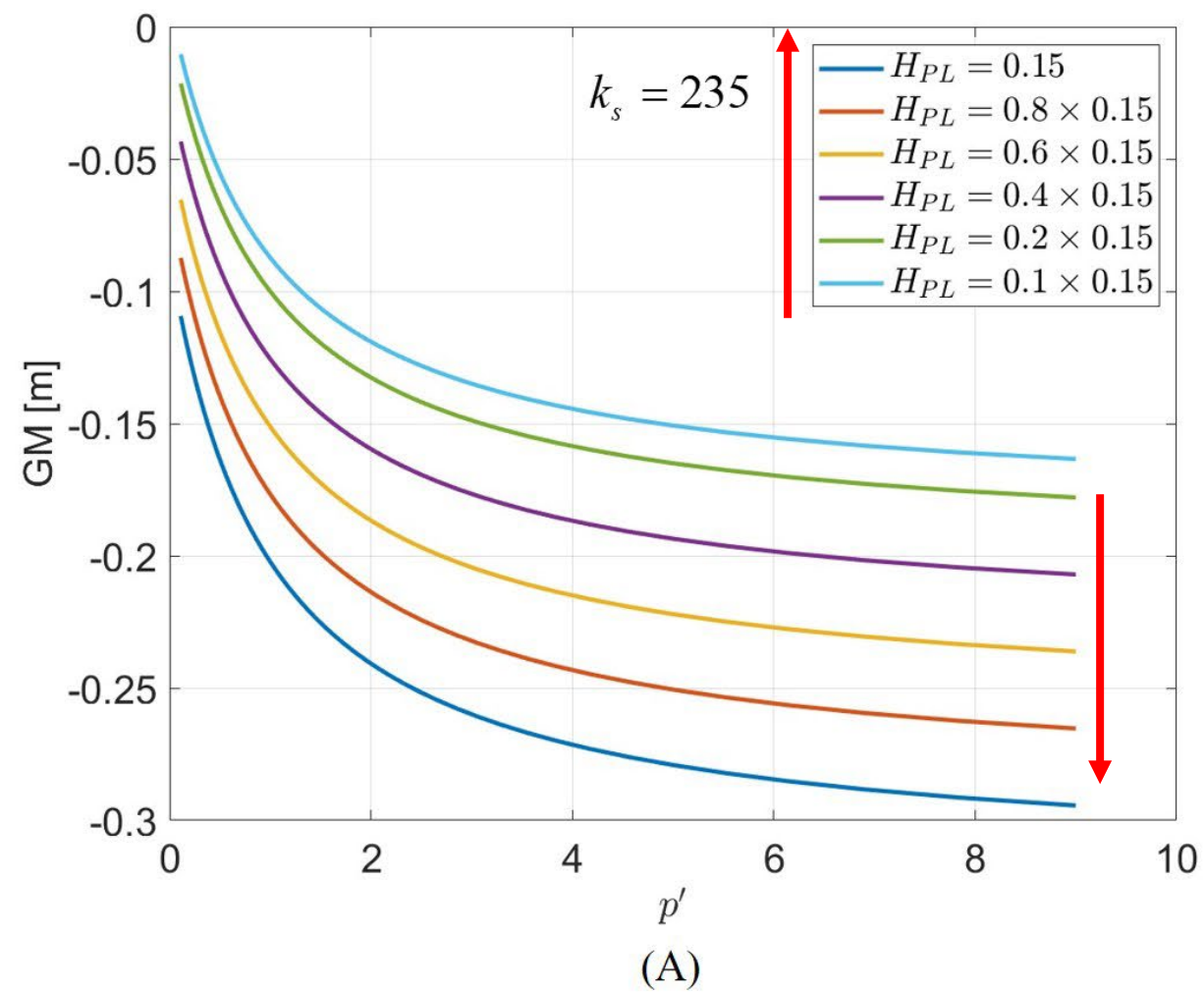


Fig.2 A prototype of suspension ship.

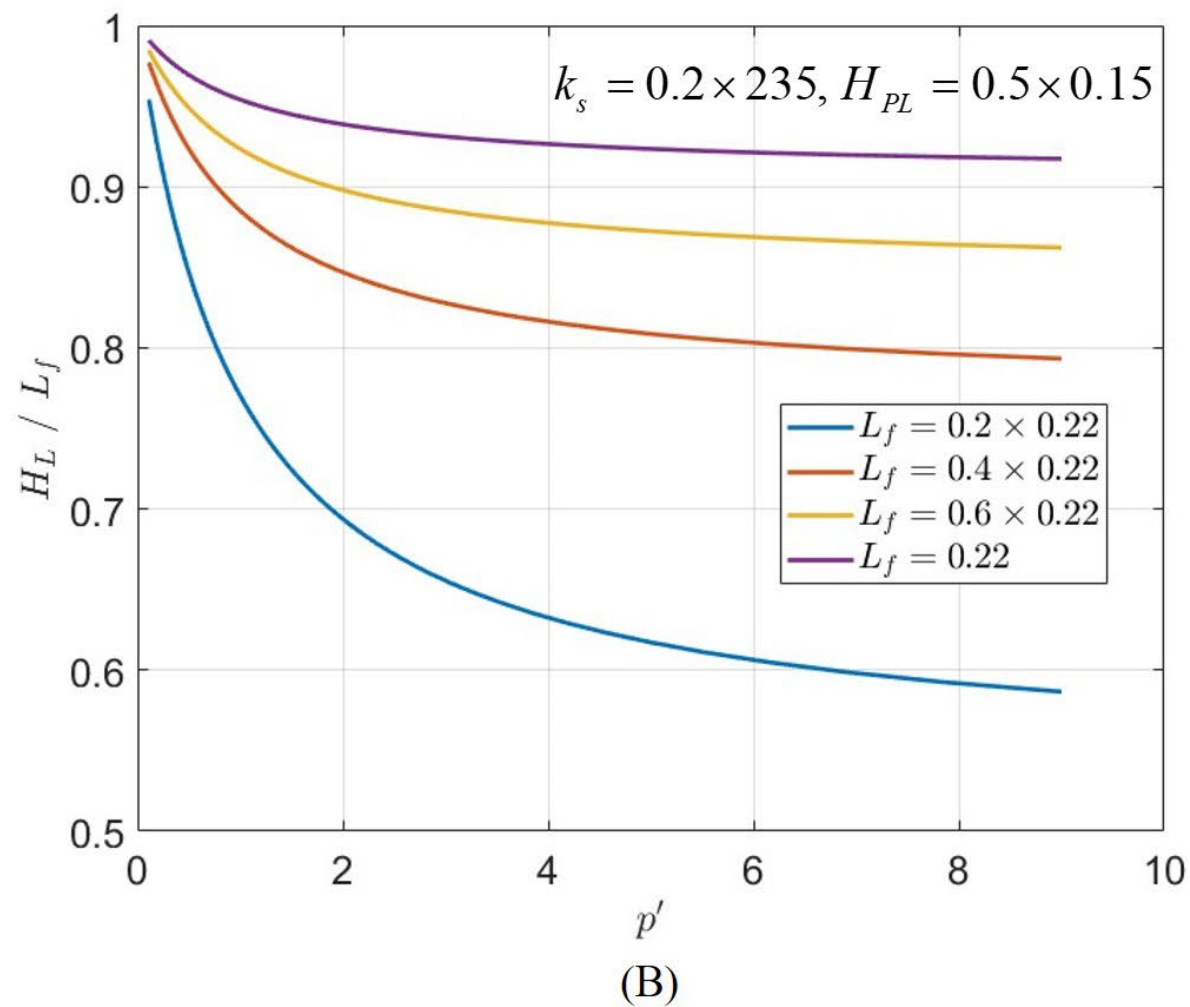
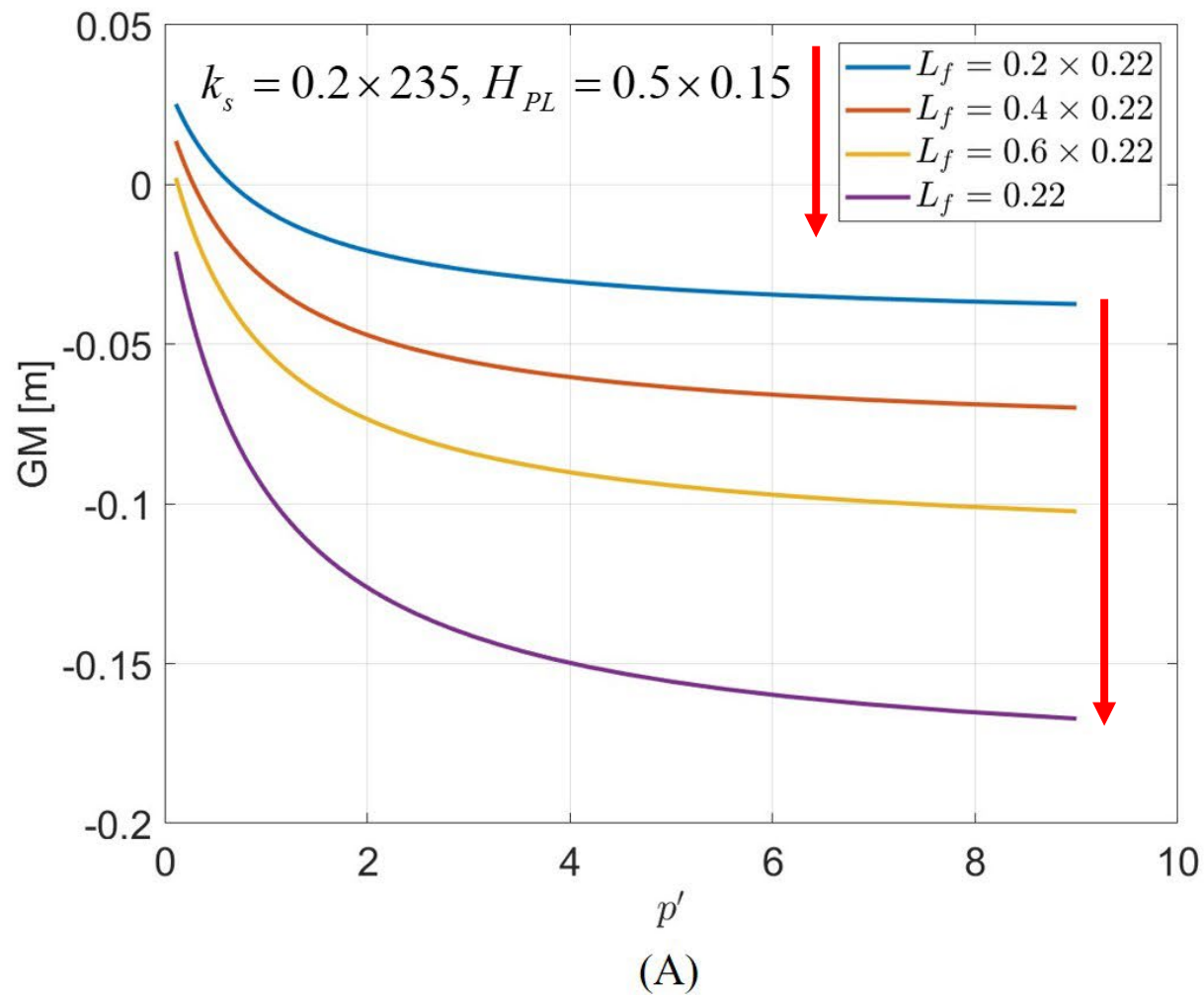
Parametric Study (k_s , $M_{\text{cabin}}/M_{\text{hull}}$)



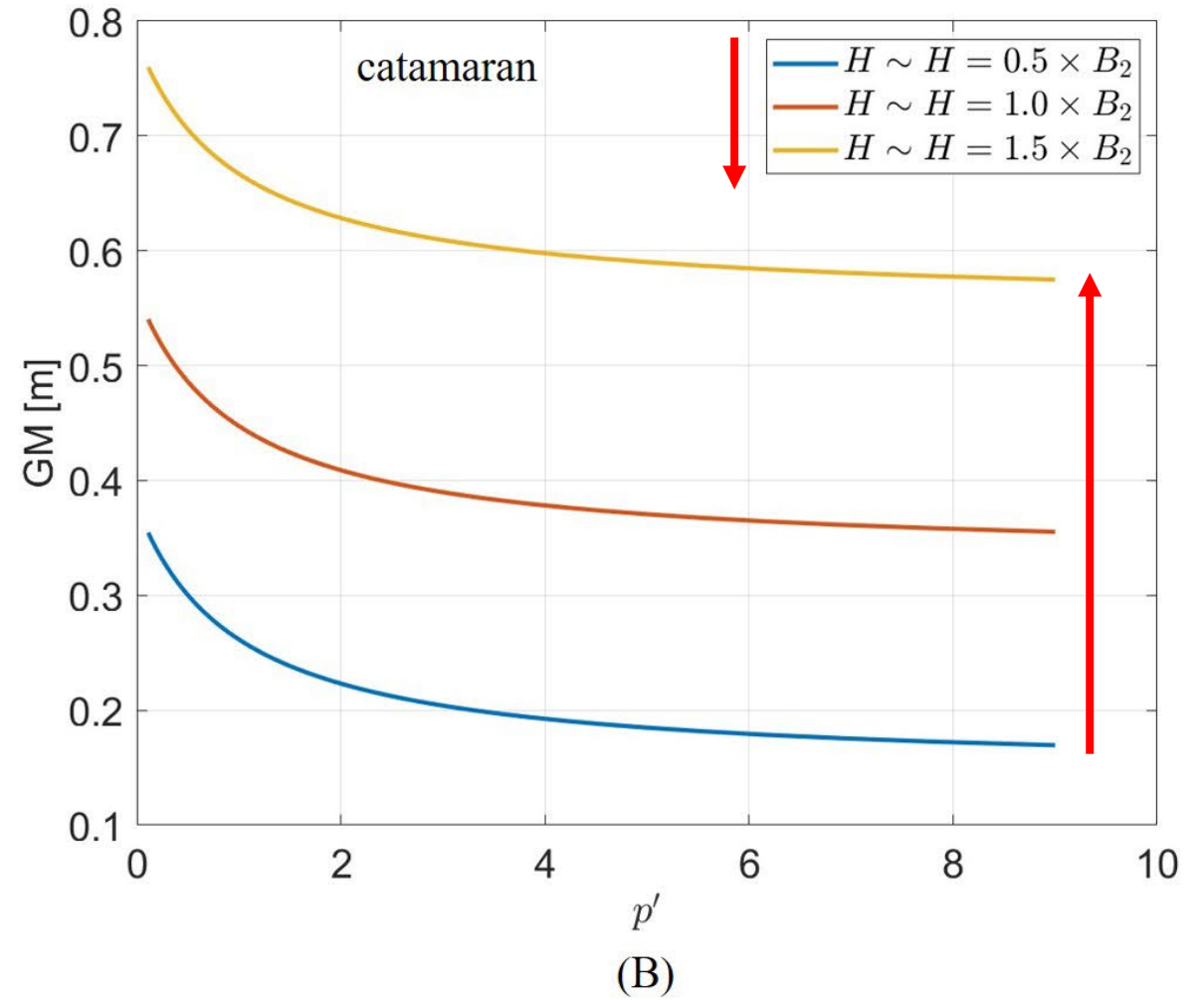
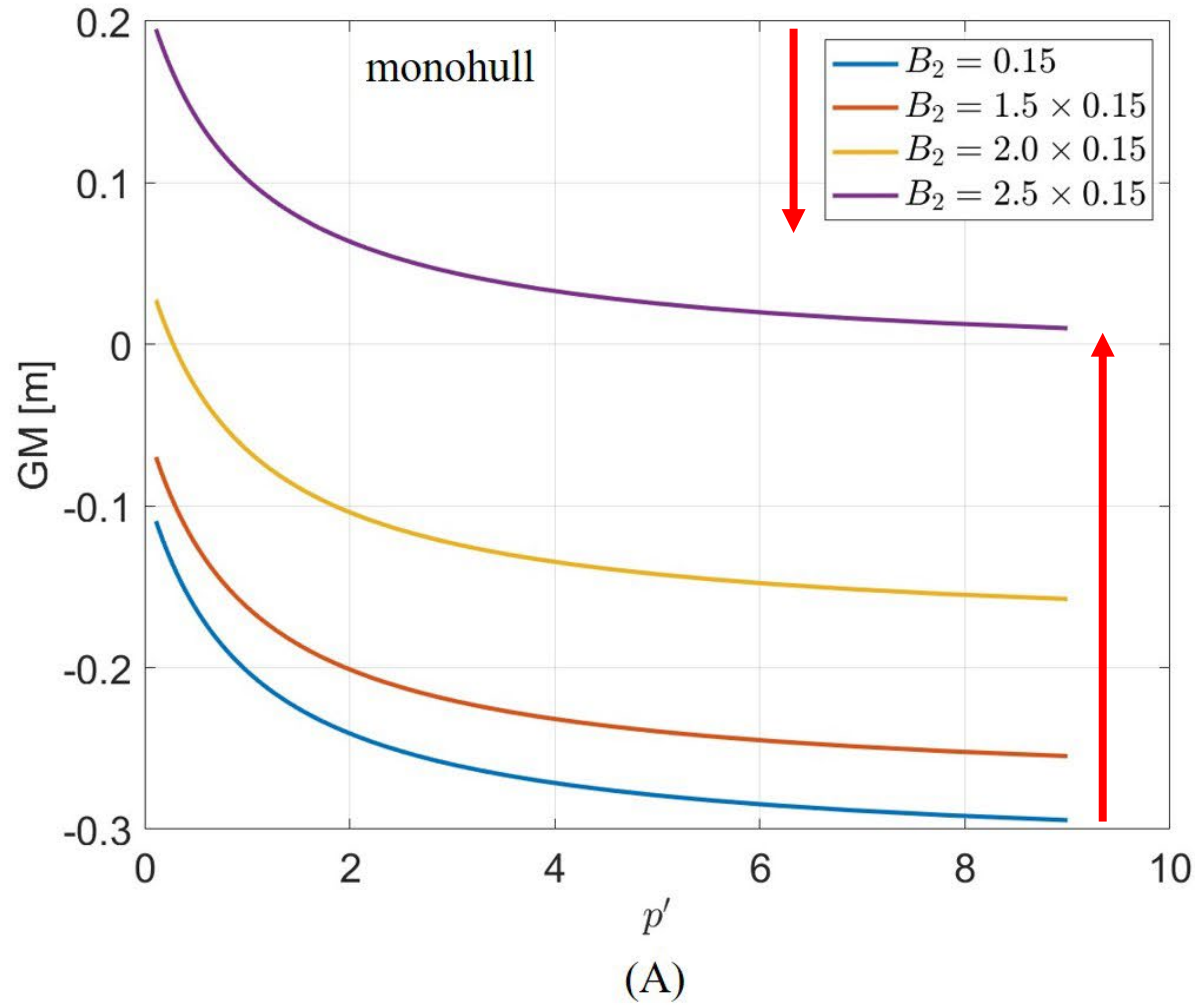
Parametric Study (H_{PL} , k_s , M_{cabin}/M_{hull})



Parametric Study (L_f , $M_{\text{cabin}}/M_{\text{hull}}$)



Parametric Study (Beam of ship)



Conclusions:

1. A reduced mass ratio results in an increased GM. The initial transverse stability displays significant variation when the mass ratio of the cabin and hull is **less than 2**. It is imperative to pay close attention if the static mass ratio falls within this range;
2. A **shorter** loaded height is preferable for a larger GM. However, the allowable travel distance must be taken into account to prevent bottom out. If springs are utilized, the spring stiffness and free length must be carefully balanced.
3. A **lower** placement location height results in a larger GM. Although, the impact becomes weaker with the reduced static mass ratio, it exerts more impact compared to the spring stiffness.
4. A **larger** beam produces a larger GM. The beam of the hull for a monohull and the overall beam of a catamaran are the dominating parameters that influence the initial transverse stability.

Thank you for your attention!

References:

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- [5] Han J, Kanno S, Mochizuki A, Kitazawa D, Maeda T and Itakura H, 2019. Study on Attitude Control of a Cabin-Suspended Catamaran by Using a Double-Loop Control System. Proceedings of the ASME 2019 38th International Conference on Ocean, Offshore and Arctic Engineering (Glasgow: June 9–14, 2019), vol(9), 95827.
- [6] Han J, Maeda T, Itakura H and Kitazawa D, 2022. Experimental study on the wave energy harvesting performance of a small suspension catamaran exploiting the maximum power point tracking approach, *Ocean Engineering*, vol(243), 110176.
- [7] Han J, Maeda T, Itakura H and Kitazawa D, 2023. Experimental study on the motion reduction performance of a small suspension catamaran exploiting an active skyhook control strategy, *Ocean Engineering*, vol(281), 114642.